



2018 2Q  
Wireless Communication Engineering

# #5 Demodulation and Matched Filter

Kei Sakaguchi  
sakaguchi@mobile.ee.

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# Course Schedule (1)

	Date	Text	Contents
#1	June 11	1, 7	Introduction to wireless communication systems
#2	June 14	2, 5, etc	Link budget design of wireless access
#3	June 18		Up/down conversion and equivalent baseband system
#4	June 21	3.3, 3.4	Digital modulation and pulse shaping
#5	June 25	3.5	Demodulation and matched filter
#6	June 28		Collaborative exercise for better understanding 1
#7	July 2	3.5	Detection and error due to noise
#8	July 5	4.4	Channel fading and diversity combining

# From Previous Lecture

## ■ Digital modulation

$$s_D(t) = s_{DI}(t) + js_{DQ}(t) = f(m(t))$$

- Amplitude
- Phase
- Frequency



Data rate, power efficiency, complexity, error rate

## ■ Pulse shaping (band limitation)

$$s_B(t) = \int g(\tau) s_D(t - \tau) d\tau$$

- Rectangular
- Nyquist
- Gaussian



Bandwidth, error rate

## ■ IQ analog modulation

$$s(t) = s_{BI}(t) \cos(2\pi f_c t) - s_{BQ}(t) \sin(2\pi f_c t)$$

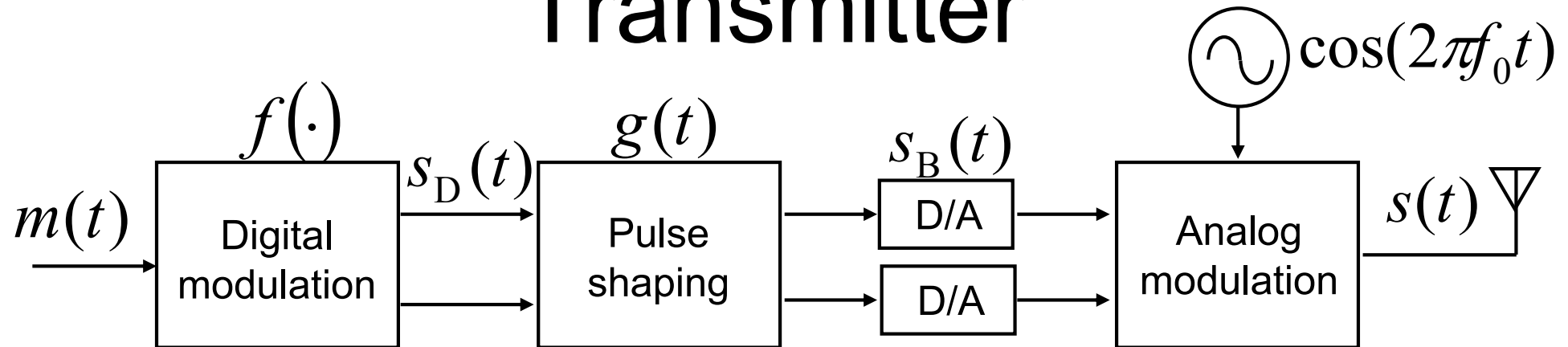


Carrier frequency

# Contents

- Structure of receiver
- Analog demodulation
- Noise through analog demodulator
- Receive sampling
- Matched filter
- Output SNR

