Remark 5.10 This is much better than the result of Theorem 5.6, since it does not depend on n.

Finally, consider the following problem under Assumption 5.11.

$$egin{aligned} \min \limits_{oldsymbol{x} \in \mathbb{R}^n} f(oldsymbol{x}) \end{aligned}$$

Assumption 5.11

- 1. $f \in \mathcal{C}^{2,2}_M(\mathbb{R}^n)$;
- 2. There is a local minimum x^* of the function f(x);
- 3. We know some bound $0 < \ell \le L < \infty$ for the Hessian at x^* :

$$\ell \boldsymbol{I} \prec f''(\boldsymbol{x}^*) \prec L \boldsymbol{I};$$

4. Our starting point x_0 is close enough to x^* .

Theorem 5.12 Let f(x) satisfy our assumptions above and let the starting point x_0 be close enough to a local minimum:

$$r_0 = \|m{x}_0 - m{x}^*\|_2 < ar{r} := rac{2\ell}{M}.$$

Then, the steepest descent method with step-size $h^* = 2/(L + \ell)$ converges as follows:

$$\|\boldsymbol{x}_k - \boldsymbol{x}^*\|_2 \le \frac{\bar{r}r_0}{\bar{r} - r_0} \left(1 - \frac{2\ell}{L + 3\ell}\right)^k.$$

This rate of convergence is called (R-)linear.

Proof:

In the steepest descent method, the iterates are $\mathbf{x}_{k+1} = \mathbf{x}_k - h_k f'(\mathbf{x}_k)$. Since $f'(\mathbf{x}^*) = 0$,

$$f'(\boldsymbol{x}_k) = f'(\boldsymbol{x}_k) - f'(\boldsymbol{x}^*) = \int_0^1 f''(\boldsymbol{x}^* + \tau(\boldsymbol{x}_k - \boldsymbol{x}^*))(\boldsymbol{x}_k - \boldsymbol{x}^*)d\tau = \boldsymbol{G}_k(\boldsymbol{x}_k - \boldsymbol{x}^*),$$

and therefore,

$$x_{k+1} - x^* = x_k - x^* - h_k G_k(x_k - x^*) = (I - h_k G_k)(x_k - x^*).$$

Let $r_k = \|\boldsymbol{x}_k - \boldsymbol{x}^*\|_2$. From Lemma 3.6,

$$f''(x^*) - \tau M r_k I \leq f''(x^* + \tau (x_k - x^*)) \leq f''(x^*) + \tau M r_k I.$$

Integrating all parts from 0 to 1 and using our hypothesis.

$$(\ell - \frac{r_k}{2}M)\mathbf{I} \leq \mathbf{G}_k \leq (L + \frac{r_k}{2}M)\mathbf{I}.$$

Therefore,

$$\left(1 - h_k(L + \frac{r_k}{2}M)\right) \mathbf{I} \leq \mathbf{I} - h_k \mathbf{G}_k \leq \left(1 - h_k(\ell - \frac{r_k}{2}M)\right) \mathbf{I}.$$

We arrive at

$$\|I - h_k G_k\|_2 \le \max\{|a_k(h_k)|, |b_k(h_k)|\}$$

where
$$a_k(h) = 1 - h(\ell - \frac{r_k}{2}M)$$
 and $b_k(h) = h(L + \frac{r_k}{2}M) - 1$.

Notice that $a_k(0) = 1$ and $b_k(0) = -1$.

Now, let us use our hypothesis that $r_0 < \bar{r}$.

When $a_k(h) = b_k(h)$, we have $1 - h(\ell - \frac{r_k}{2}M) = h(L + \frac{r_k}{2}M) - 1$, and therefore

$$h_k^* = \frac{2}{L+\ell}.$$

(Surprisingly, it does not depend neither on M nor r_k). Finally,

$$r_{k+1} = \|m{x}_{k+1} - m{x}^*\|_2 \le \left(1 - rac{2}{L+\ell} \left(\ell - rac{r_k}{2} M
ight)
ight) \|m{x}_k - m{x}^*\|_2.$$

That is,

$$r_{k+1} \le \left(\frac{L-\ell}{L+\ell} + \frac{r_k M}{L+\ell}\right) r_k.$$

and $r_{k+1} < r_k < \bar{r}$.

Now, let us analyze the rate of convergence. Multiplying the above inequality by $M/(L+\ell)$,

$$\frac{Mr_{k+1}}{L+\ell} \le \frac{M(L-\ell)}{(L+\ell)^2} r_k + \frac{M^2 r_k^2}{(L+\ell)^2}.$$

Calling $\alpha_k = \frac{Mr_k}{L+\ell}$ and $q = \frac{2\ell}{L+\ell}$, we have

$$\alpha_{k+1} \le (1-q)\alpha_k + \alpha_k^2 = \alpha_k(1 + \alpha_k - q) = \frac{\alpha_k(1 - (\alpha_k - q)^2)}{1 - (\alpha_k - q)}.$$
 (7)

Now, since $r_k < \frac{2\ell}{M}$, $\alpha_k - q = \frac{Mr_k}{L+\ell} - \frac{2\ell}{L+\ell} < 0$, and $1 + (\alpha_k - q) = \frac{L-\ell}{L+\ell} + \frac{Mr_k}{L+\ell} > 0$. Therefore, $-1 < \alpha_k - q < 0$, and (7) becomes $\leq \frac{\alpha_k}{1+q-\alpha_k}$.

