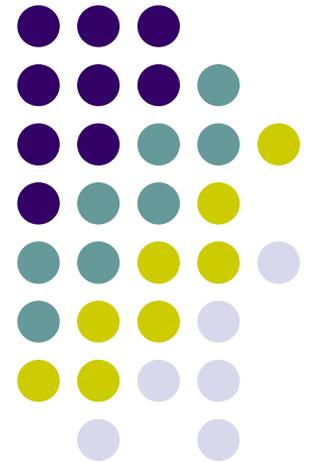
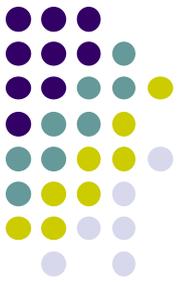


# Practical Parallel Computing (実践的並列コンピューティング)

Part2: GPU (3)  
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# Overview of This Course

- Part 0: Introduction
  - 2 classes
- Part 1: OpenMP for shared memory programming
  - 4 classes
- Part 2: **GPU** programming
  - 4 classes                      ← We are here (3/4)
  - OpenACC (1.5 classes) and **CUDA (2.5 classes)**
- Part 3: **MPI** for distributed memory programming
  - 3 classes

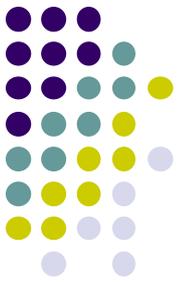
# Comparing OpenMP/OpenACC/CUDA



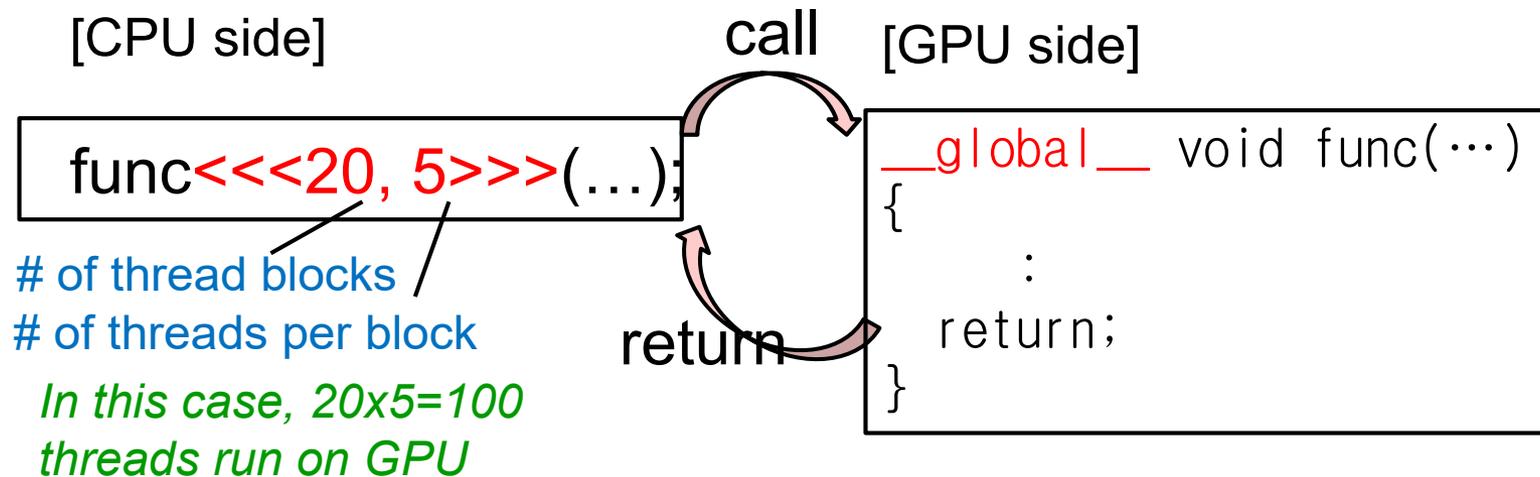
	OpenMP	OpenACC	CUDA
Processors	CPU	CPU+GPU	
File extension	.c, .cc		.cu
To start parallel (GPU) region	#pragma omp parallel	#pragma acc kernels	func<<<..., ...>>>()
To specify # of threads	export OMP_NUM_THREADS=...	(num_gangs, vector_length etc)	
Desirable # of threads	# of CPU cores or less	# of GPU cores or “more”	
To get thread ID	omp_thread_num()	-	blockIdx, threadIdx
Parallel for loop	#pragma omp for	#pragma acc loop	-
Task parallel	#pragma omp task	-	-
To allocate device memory	-	#pragma acc data	cudaMalloc()
To copy to/from device memory	-	#pragma acc data #pragma acc update	cudaMemcpy()
Function on GPU	-	#pragma acc routine	__global__, __device__

※ “# of XXX” = “The number of XXX”

