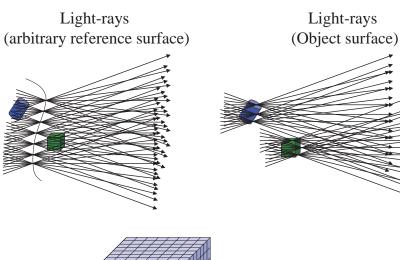


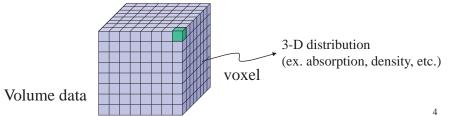
6. 三次元画像とホログラフィー

6. Three-dimensional imaging and holography

6.1 Variations of 3-D information

Туре	Parameters	Amount of data
2D image	x, y, value	$N^2 \times L_b$
Depth map	x, y, depth	$N^2 \times L_d$
Shape data	x, y, z	$3P \times X$
Surface data	x, y, z, reflectivity	$3P \times L_b \times X$
	x, y, z, color	
Slice stack	x, y, value, number	$N^2 \times L_b \times D$
Stereography	x, y, value, angle	$N^2 \times L_b \times M$
Volume data	x, y, z, value	$N^3 \times L_b$
Light-field	x, y, value, angle _x , angle _y	$N^2 \times L_b \times M^2$
Time-sequence	x, y, value, t	$N^2 \times L_b \times T_2$

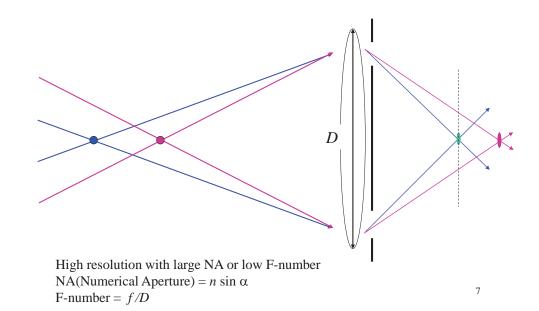




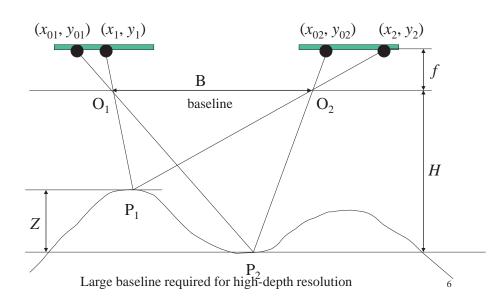
6.2 3D measurement techniques

Туре	Principle	Technology	Example(s)
Passive	Monocular	Texture, shade	
	Disparity	Lens focus	Stereo matching
	Trigonometric	Stereo	focusing
		Motion parallax	
	Projection	Projection	Computed tomography
			Confocal microscopy
Active	Disparity	Active stereo,	Laser projection
	Trigonometric	Structured light	slit, coded pattern,
		illumination	Fringe
		Moire	
	Photometric	Photometric stereo	Depth from shading
	Optical path	Interference	Heterodyne
	measurement		Optical Coherence Tomography
			Phase difference
			Time of flight 5

Light-rays captured by a lens



Principle of trigonometry



6.3 3D display techniques

	Principle	Method	Depth-cues (Only important cues shown)
No parallax Single 2D image	Monocular depth-cue	Pictorial techniques	Overlapping, Linear Perspective Texture Gradient, Shades and Shadows, Aerial Perspective
		Large field of view Floating real-image	Display surface becomes unstable
No parallax Multiple 2D images		Motion picture Observer Tracking	Motion Parallax
Binocular stereogram Two 2-D images	Binocular parallax	Polarizing glasses, Anaglyph, Time-sequential, Goggle, Lenticular stereogram (binocular)	Binocular Parallax
Autostereoscopic 3D display (3D images)	Multi-view	Parallax panoramagram Lenticular sheet IP, Integral imaging	Binocular Parallax, Motion Parallax
	Depth sampling	Varifocal mirror LCD Stack	Binocular Parallax, Motion Parallax Accommodation, Convergence Difficult to reproduce overlapping effect
	light-ray or wavefront reconstruction	IP, Parallax barrier, High-density light-ray reproduction Holography	Binocular Parallax, Motion Parallax Accommodation, Convergence