# Transmitter



Carrier freq.  $f_0$

Coverage  $d_0 = \sqrt{\frac{A_t P_t}{4\pi\alpha N_0 f_0 \gamma_0}}$

Symbol length  $T_s$

Bandwidth  $B \propto 1/T_s$

Modulation order  $M$

Data rate  $\frac{\log_2 M}{T_s}$

Modulation  $f(\cdot)$

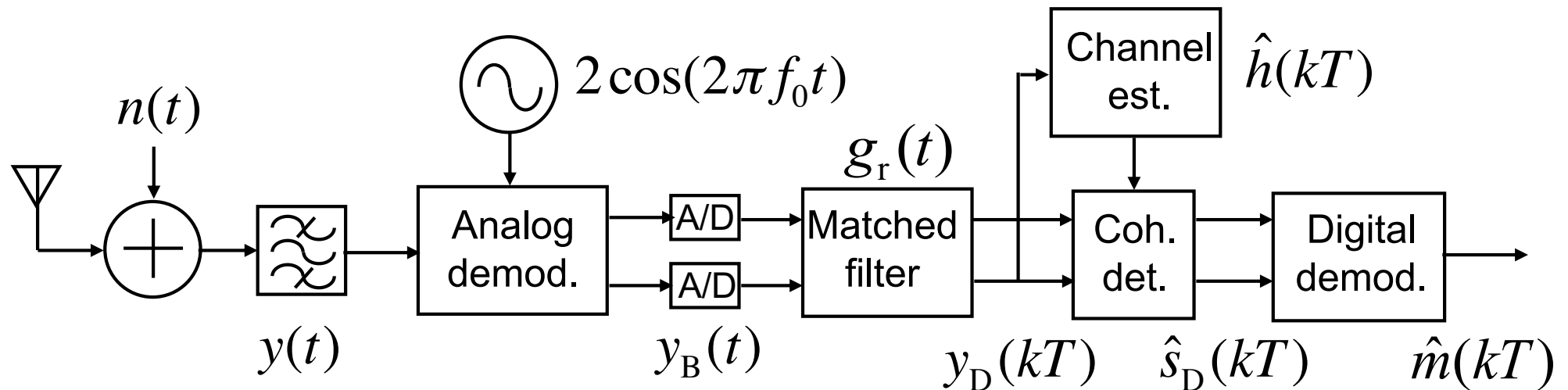
Energy efficiency,  
Complexity of circuit,  
Bit error rate  $p_e$