# Calling A GPU Kernel Function from CPU



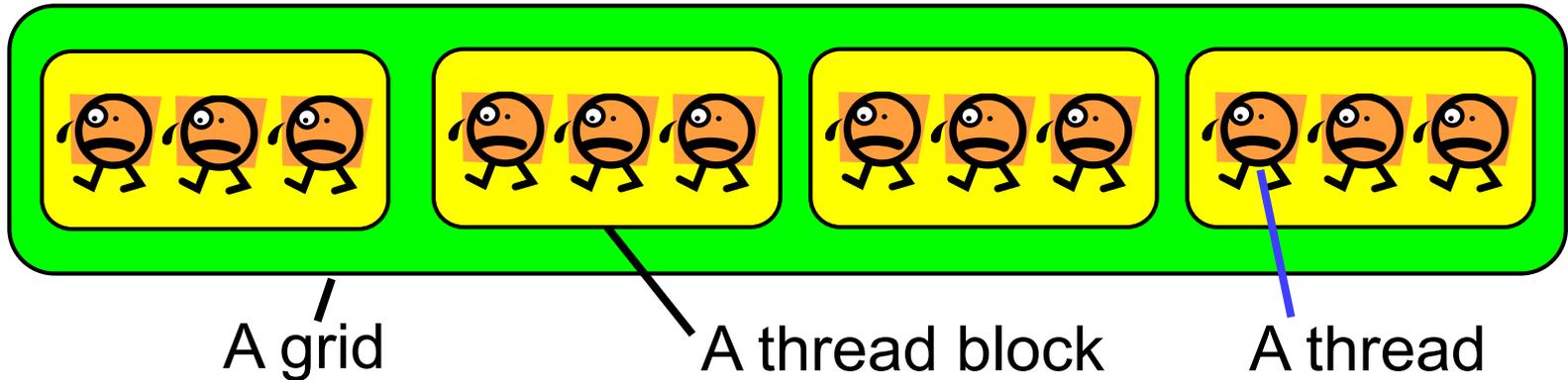
- A region executed by GPU must be a distinct function
  - called a GPU kernel function





# Threads in CUDA

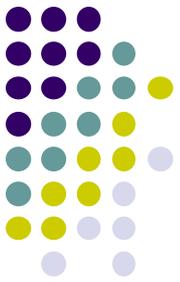
Specify 2 numbers (at least) for number of threads, when calling a GPU kernel function



