Advanced Macroeconomics

(Department of Industrial Engineering and Economics, Spring 2Q, FY2016)

An Introduction to Dynamic Optimization

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Plan of Lectures in the Part of "Dynamic Optimization"

- June, 14 (Tue) (Today): An introduction to dynamic optimization
- June, 17 (Fri): Infinite-horizon dynamic programming in discrete time
- June, 21 (Tue): Continuous-time optimal control
- June, 24 (Fri): Dynamical system

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Introduction: A Cake-eating Problem

- Suppose that you are presented with a cake of size W > 0.
- In each period $t \ (=1,2,3,\ldots,T),$ you can eat some of the cake, and save the rest.
- Let
 - $c_t \ge 0$ be amount of your consumption in period t;
 - $u: \mathbb{R}_+ \to \mathbb{R}$ be your one-period utility function from c_t ;

•
$$\boldsymbol{c} = (c_1, c_2, \ldots, c_T) \in \mathbb{R}^T_+.$$

Your Preferences

• Your preferences are assumed to be given by the function $U : \mathbb{R}^T_+ \to \mathbb{R}$:

$$U(c) = u(c_1) + \beta u(c_2) + \ldots + \beta^{T-1} u(c_T)$$

= $\sum_{t=1}^{T} \beta^{t-1} u(c_t),$

where $\beta \in (0,1)$ is called the discount factor (割引因子).

• If one defines $\rho > 0$ such that $\beta \equiv \frac{1}{1+\rho}$, then ρ is called the discount rate (割引率).

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- Question: How do you decide your optimal plans of eating the cake?
- From the view point of microeconomic theory, the problem is formulated as the utility maximization problem as follows:

$$\max_{c} \sum_{t=1}^{T} \beta^{t-1} u(c_{t}),$$

s.t.
$$\sum_{t=1}^{T} c_{t} \leq W,$$

$$c_{t} \geq 0 \quad t = 1, 2, \dots, T.$$
 (P)

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(*) From the above constraints, $c_t \leq W$ automatically implies for all t.

- Thus, in this simple example, there is no
 - Trade in markets: you do not buy or sell the cake; or
 - Strategic interactions between you and other people: you do not need to share the cake with any others.
- Instead, this example focus on your own *intertemporal choice* of consumption. This gives the benchmark for the analysis of an individual's saving-consumption decision in macroeconomics.

• Let *D* denote the constraint set (制約集合):

$$\mathcal{D} = \left\{ \boldsymbol{c} \in \mathbb{R}_{+}^{T} \mid \sum_{t=1}^{T} c_{t} \leq W \right\}$$

 $\Rightarrow \mathcal{D} \text{ is compact.}$

Assumption

 $U: \mathbb{R}^T_+ \to \mathbb{R}$ is a continuous function on \mathcal{D} .

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The Weierstrass Theorem:
 U attains a maximum (and a minimum) on D.

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• Exercise 1.1: Suppose that $u(c_t) = c_t$ for all t = 1, 2, ..., T. Then, show that U is maximized at

$$c_1 = W, \quad c_2 = c_3 = \ldots = c_T = 0.$$

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Inequality-constrained Optimization

- The above problem (P) is the inequality-constrained optimization problem.
- · Hereafter, in addition to its continuity, we assume

Assumption

1 u'(c) > 0;

2 u''(c) < 0;

3 $\lim_{c\to 0} u'(c) = +\infty.$

The third property is called the Inada condition (稲田条件).

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Using the Theorem of Kuhn and Tucker: A "Cookbook" Procedure

• Construct the following Lagrangian:

$$L(\boldsymbol{c}, \lambda, \boldsymbol{\mu}) = U(\boldsymbol{c}) + \lambda \left(W - \sum_{t=1}^{T} c_t \right) + \sum_{t=1}^{T} \mu_t c_t,$$

where

- λ : The KT multiplier associated with the constraint: $\sum_{t=1}^{T} c_t \leq W$;
- μ_t : That associated with the constraint $c_t \ge 0$, and $\mu = (\mu_1, \mu_2, \dots, \mu_T)$.