Pulse  $g(t)$

Power leakage

$$S_B^s(t) = |g(f)|^2 S_D^s(f)$$

# Receiver



Additive white noise

Thermal noise generated in receiver

Bandpass filter

Inter system interference cancellation

Analog demodulation

Convert signal from RF to BB

Matched filter

Maximization of SNR

Coherent detection

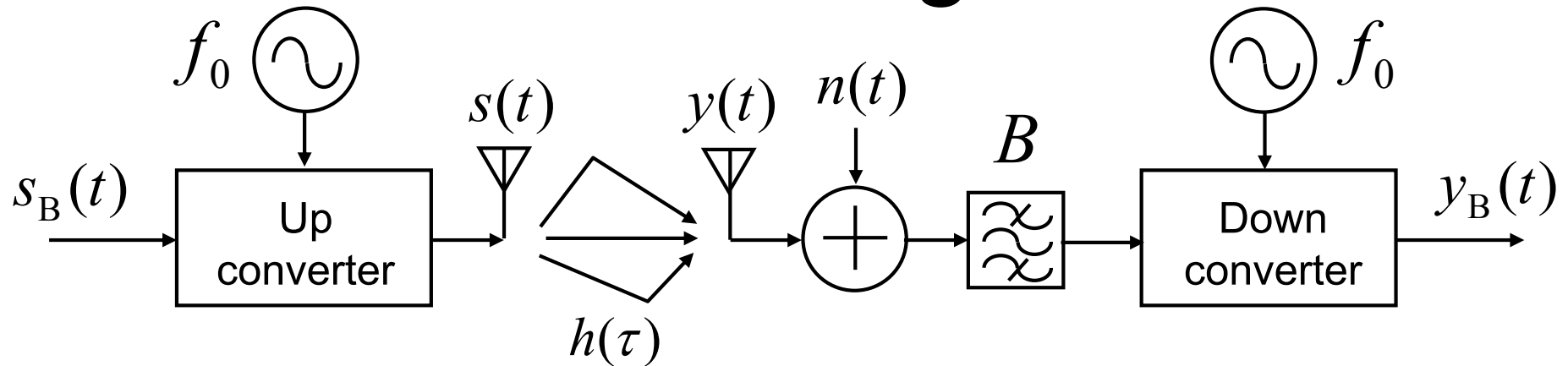
Compensation of channel response

Digital demodulation

Convert complex signal to message



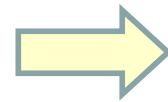
# RF & BB Signals



Transmitter

Receiver

$$s(t) = \text{Re}[s_A(t)]$$



$$y(t) = \int h(\tau) s(t - \tau) d\tau$$



$$s_A(t) = s_B(t) e^{j2\pi f_0 t}$$



$$y_A(t) = y(t) + j \text{hilb}(y(t))$$



$$s_B(t)$$



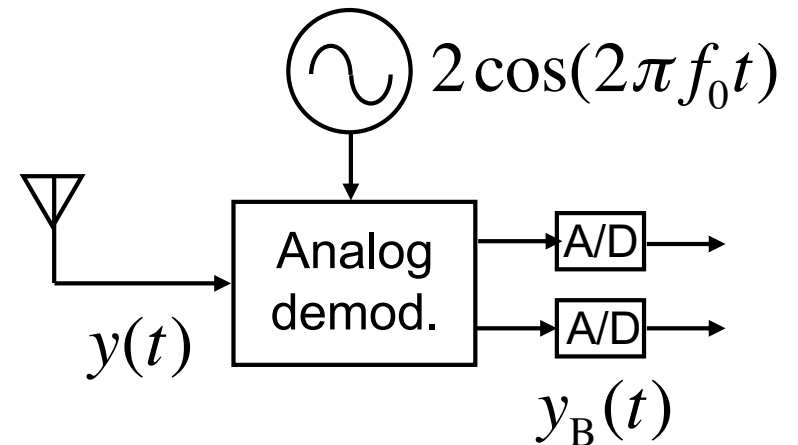
$$y_B(t) = y_A(t) e^{-j2\pi f_0 t}$$

# Analog Demodulation

Inputs & outputs of analog demodulator

$$y_B(t) = y_{BI}(t) + jy_{BQ}(t)$$

$$y_A(t) = y_B(t)e^{j2\pi f_0 t}$$



$$y(t) = \text{Re}[y_A(t)]$$

RF input

$$= y_{BI}(t) \cos 2\pi f_0 t - y_{BQ}(t) \sin 2\pi f_0 t$$

BB output

BB output



# Analog Demodulation

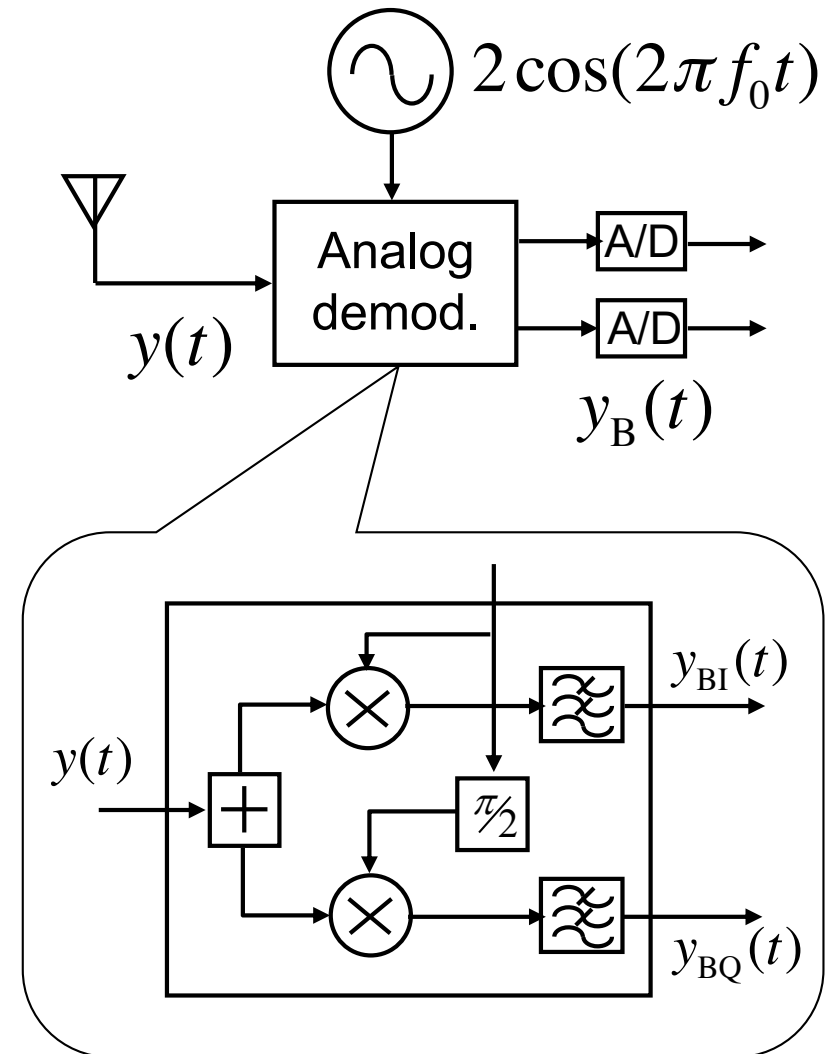
$$y(t) = y_{\text{BI}}(t) \cos 2\pi f_0 t - y_{\text{BQ}}(t) \sin 2\pi f_0 t$$