cf) func <<< 4, 3 >>> (); → 12 threads

Number of thread blocks = gridDim  
Number of threads per block = blockDim

The reason is related to GPU hardware  
Thread block ⇔ SMX, Thread ⇔ CUDA core

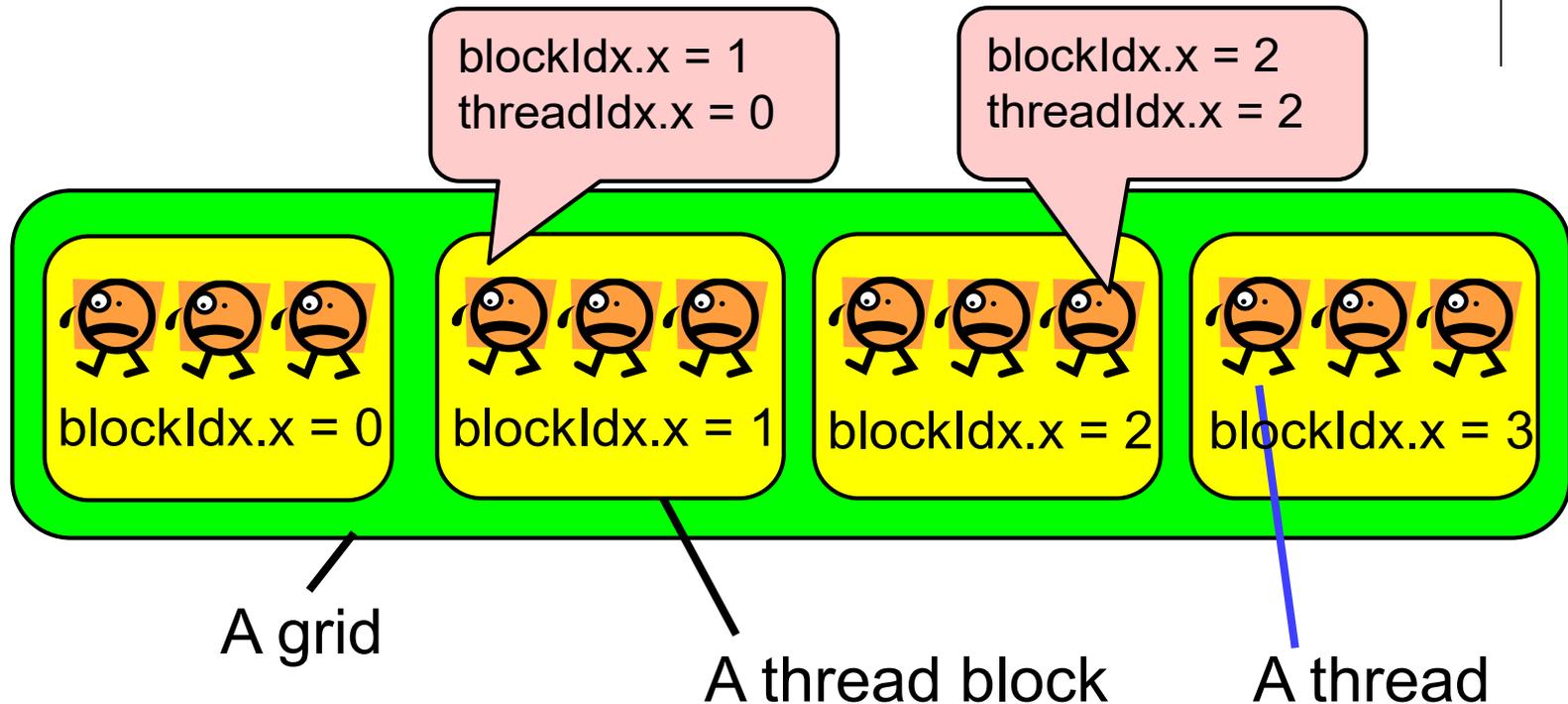


# To See Who am I

- By reading the following special variables, each thread can see its thread ID in GPU kernel function
- My ID
  - blockIdx.x: Index of the block the thread belong to ( $\geq 0$ )
  - threadIdx.x: Index of the thread (**inside the block**) ( $\geq 0$ )
- Number of thread/blocks
  - blockDim.x: How many threads (**per block**) are running



# Thread Block ID, Thread ID



For every thread, `gridDim.x = 4`, `blockDim.x = 3`

Note: In order to see the entire sequential ID, we should compute  $\text{blockIdx.x} * \text{blockDim.x} + \text{threadIdx.x}$

# How Number of Threads is Designed? (1)



On CUDA, Different strategy is required from on OpenMP

- On OpenMP, number of threads (`OMP_NUM_THREADS`) should be  $\leq$  CPU cores

- The number is basically determined by hardware
- $\leq 7$  on q\_node node,  $\leq 28$  on f\_node

- On CUDA, it is better to use number of thread  $\geq$  GPU cores

- $\geq 3584$  on TSUBAME3's P100 GPU
- You can use  $>1,000,000$  threads!

# How Number of Threads is Designed? (2)



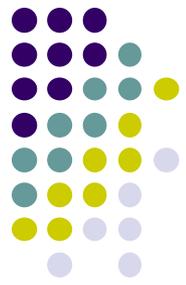
We have to decide 2 numbers  
<<<block number, block size>>>

A better way would be

- (1) We decide **total** number of threads  $P$
- (2) We tune each block size  $BS$ 
  - Good candidates are 16, 32, 64, ... 1024
- (3) Then block number is  $P/BS$ 
  - We consider indivisible cases later



# “mm” sample: Matrix Multiply (related to [G2])



CUDA versions are at

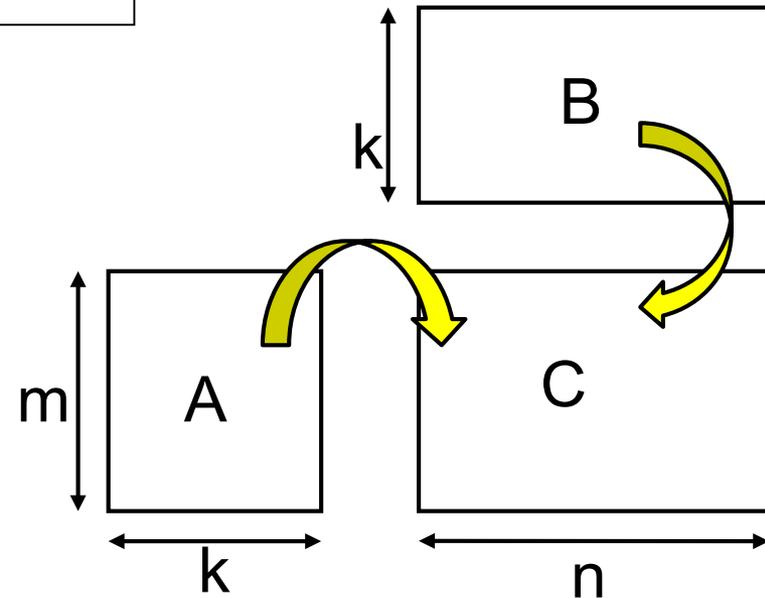
- </gs/hs1/tga-ppcomp/20/mm-v1-cuda/>
- </gs/hs1/tga-ppcomp/20/mm-cuda/>

A: a  $(m \times k)$  matrix, B: a  $(k \times n)$  matrix

C: a  $(m \times n)$  matrix

$$C \leftarrow A \times B$$

- Supports variable matrix size
- Execution: `./mm [m] [n] [k]`



On CUDA, We need to design  
(1) How we parallelize computation  
(2) How we put data on host memory & device memory



