## Geometric group theory Summary of Lecture 14

We aim to prove the quasi-isometry invariance of hyperbolicity.

Theorem 6.19 : Suppose that $X$ and $X^{\prime}$ are geodesic spaces with $X \sim X^{\prime}$, then $X$ is hyperbolic if and only if $X^{\prime}$ is.

Proof : Let $\phi:(X, d) \longrightarrow\left(X^{\prime}, d^{\prime}\right)$ be a quasi-isometry and suppose that $X^{\prime}$ is $k$ hyperbolic.
Let $(\alpha, \beta, \gamma)$ be a geodesic triangle in $X$.
Let $\bar{\alpha}, \bar{\beta}, \bar{\gamma}$ be the quasigeodesics a bounded distance from $\phi(\alpha), \phi(\beta), \phi(\gamma)$ as constructed above.

By Lemma $6.18,(\bar{\alpha}, \bar{\beta}, \bar{\gamma})$ has a $t$-centre, $q$, where $t$ depends only on $k$ and the quasigeodesics constants.
Since $\phi(X)$ is cobounded, there is some $p \in X$ with $\phi(p)$ a bounded distance from $q$.
Now $\phi(p)$ is a bounded distance from each of $\phi(\alpha), \phi(\beta)$ and $\phi(\gamma)$.
It now follows that $p$ is a bounded distance from each of $\alpha, \beta, \gamma$.
In other words $p$ is a centre for the triangle $(\alpha, \beta, \gamma)$.

In fact, we see that the hyperbolicity constant of $X$ depends only on that of $X^{\prime}$ and the quasi-isometry constants.
(In the construction of $\bar{\alpha}, \bar{\beta}, \bar{\gamma}$ it is natural to take $h=k$.
In this way, we get linear bounds between the hyperbolicity contants.)
Some immediate consequences of Theorem 6.19:
(1) If $m, n \geq 2$, then $\mathbf{R}^{m} \nsim \mathbf{H}^{n}$.
(2) If $n \geq 2$, then $\mathbf{R}^{n}$ is not quasi-isometric to any tree.

In particular, we get another proof that $\mathbf{R}^{2} \nsucc \mathbf{R}$ and that $\mathbf{R}^{2} \nsim[0, \infty)$.

### 6.10. Hyperbolic groups.

Definition : A group $\Gamma$ is hyperbolic if it is finitely generated and its Cayley graph $\Delta(\Gamma)$ is hyperbolic.

By Theorem 3.3 and Theorem 6.19 this is well defined - it doesn't matter which finite generating set we take to construct the Cayley graph.

Lemma 6.20 : Suppose that $\Gamma$ acts properly discontinously cocompactly on a proper hyperbolic (geodesic) space, then $\Gamma$ is hyperbolic.

Proof : By Theorem 3.5, Theorem 3.6 and Theorem 6.19.

## Examples:

(1) Any finite group.
(2) Any virtually free group.
(3) The fundamental group of any compact hyperbolic manifold.

Note that if $\Gamma=\pi_{1}(M)$, where $M$ is compact hyperbolic, then $\Gamma$ acts properly discontinously cocompactly on $\mathbf{H}^{n}$.
(4) In particular, if $\Sigma$ is any compact (orientable) surface of genus at least 2 , then $\pi_{1}(\Sigma)$ is hyperbolic.

## Non-examples:

(1) $\mathbf{Z}^{n}$ for any $n \geq 2$.
(2) It turns out that a hyperbolic group cannot contain any $\mathbf{Z}^{2}$ subgroup, so this fact provides many more non-examples.
For example, many matrix groups $S L(n, \mathbf{Z})$ etc., knot groups (fundamental groups of knot complements), mapping class groups, braid groups etc. This is not the only obstruction, however.

### 6.11. The word problem.

We show that the word problem for a hyperbolic group is soluble.
Some notes for this can be found at:
http://www.warwick.ac.uk/~masgak/tit/ggtcourse.html