In-phase BB receive signal

$$\begin{aligned} y_{\text{BI}}(t) &= \text{LPF}[2y(t) \cos 2\pi f_0 t] \\ &= \text{LPF}[y_{\text{BI}}(t)(1 + \cancel{\cos 4\pi f_0 t}) \\ &\quad - y_{\text{BQ}}(t) \cancel{\sin 4\pi f_0 t}] \end{aligned}$$

Quadrature BB receive signal

$$\begin{aligned} y_{\text{BQ}}(t) &= \text{LPF}[-2y(t) \sin 2\pi f_0 t] \\ &= \text{LPF}[-y_{\text{BI}}(t) \cancel{\sin 4\pi f_0 t} \\ &\quad + y_{\text{BQ}}(t)(1 - \cancel{\cos 4\pi f_0 t})] \end{aligned}$$



# Noise Through Analog Demodulator

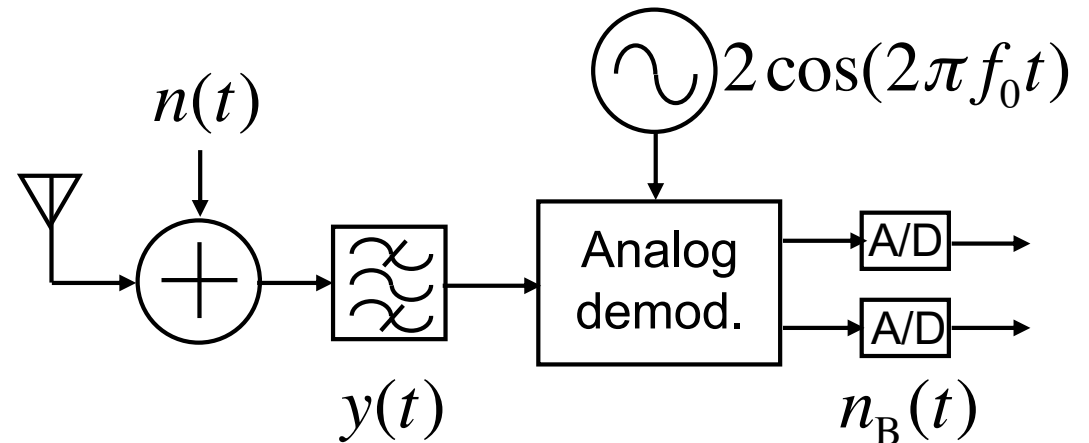