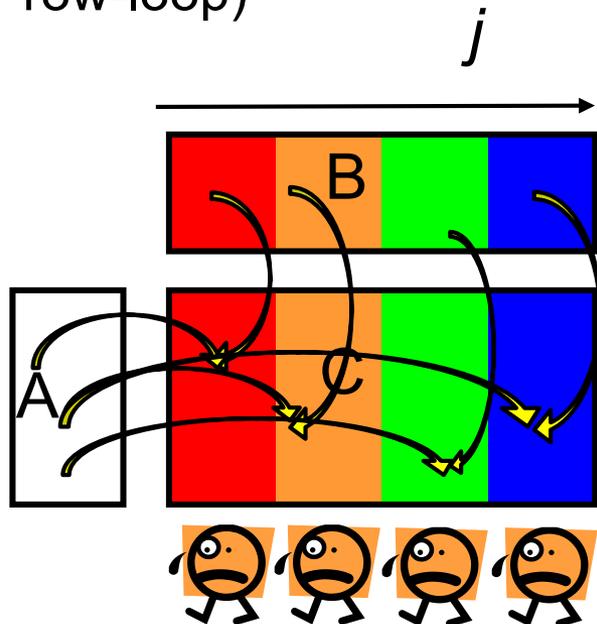
# How We Parallelize Computation

In mm, we can compute different C elements in parallel

- On the other hand, it is harder to parallelize dot-product loop

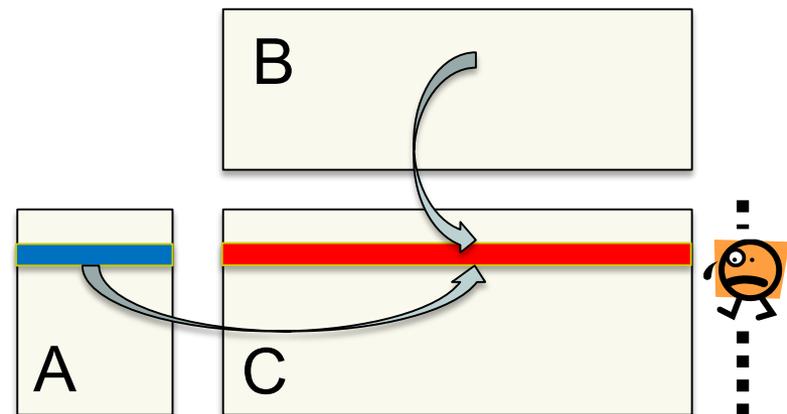
## OpenMP

- Parallelize column-loop  
(or row-loop)



## CUDA (mm-v1-cuda)

- We can create many threads
- 1 thread computes 1 row
  - We use  $m$  threads



✘ This is not the unique way



# Parallelism in mm-v1-cuda

- It is ok to make  $>1000$ ,  $>10000$  threads on CUDA
- We use  $m$  threads for  $m$  rows computation

```
add<<<m/BS, BS>>>(.....);
```

gridDim

blockDim (BS=16 in this sample)

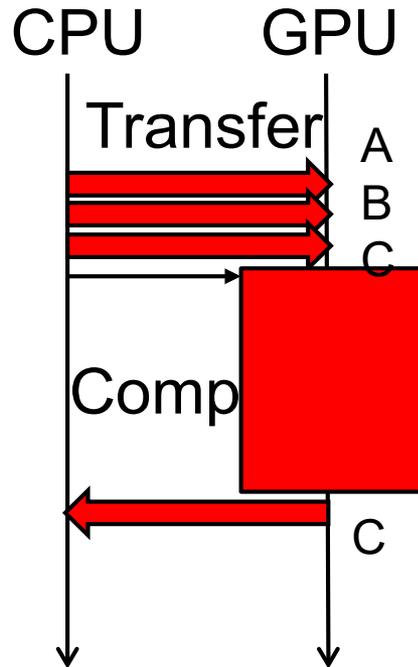
1 element for 1 row  $\rightarrow$  No need of “i” loop in this sample

Note1:  $\langle\langle\langle m, 1 \rangle\rangle\rangle$  also works, but speed is not good  
 $\langle\langle\langle 1, m \rangle\rangle\rangle$  causes an error if  $m > 1024$  (CUDA's rule)

Note2: To support the case  $m$  is indivisible by  $BS$ , we should use  
 $\langle\langle\langle (m+BS-1)/BS, BS \rangle\rangle\rangle$   
 $\rightarrow$  But # of threads may be larger  $m$ . “Extra” threads ( $id \geq m$ ) should not work. See [mm-v1-cuda/mm.c](#)



# Data Transfer in mm-v1-cuda

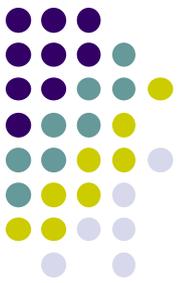


- A, B, C are copied from CPU to GPU before computation
  - `cudaMemcpy(DA, A, ... ) ...`
- C is copied from GPU to CPU after computation
  - `cudaMemcpy(C, DC, ... )`



# Notes in Time Measurement

- `clock()`, `gettimeofday()` must be called from CPU
- For accurate measurement, we should call `cudaDeviceSynchronize()` before measurement
  - Actually GPU kernel function call and `cudaMemcpy(HostToDevice)` are non-blocking



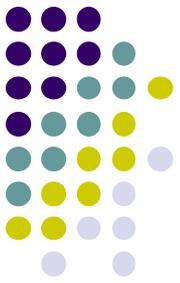
# Speed of mm-v1-cuda

- Measured with a P100 GPU on TSUBAME3

m=n=k	mm-acc	mm-v1-cuda
1000	143(Gflops)	14(Gflops)
2000	173	27
4000	164	50
6000	138	70
8000	137	85

- The program outputs 2 speeds
  - Speed with data transfer costs → shown on the above table
  - Speed without data transfer costs