$$\frac{1}{\alpha_{k+1}} \ge \frac{1+q}{\alpha_k} - 1.$$

$$\frac{q}{\alpha_{k+1}} - 1 \ge \frac{q(1+q)}{\alpha_k} - q - 1 = (1+q)\left(\frac{q}{\alpha_k} - 1\right).$$

and then,

$$\frac{q}{\alpha_k} - 1 \ge (1+q)^k \left(\frac{q}{\alpha_0} - 1\right) = (1+q)^k \left(\frac{2\ell}{L+\ell} \frac{L+\ell}{Mr_0} - 1\right) = (1+q)^k \left(\frac{\bar{r}}{r_0} - 1\right).$$

Finally, we arrive at

$$r_k = \|\boldsymbol{x}_k - \boldsymbol{x}^*\|_2 \le \frac{\bar{r}r_0}{\bar{r} - r_0} \left(1 - \frac{2\ell}{L + 3\ell}\right)^k.$$

5.4 The Newton Method

Example 5.13 Let us apply the Newton method to find the root of the following function

$$\phi(t) = \frac{t}{\sqrt{1+t^2}}.$$

Clearly $t^* = 0$.

The Newton method will give:

$$t_{k+1} = t_k - \frac{\phi(t_k)}{\phi'(t_k)} = t_k - t_k(1 + t_k^2) = -t_k^3.$$

Therefore, the method converges if $|t_0| < 1$, it oscillates if $|t_0| = 1$, and finally, diverges if $|t_0| > 1$.

Assumption 5.14

- 1. $f \in \mathcal{C}^{2,2}_M(\mathbb{R}^n);$
- 2. There is a local minimum x^* of the function f(x);
- 3. The Hessian is positive definite at x^* :

$$f''(\boldsymbol{x}^*) \succeq \ell \boldsymbol{I}, \quad \ell > 0;$$

4. Our starting point x_0 is close enough to x^* .

Theorem 5.15 Let the function f(x) satisfy the above assumptions. Suppose that the initial starting point x_0 is close enough to x^* :

$$\|\boldsymbol{x}_0 - \boldsymbol{x}^*\|_2 < \bar{r} := \frac{2\ell}{3M}.$$

Then $||x_k - x^*||_2 < \bar{r}$ for all k of the Newton method and it converges quadratically:

$$\|\boldsymbol{x}_{k+1} - \boldsymbol{x}^*\|_2 \le \frac{M\|\boldsymbol{x}_k - \boldsymbol{x}^*\|_2^2}{2(\ell - M\|\boldsymbol{x}_k - \boldsymbol{x}^*\|_2)}.$$

Proof:

Let $r_k = \|\boldsymbol{x}_k - \boldsymbol{x}^*\|_2$. From Lemma 3.6 and the assumption, we have for k = 0,

$$f''(\boldsymbol{x}_0) \succeq f''(\boldsymbol{x}^*) - Mr_0 \boldsymbol{I} \succeq (\ell - Mr_0) \boldsymbol{I}. \tag{8}$$

Since $r_0 < \bar{r} = \frac{2\ell}{3M} < \frac{\ell}{M}$, we have $\ell - Mr_0 > 0$ and therefore, $f''(\boldsymbol{x}_0)$ is invertible. Consider the Newton method for k = 0, $\boldsymbol{x}_1 = \boldsymbol{x}_0 - [f''(\boldsymbol{x}_0)]^{-1}f'(\boldsymbol{x}_0)$.

$$\begin{aligned}
x_1 - x^* &= x_0 - x^* - [f''(x_0)]^{-1} f'(x_0) \\
&= x_0 - x^* - [f''(x_0)]^{-1} \int_0^1 f''(x^* + \tau(x_0 - x^*))(x_0 - x^*) d\tau \\
&= [f''(x_0)]^{-1} G_0(x_0 - x^*)
\end{aligned}$$

where $G_0 = \int_0^1 [f''(x_0) - f''(x^* + \tau(x_0 - x^*))] d\tau$. Then

$$\|\boldsymbol{G}_{0}\|_{2} = \left\| \int_{0}^{1} [f''(\boldsymbol{x}_{0}) - f''(\boldsymbol{x}^{*} + \tau(\boldsymbol{x}_{0} - \boldsymbol{x}^{*}))] d\tau \right\|_{2}$$

$$\leq \int_{0}^{1} \|f''(\boldsymbol{x}_{0}) - f''(\boldsymbol{x}^{*} + \tau(\boldsymbol{x}_{0} - \boldsymbol{x}^{*}))\|_{2} d\tau$$

$$\leq \int_{0}^{1} M|1 - \tau|r_{0} d\tau = \frac{r_{0}}{2} M.$$

From (8),

$$||[f''(\boldsymbol{x}_0)]^{-1}||_2 \le (\ell - Mr_0)^{-1}$$

Then

$$r_1 \le \frac{Mr_0^2}{2(\ell - Mr_0)}.$$

Since $r_0 < \bar{r} = \frac{2\ell}{3M}$, $\frac{Mr_0}{2(\ell - Mr_0)} < 1$, and $r_1 < r_0$. One can see now that the same argument is valid for all k's.