## BB noise

$$n_B(t) = n_{BI}(t) + jn_{BQ}(t)$$

$$n_A(t) = n_B(t)e^{j2\pi f_0 t}$$

$$n(t) = \text{Re}[n_A(t)]$$

$$= n_{BI}(t) \cos 2\pi f_0 t - n_{BQ}(t) \sin 2\pi f_0 t$$



## Analog demodulation

$$n_{BI}(t) = \text{LPF}[2n(t)\cos 2\pi f_0 t]$$

$$n_{BQ}(t) = \text{LPF}[-2n(t)\sin 2\pi f_0 t]$$

# Property of Noise

## Noise power

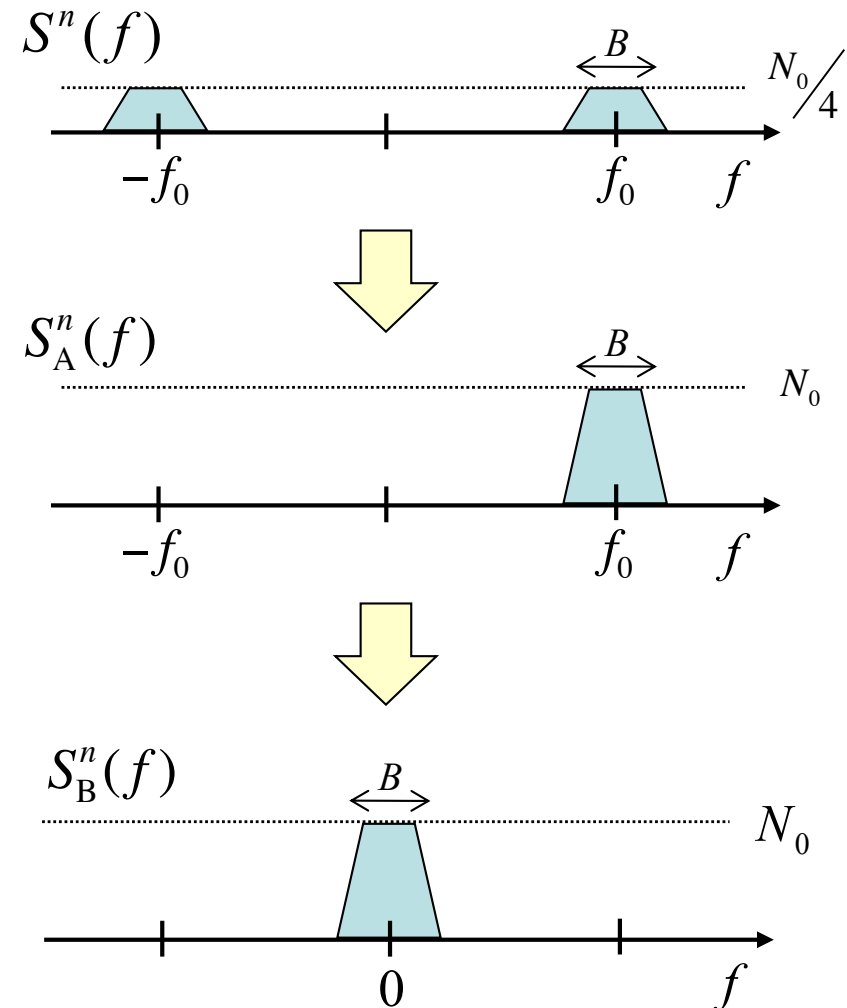
$$P_n = P_{nI} + P_{nQ} = N_0 B = \sigma^2$$

## PDF of noise

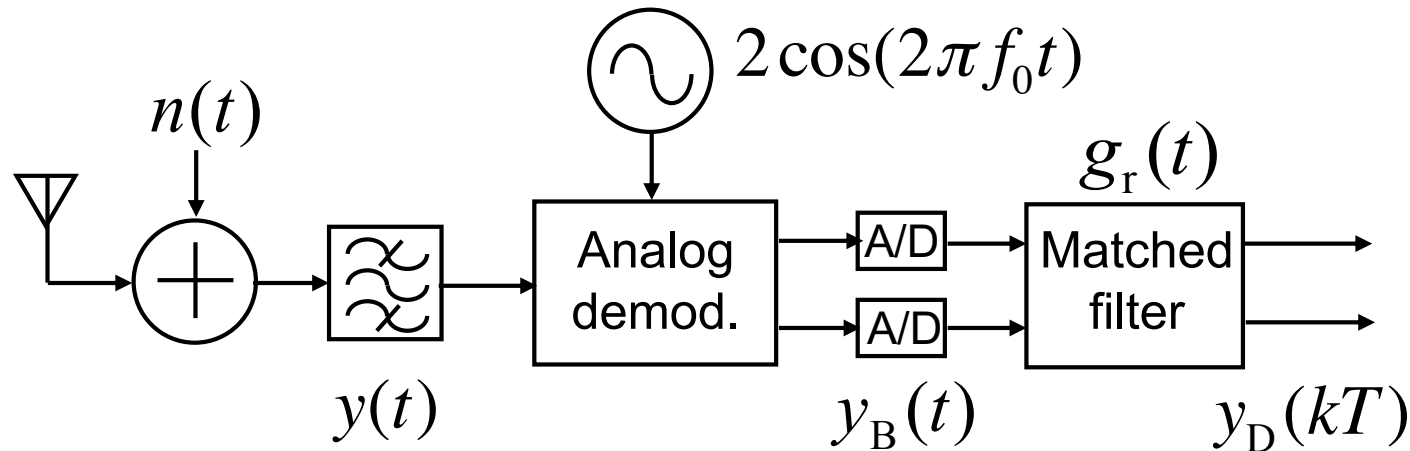
$$p(n_I) = p(n_Q) = \frac{1}{\sqrt{\pi\sigma^2}} e^{-\frac{n_x^2}{\sigma^2}}$$