# Discussion on Speed (related to [G2])



- mm-v1-cuda is slower than mm-acc
  - In mm-acc, i-loop and j-loop has “loop independent”  
→  $m n$  elements are computed in parallel
- In mm-v1-cuda, we use  $m$  threads are used  
→ We need more parallelism on a GPU!
  - We see 4000 or 6000 threads are still insufficient
- (1thread=1row) and (1thread=1column) have different speed
  - Due to “coalesced memory access”, explained in the next class

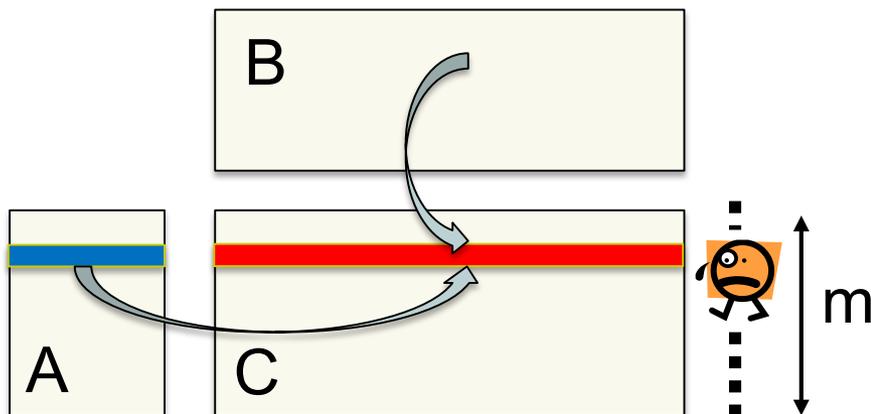
# Parallelization of mm Sample (related to [G2])



In mm, computation of each C element is independent with each other

CUDA (mm-v1-cuda)

- 1 thread computes 1 row
  - We use  $m$  threads



⊗ This is not the unique way

We have seen that this is slower than OpenACC version ☹ -- Why?

- The number of threads ( $m$ ) is still insufficient on GPUs
- If (1thread = 1element), we can use  $m*n$  threads

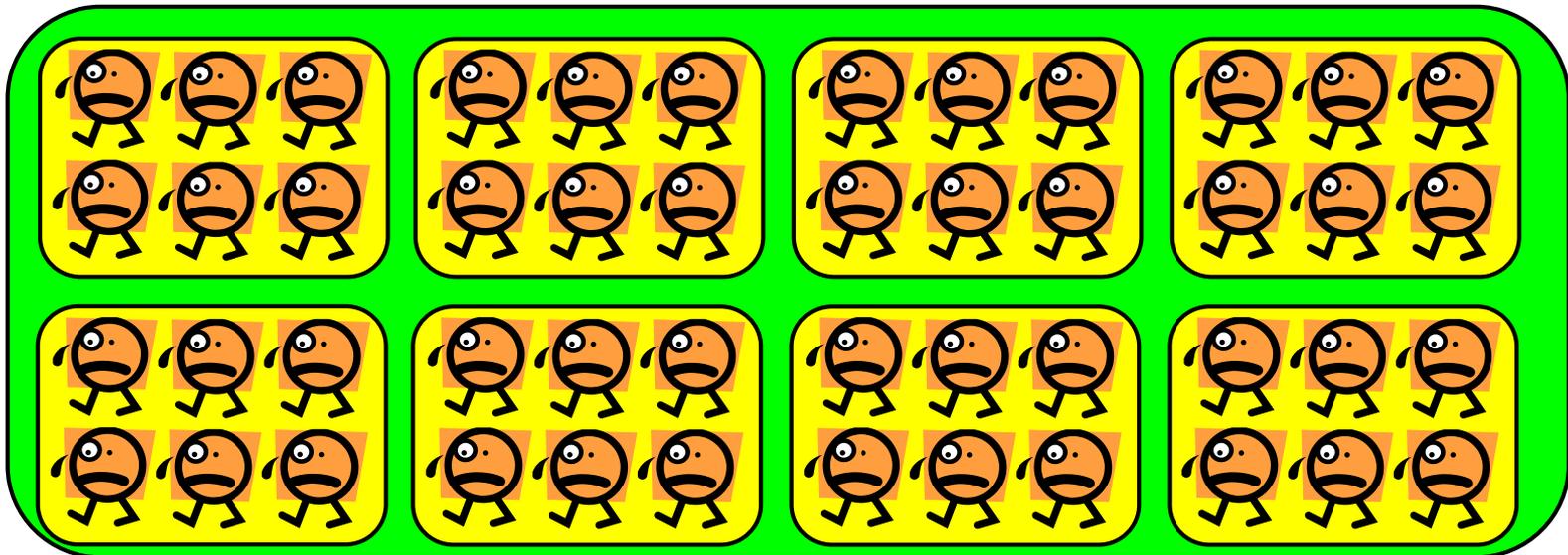
How can we do that on CUDA?

