2018 Practical Parallel Computing (実践的並列コンピューティング) No. 8

Distributed Memory Parallel Programming with MPI (2)

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- Receiver specifies "source" and "tag" that it wants to receive
- Generally, several messages may arrive indefinite order
- \rightarrow The message that matches the condition is delivered
- Other messages should be received by other MPI_Recv calls

Notes on MPI_Recv: Message Matching (2)



- In some algorithms, the sender may not be known beforehand
 - cf) client-server model
- For such cases, MPI_ANY_SOURCE / MPI_ANY_TAG can be used



Notes on MPI_Recv: What If Message Size is Unmatched



MPI_Recv(b, 16, MPI_INT, 0, 100, MPI_COMM_WORLD, &stat);



If message is larger than expected, it's an error (the program aborts)

If message is smaller than
expected, it's ok
→ Receiver can know the
actual size by
MPI_Get_Count(&stat, MPI_INT, &s);

It is a good idea for receiver to prepare enough memory

"diffusion" Sample Program (1) (Revisited)

An example of diffusion phenomena:

• Pour a drop of ink into a water glass



The ink spreads gradually, and finally the density becomes uniform (Figure by Prof. T. Aoki)

 Density of ink in each point vary according to time → Simulated by computers



"diffusion" Sample Program (2) (Revisited)

Available at ~endo-t-ac/ppcomp/18/diffusion/

- Execution:./diffusion [nt]
- nt: Number of time steps
- nx, ny: Space grid size
 - nx=8192, ny=8192 (Fixed. See the code)
 - How can we make them variables? (See mm sample)
- Compute Complexity: O(nx × ny × nt)

Data Structures in diffusion (Revisited)

 Space to be simulated are divided into grids, and expressed by arrays (2D in this sample)

NX

 Array elements are computed via timestep, by using "previous" data

NY





Double Buffering Technique (Revisited)

- A simple way is to make arrays for all time steps, but it consumes too much memory!
- → It is sufficient to have "current" array and "previous" array. "Double buffers" are used for many times



Sample program uses a global variables float data[2][NY][NX];



How Do We Parallelize "diffusion" Sample?



Parallelization method with OpenMP:

[Algorithm] Parallelize spatial (Y or X) for-loop

- Each thread computes its part in the space
- Time (T) loop cannot be parallelized, due to dependency

[Data] Data structure is same as sequential version

With MPI:

[Algorithm] Same policy as OpenMP version

• Each process computes its part in the space

[Data] Arrays are divided among processes

• Each process has its own part of arrays

Considering Data Distribution (1)





• A color = a process

Considering Data Distribution (2)

• A simple distribution is like:



So, where should received data be put?

Introducing "Halo" Region



It is a good idea to make additional rows to arrays

→ called "Halo" region or "sleeve" region



Each time step consists of:

- (1) Communication: Recv data and store into "halo" region
 - Also neighbor processes need "my" data
- (2) Computation: Old data at time t (including "halo")
 - → New data at time t+1



The name of "Halo" Region



en.wiktionary.org

C dak

Overview of MPI "diffusion" (Still Unsafe)





for (t = 0; t < nt; t++) {
 Send B to rank-1, Send D to rank+1
 Recv A from rank-1, Recv E from rank+1 }-(1) Communication</pre>

Computes points in rows B-D \rightarrow (2) Computation Switch old and new arrays

This version is still unsafe, because this may cause deadlock

A Sample for Safe Neighbor Communication

Available at ~endo-t-ac/ppcomp/18/neicomm/ Execution: mpirun –np [np] ./neicomm

(1) Each process produces a single value (rank² here)
(2) Each process receives values from its neighbors (rank-1 and rank+1)





Neighbor Communication

Unsafe version ⊗ neicomm_unsafe() in neicomm sample

Send to rank-1 Send to rank+1 Recv from rank-1 Recv from rank-1



Safe version © neicomm_safe() in neicomm sample

Start to send to rank-1 Start to send to rank+1 Recv from rank-1 Recv from rank-1 Finish to send to rank-1 Finish to send to rank+1

 It requires a long story to see the reason of deadlock, so omitted here
 Hint: Not only MPI_Recv, but MPI_Send is "blocking" communication if message size is very large



Non-Blocking Communication



- Non-blocking communication: starts a communication (send or receive), but does not wait for its completion
 - MPI_Recv is blocking communication, since it waits for message arrival
- Program must wait for its completion later



Non-Blocking Receive



MPI_Irecv: starts receiving, but it returns Immediately MPI_Wait: wait for message arrival MPI_Request looks like a "ticket" for the communication

Behavior of MPI_Irecv

- MPI_Irecv itself immediately returns
- Program can use received data after MPI_Wait
- ※ MPI_Recv = MPI_Irecv + MPI_Wait





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Non-Blocking Send



MPI_Isend: starts sending, but it returns Immediately MPI_Wait must be used later ※ MPI_Send = MPI_Isend + MPI_Wait

MPI_Wait Family



- MPI_Wait(&req, &stat); ←wait for completion of one communication
- MPI_Waitall(n, reqs, stats); ←wait for completion of all n communications
- MPI_Waitany(n, reqs, &idx, &stat); ←wait for completion of one of n communications
- MPI_Test(&req, &flag, &stat); ←check completion of one communication
- MPI_Testall, MPI_Testany...

Assignments in MPI Part (Abstract)



Choose <u>one of</u> [M1]—[M3], and submit a report Due date: May 28 (Monday)

[M1] Parallelize "diffusion" sample program by MPI.[M2] Improve mm-mpi sample in order to reduce memory consumption.

[M3] (Freestyle) Parallelize *any* program by MPI.

For more detail, please see No. 7 slides or OCW-i.

Next Class

- MPI (3)
 - Improvement of "matrix multiply" sample
 - Group Communication