$$E[n_I] = E[n_Q] = 0$$

$$E[|n_I|^2] = E[|n_Q|^2] = \frac{\sigma^2}{2}$$



# BB Receive Filter



BB received signal

$$y_B(t) = h_B s_B(t) + n_B(t)$$

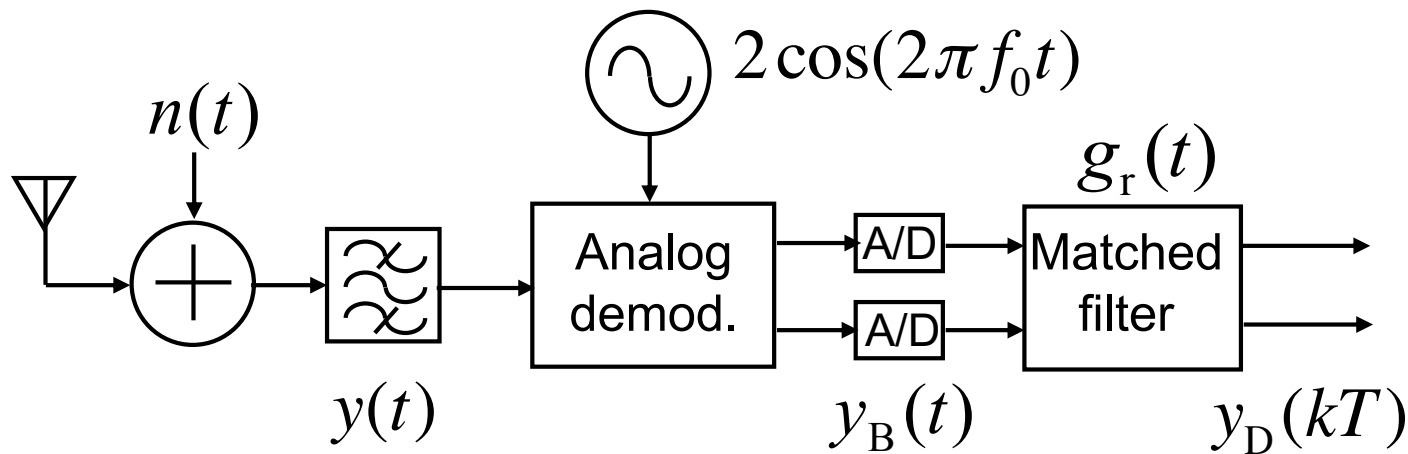
BB transmit signal

$$s_B(t) = \underbrace{g_s(t)}_{\text{Transmit pulse}} \otimes s_D(t) = \sum_n a_n g_s(t - nT)$$

Output of receiver filter

$$y_D(t) = \underbrace{g_r(t)}_{\text{Receive pulse}} \otimes \underbrace{g_s(t)}_{\text{Combined pulse}} \otimes s_D(t) + g_r(t) \otimes n_B(t)$$