# Creating Threads with 2D/3D IDs



- Now we want to make  $m*n$  (may be  $>1,000,000$ ) threads
  - `<<<(m*n)/BS, BS>>>` is ok, but coding is bothersome
- On CUDA, `gridDim` and `blockDim` may have “**dim3**” type, 3D vector structure with `x`, `y`, `z` fields

cf) func `<<< dim3(4,2,1), dim3(3,2,1) >>> ();` → 48 threads

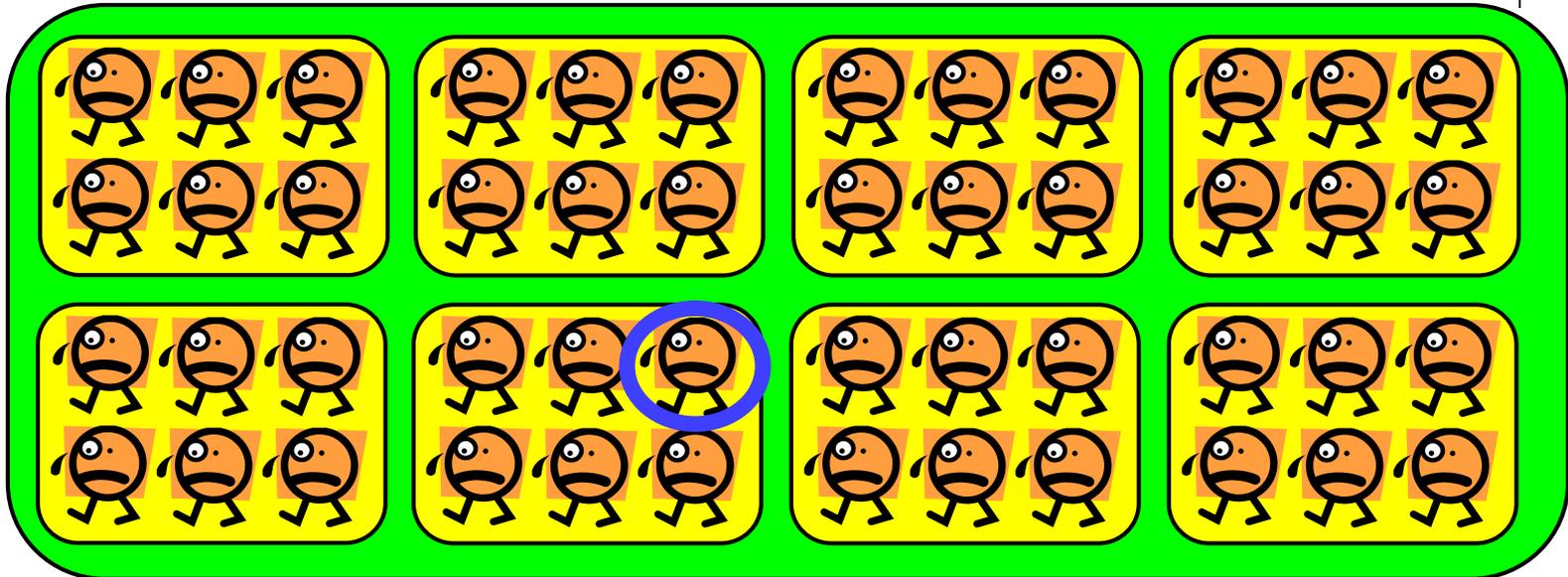


✘ This example is the case of 2D (Z dimensions are 1)