Using the Theorem of Kuhn and Tucker: A "Cookbook" Procedure

• Then, derive the first order conditions (F.O.Cs):

$$\beta^{t-1}u'(c_t) + \mu_t = \lambda, \quad t = 1, 2, \dots, T,$$
(1)

$$\sum_{t=1}^{T} c_t \le W, \ \lambda \ge 0, \ \lambda \left(W - \sum_{t=1}^{T} c_t \right) = 0,$$
(2)

$$c_t \ge 0, \ \mu_t \ge 0, \mu_t c_t = 0.$$
 (3)

- (2) and (3) are called the complementary slackness condition (相補性条件).
- Thanks to the concavity of U and the fact that \mathcal{D} is a convex set, the above F.O.Cs provide necessary and sufficient conditions for the maximization problem.

Solution

- Let $c^* = (c_1^*, c_2^*, ...)$ denote the solution of the problem. Hereafter, we call this the optimal consumption plan (最適消費計画).
- Since u'(c) > 0,

$$\sum_{t=1}^{T} c_t^* = W. \tag{4}$$

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• In addition, thanks to the Inada condition $\lim_{c \to 0} u'(c) = +\infty$, it follows that

$$c_t^* > 0 \forall t.$$

Solution

- Since $c_t^* > 0$, $\mu_t = 0$ holds from (3).
- Then, substituting $\mu_t = 0$ into (1), we have

$$\beta^{t-1}u'(c_t^*) = \lambda, \quad t = 1, 2, \dots, T.$$

 $\Rightarrow c_t$ is obtained as $c_t^* = (u')^{-1} (\lambda/\beta^{t-1})$, where $(u')^{-1}$ is the inverse function of u.

 \Rightarrow Substituting this result into (4),

$$\sum_{t=1}^{T} \beta^{t-1} \underbrace{(u')^{-1} (\lambda/\beta^{t-1})}_{c_t^*} = W.$$

Thus, by specifying the functional form of u, we can solve the above equation for λ , which in turn determines the value of c_t^* .

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Reformulation of the Problem: Optimal Control

- Consider the same problem, but now consider a "dynamic feature" of the problem explicitly.
- Let w_t denote the size of the leftover cake, which remains to be available for you in period t. The following two conditions are satisfied.

$$w_1 = W,$$

$$w_t \le W \quad t = 2, 3, \dots, T+1.$$

• The value of w_t changes over time, according to the following law of motion:

$$w_{t+1} = w_t - c_t. (5)$$

(5) is called the transition equation (推移方程式).

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Reformulation of the Problem: Optimal Control

• Then, the cake-eating problem can be formulated also as the following optimal control problem (最適制御問題) in discrete time:

$$\begin{aligned} \max \quad U(\boldsymbol{c}) &= \sum_{t=1}^{T} \beta^{t-1} u(c_t) \\ \text{s.t.} \quad w_{t+1} &= w_t - c_t, \quad t = 1, 2, \dots, T \\ w_{T+1} &\geq 0 \quad (\text{terminal condition}), \\ w_1 &= W \quad (\text{initial condition}). \end{aligned}$$

(*) The inequality constraint, $c_t \ge 0$, is now omitted because we have already known that it never binds owing to the Inada condition.

• w_{T+1} is amount of a leftover piece of cake in period T. Thus, notice that

$$\sum_{t=1}^{T} c_t = W \Leftrightarrow w_{T+1} = 0.$$

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Euler Equation and Transversality Condition

- Once reset the meanings of notations, λ and μ , defined above.
- Construct the following Lagrangian :

$$L = \sum_{t=1}^{T} \beta^{t-1} u(c_t) + \sum_{t=1}^{T} \tilde{\lambda}_t (w_t - c_t - w_{t+1}) + \mu w_{T+1}$$
$$= \sum_{t=1}^{T} \beta^{t-1} [u(c_t) + \lambda_t (w_t - c_t - w_{t+1})] + \mu w_{T+1}$$

where

- $\lambda_t (= \beta^{-(t-1)} \tilde{\lambda}_t)$: The multiplier associated with the transition equation;
- μ : The KT multiplier associated with the constraint $w_{t+1} \ge 0$.