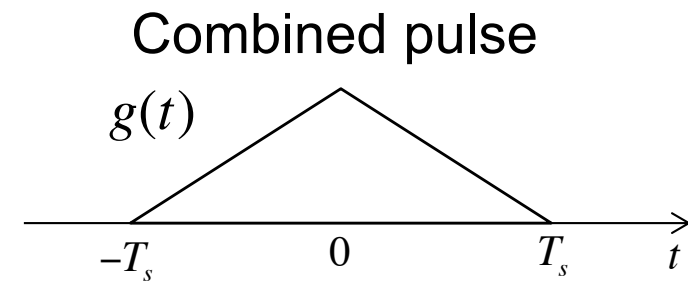
# BB Receive Sampling



Output of receive filter (wo noise)

$$y_D(t) = g_r(t) \otimes g_s(t) \otimes s_D(t)$$

$$= g(t) \otimes s_D(t)$$

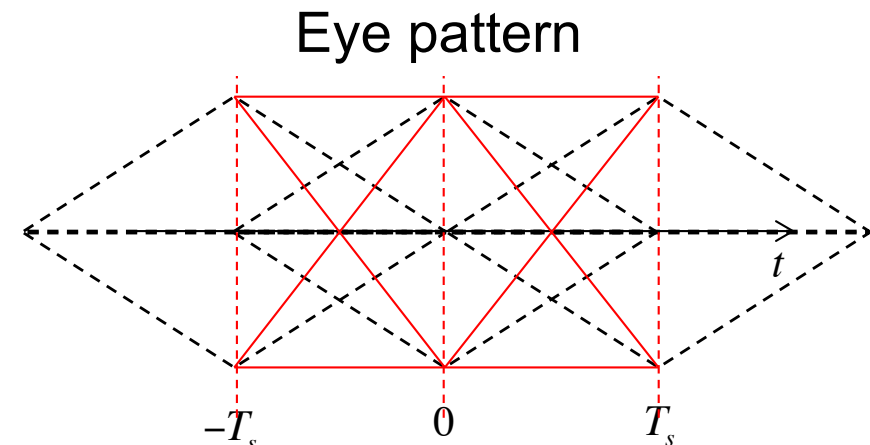


Digital modulated signal (BPSK)

$$s_D(t) = \sum_k a_{2k} \delta(t - kT_s)$$

Receive sampling

$$y_D(kT_s) = g(0)a_{2k}$$



# BB Receive Power

## Signal power

$$\begin{aligned}
 g(t) &= g_r(t) \otimes g_s(t) & \Leftrightarrow & & G(f) &= G_r(f)G_s(f) \\
 g(0) & & = & & \int G_r(f)G_s(f)e^{j2\pi ft} df & \\
 P_s &= |g(0)|^2 & = & & \left| \int G_r(f)G_s(f) df \right|^2 &
 \end{aligned}$$

## Noise power

$$\begin{aligned}
 R_B^n(\tau) &= E[n_B^*(t)n_B(t+\tau)] = N_0\delta(0) & \Leftrightarrow & & S_B^n(f) &= N_0 \\
 n_D(t) &= g_r(t) \otimes n_B(t) & \Leftrightarrow & & S_D^n(f) &= |G_r(f)|^2 S_B^n(f) = N_0 |G_r(f)|^2 \\
 P_n &= E[|n_D(t)|^2] & = & & N_0 \int |G_r(f)|^2 e^{j2\pi f\tau} df &= N_0 \int |G_r(f)|^2 df
 \end{aligned}$$

# Matched Filter

SNR maximization

$$\gamma_{\max} = \max \frac{P_s}{P_n} = \max_{G_r(f)} \frac{\left| \int G_r(f) G_s(f) df \right|^2}{N_0 \int |G_r(f)|^2 df}$$

Schwartz inequality

$$\left| \int G_r(f) G_s(f) df \right|^2 \leq \int |G_r(f)|^2 df \int |G_s(f)|^2 df$$