# Thread IDs in multi-dimensional cases



In the case of func `<<< dim3(4,2,1), dim3(3,2,1) >>> ();`

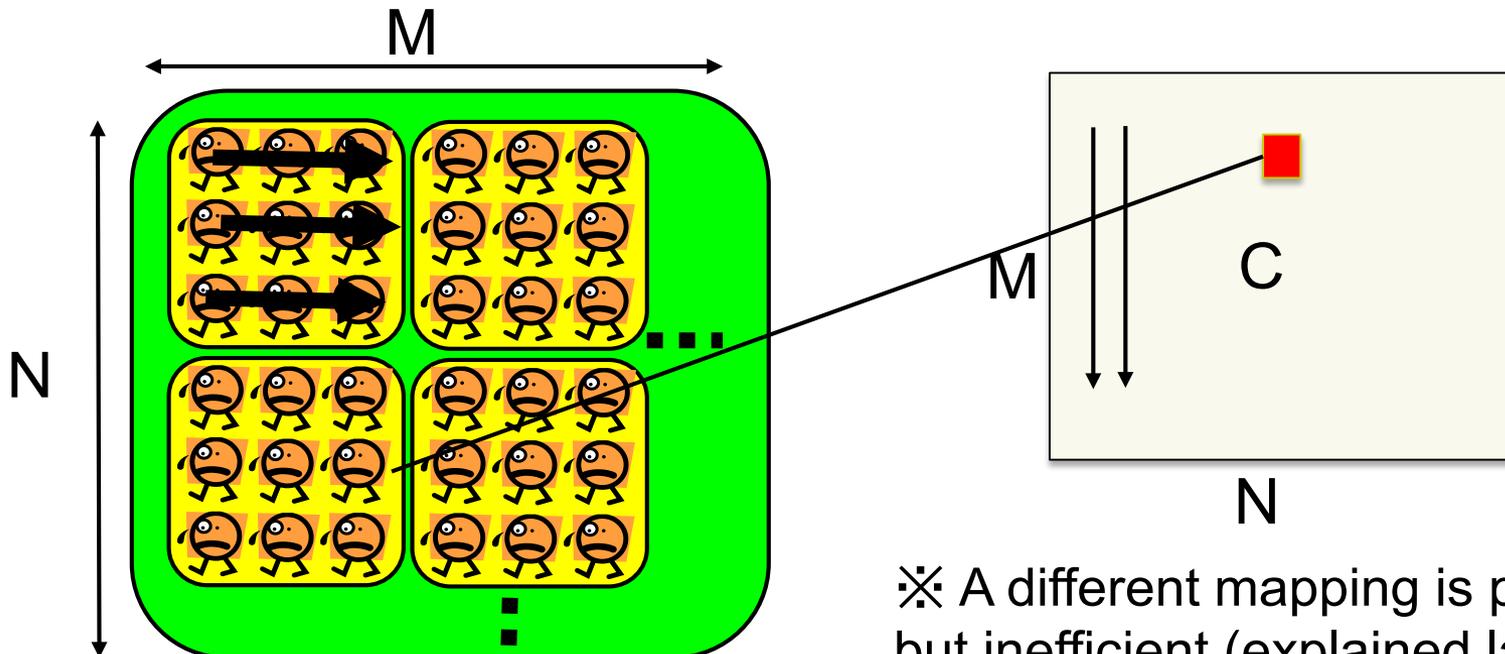


- For every thread,  
gridDim.x=4, gridDim.y=2, gridDim.z=1  
blockDim.x=3, blockDim.y=2, blockDim.z=1
- For the thread with blue mark,  
blockIdx.x=1, blockIdx.y=1, blockIdx.z=0  
threadIdx.x=2, threadIdx.y=0, threadIdx.z=0



# Threads in mm-cuda Sample

- The total number of threads are  $m*n$
- How do we determine gridDim, blockDim?
  - `<<<m, n>>>` does not work for constraints explained later ☹
- Here, we use fixed blockDim ( $x=16, y=16 \rightarrow 256$  threads per block)
- Then gridDim is computed from  $M, N$
- $x$  is mapped to row index,  $y$  is mapped to column index (⊗)



⊗ A different mapping is possible, but inefficient (explained later)



# Code in mm2-cuda

gridDim

blockDim

```
matmul_kernel<<<dim3(m / BS, n / BS, 1), dim3(BS, BS, 1)>>>  
(DA, DB, DC, m, n, k);
```

**BS=16 in this sample**  
**Actually, we use rounding up**

*In matmul\_kernel function,*

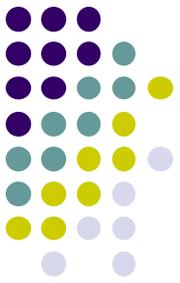
:

$j = \text{blockIdx.y} * \text{blockDim.y} + \text{threadIdx.y};$

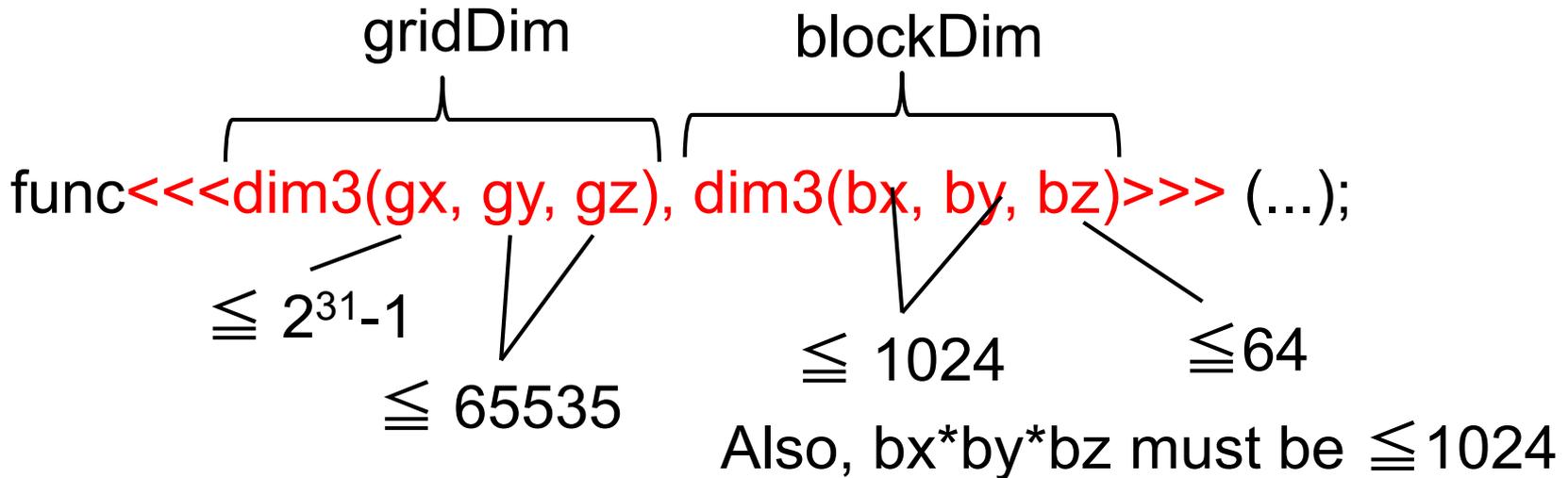
$i = \text{blockIdx.x} * \text{blockDim.x} + \text{threadIdx.x};$