(*) λ_t is called the costate variable (共役変数) in the context of control.

Euler Equation and Transversality Condition

• The F.O.Cs are given by

$$u'(c_t) = \lambda_t,\tag{6}$$

$$\lambda_t = \beta \lambda_{t+1},\tag{7}$$

$$\lambda_T = \mu,, \qquad (8)$$

$$w_{T+1} \ge 0, \ \lambda_T \ge 0, \ \beta^{T-1} \lambda_T w_{T+1} = 0.$$
 (9)

• From (6) and (7), we can have the following expression:

$$u'(c_t) = \beta u'(c_{t+1}).$$
 (10)

(10) is called the Euler equation.

• On the other hand, from (6), (8) and (9), the third condition of (11) is rewritten as

$$\beta^{T-1}u'(c_T)w_{T+1} = 0.$$
(11)

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This is called the transversality condition.

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• In sum, the optimal consumption plan $c^* = (c_1^*, c_2^*, \dots c_T^*)$ and $w^* \equiv (w_1^*, w_2^*, \dots, w_{T+1}^*)$ are given by the following 2T+1 equations:

(i) Transition equation:
$$w_{t+1}^* = w_t^* - c_t^*$$
 $t = 1, 2, ..., T$,
(ii) Euler equation: $u'(c_t^*) = \beta u'(c_{t+1}^*)$ $t = 1, 2, ..., T - 1$,
(iii) Transversality condition: $\beta^{T-1}u'(c_T^*)w_{T+1}^* = 0$,
 $\Rightarrow w_{T+1}^* = 0$ in this case,
(iv) Initial condition: $w_1^* = W$.

Of course, the obtained consumption plan must be the same as that obtained under the original formulation (on pp. 13).

- So, what is advantage of this formulation?
 - **1** We can use this method even when the transition equation is non-linear.
 - 2 We can utilize the "recursive feature" of the problem.

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Recursive Feature of the Problem

- So far, we formulate the cake-eating problem in two different ways.
- Note that, in either case, you solved the problem in the initial period.
- Suppose that you stop and reconsider the problem in period, say, t_0 . Your problem from then on is

$$\max \sum_{t=t_0}^{T} \beta^{t-t_0} u(c_t)$$

s.t. $w_{t+1} = w_t - c_t,$
 $w_{T+1} \ge 0,$
 w_{t_0} given.

You will solve essentially the same problem as you did in the initial period!

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Recursive Feature of the Problem

• The dynamic programming technique, based on the Bellman's principle of optimality, utilizes such a property that the problem is recursively defined.

Let

$$V(w_1) = \max_{c} \left\{ \sum_{t=1}^{T} \beta^{t-1} u(c_t) \mid w_{t+1} = w_t - c_t, t = 1, 2, \dots T \right\},\$$

where $V : \mathbb{R}_+ \to \mathbb{R}$ is called the value function (価値関数). In the context of economics, V is called the indirect utility function.

Bellman Equation

· Briefly speaking, the principle of optimality means

$$V(w_1) = \max_{c} \left\{ \sum_{t=1}^{T} \beta^{t-1} u(c_t) \mid w_{t+1} = w_t - c_t, t = 1, 2, \dots T \right\}$$
$$= \max_{c_1} \left\{ u(c_1) + \beta V(w_2) \mid w_2 = w_1 - c_1 \right\}.$$
(12)

(12) is called the Bellman equation (ベルマン方程式).

• The dynamic programming technique, now widely used in macroeconomics, solves the maximization problem by converting the original problem into a two-period problem characterized in the Bellman equation.

(*) Note that the value function in (12) is *still to be determined*. Thus, the Bellman equation is a functional equation.

Next Week

· Infinite-horizon dynamic programming with more general functional forms