Matched filter

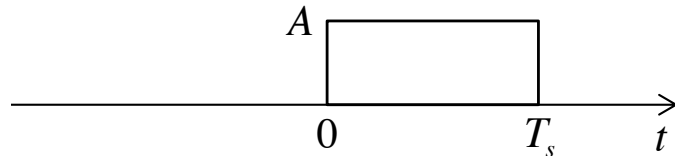
$$G_r(f) = (G_s(f))^* \iff g_r(t) = g_s(-t)$$

$$\gamma_{\max} = \frac{1}{N_0} \int |G_s(f)|^2 df$$

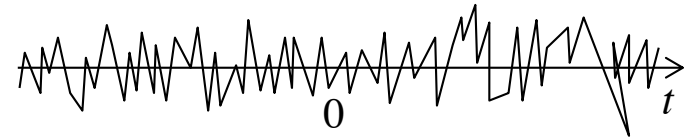


# Example of Matched Filter

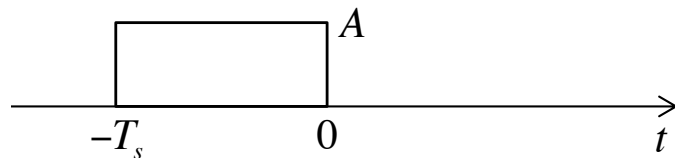
$$g_s(t)$$



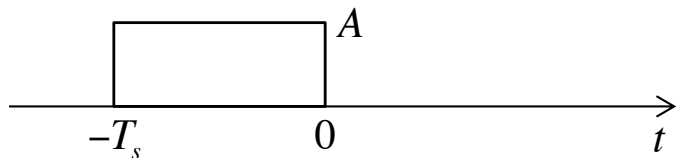
$$n_B(t)$$



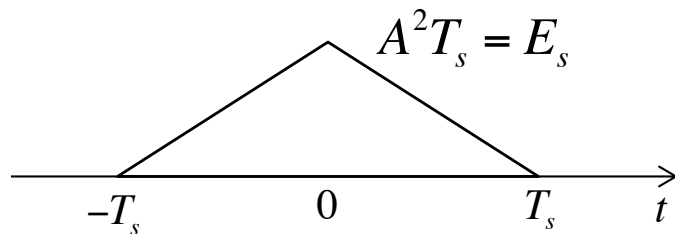
$$g_r(t) = g_s(-t)$$



$$g_r(t) = g_s(-t)$$

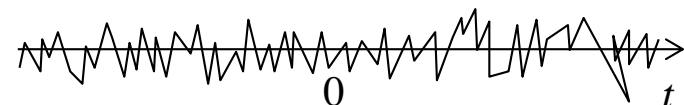


$$g(t) = \int g_r(\tau) g_s(t - \tau) d\tau$$



$$n_D(t) = \int g_r(\tau) n_B(t - \tau) d\tau$$

$$E[|n_D(t)|^2] = N_0 \int |G_r(f)|^2 df = A^2 T_s N_0$$



# Output SNR

Matched filter output

$$\gamma_{\max} = \frac{1}{N_0} \int |G_s(f)|^2 df$$

Parseval's theorem

$$\int |G_s(f)|^2 df = \int |g_s(t)|^2 dt = E_s$$

Energy per symbol

Output SNR

$$\gamma_{\max} = \frac{E_s}{N_0} = \frac{P_s T_s}{N_0} = \frac{P_s}{N_0 B} = \frac{P_s}{\sigma^2}$$

# Summary

## ■ Analog demodulation

$$y(t) = y_{\text{BI}}(t) \cos 2\pi f_0 t - y_{\text{BQ}}(t) \sin 2\pi f_0 t$$

$$y_{\text{BI}}(t) = \text{LPF}[2y(t) \cos 2\pi f_0 t] \quad y_{\text{BQ}}(t) = \text{LPF}[-2y(t) \sin 2\pi f_0 t]$$

## ■ Matched filter

$$P_s = \left| \int G_r(f) G_s(f) df \right|^2 \leq \int |G_r(f)|^2 df \int |G_s(f)|^2 df$$

$$G_r(f) = (G_s(f))^* \quad \Leftrightarrow \quad g_r(t) = g_s(-t)$$

## ■ Output SNR

$$\gamma_{\text{max}} = \frac{1}{N_0} \int |G_s(f)|^2 df = \frac{E_s}{N_0} = \frac{P_s}{\sigma^2}$$