: This thread computes  $C_{ij} \leftarrow$  Only k loop

# CUDA Rules on Number of Threads



`func<<<gs, bs>>> (...);` is interpreted as  
`func<<<dim3(gs,1,1), dim3(bs,1,1)>>> (...);`



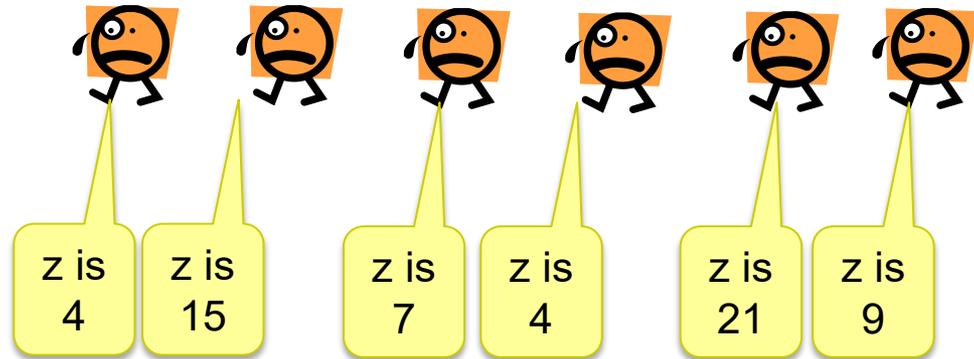
BlockDim has severe limitation ☹

Cf) `<<<m, n>>>` causes an error if  $n > 1024$  ☹



# Rules for Memory/Variables

- Variables declared in GPU kernel functions are “**thread private**”



- Device memory is **shared** by all CUDA threads
  - Be careful to avoid race condition problem (multiple threads write same address)
  - Reading same address is ok
- Do not forget host memory and device memory are distributed



# Two Types of GPU Kernel Functions

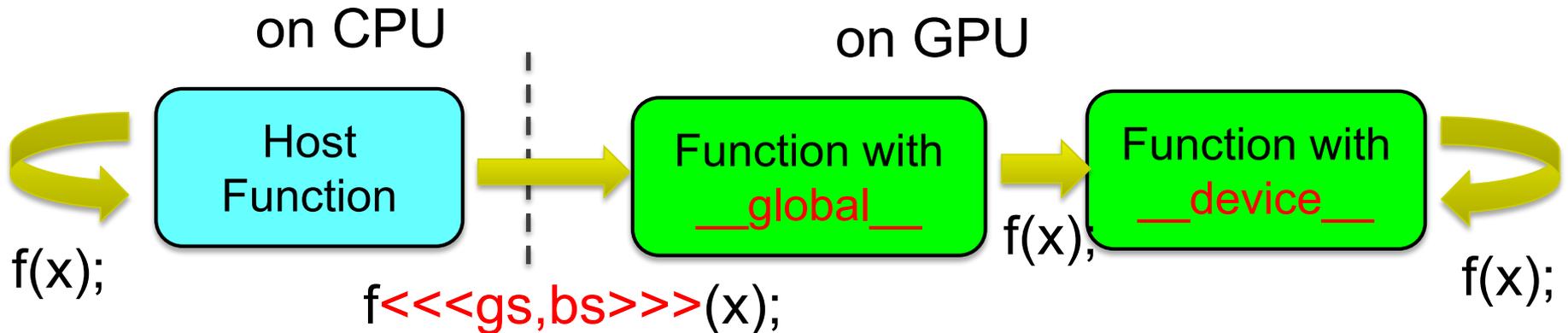
## 1) Functions with `__global__` keyword

- “Gateway” from CPU
- Return value type must be “void”

## 2) Function with `__device__` keyword

- Callable only from GPU
- Can have return values
- Recursive call is OK

→ In OpenACC, `#pragma acc routine`

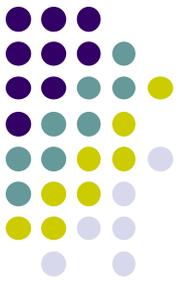


# What Can be Done in GPU Functions?



- Basic computations (+, -, \*, /, %, &&, ||...) are **OK**
- if, for, while, return are **OK**
- Device memory access is **OK**
- Host memory access is **NG**
- Calling host functions is **NG**
- Calling most of functions in libc or other libraries for CPUs are **NG**
  - Several mathematical functions, sin(), sqrt()... are **OK**
    - like OpenACC
  - Exceptionally, printf() is **OK**
    - unlike OpenACC 😊
  - Calling malloc()/free() on GPU is **OK**, if the size is small
    - If we need large regions on device memory, call cudaMalloc() from CPU

# Assignments in GPU Part (Abstract)



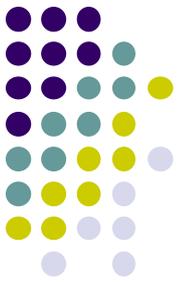
Choose one of [G1]—[G3], and submit a report

Due date: **June 18 (Thursday)**

[G1] Parallelize “diffusion” sample program by OpenACC or CUDA

[G2] Evaluate speed of “mm-acc” or “mm-cuda” in detail

[G3] (**Freestyle**) Parallelize *any* program by OpenACC or CUDA.



# Next Class:

- GPU Programming (4)
  - Discussion on diffusion
  - Some techniques for speed