

## Optical imaging and image processing (IX)

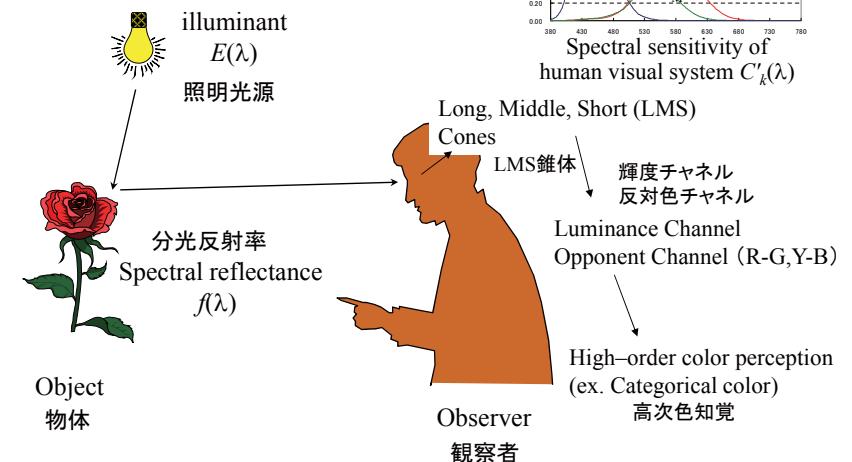
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<http://guchi.gsic.titech.ac.jp>

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### 5.1 Color spaces

#### 5.1 色空間

Color perception by human observer



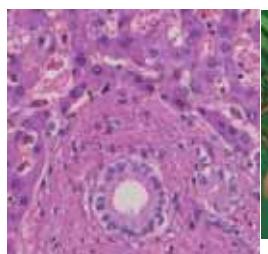
LMS Cone Sensitivity

<http://www.psychologie.uni-kiel.de/golz/publications/2003a/LMS.html>

V.C. Smith and J. Pokorny, "Spectral sensitivity of the foveal cone photopigments between 400 and 500 nm," Vis. Res. 15, 161-171 (1975).

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### 5. Color Imaging 5. カラー画像

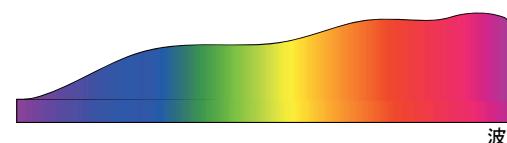


R, G, B  
Luminance(Y), Chromaticity(C)  
YCbCr, YPbPr, YUV, L\*a\*b\*  
Y, M, C, K  
Hue(H), Saturation(S), Value(V), L\*C\*h

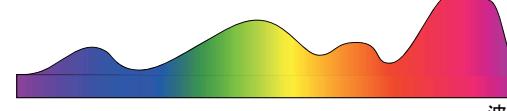
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### Color and the spectrum of light

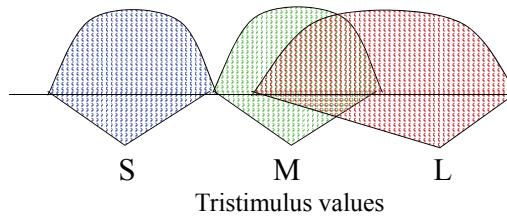
$$g_k = \int f(\lambda) E(\lambda) C'_k(\lambda) d\lambda$$



Spectral radiance of illumination light  
照明光源の分光放射輝度

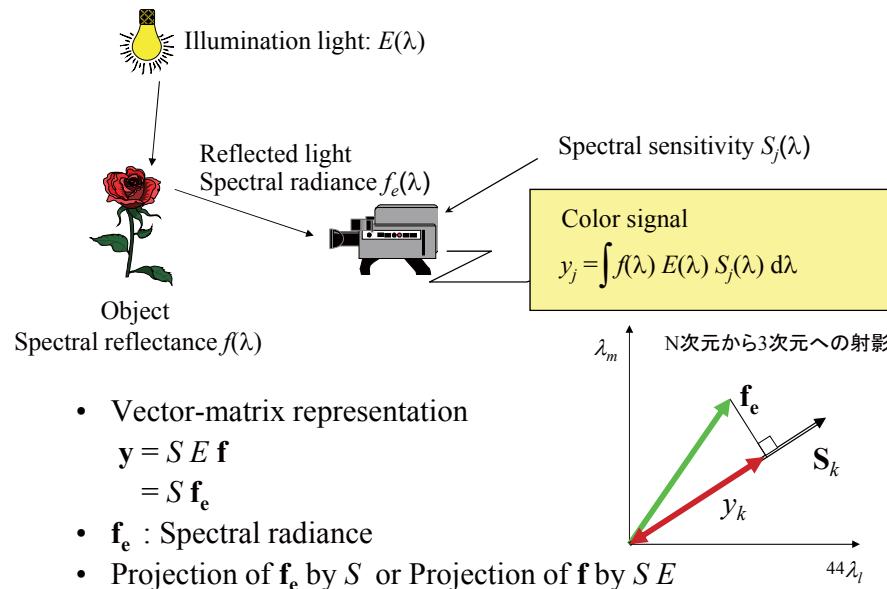


Spectral reflectance of the object  
物体の分光反射率

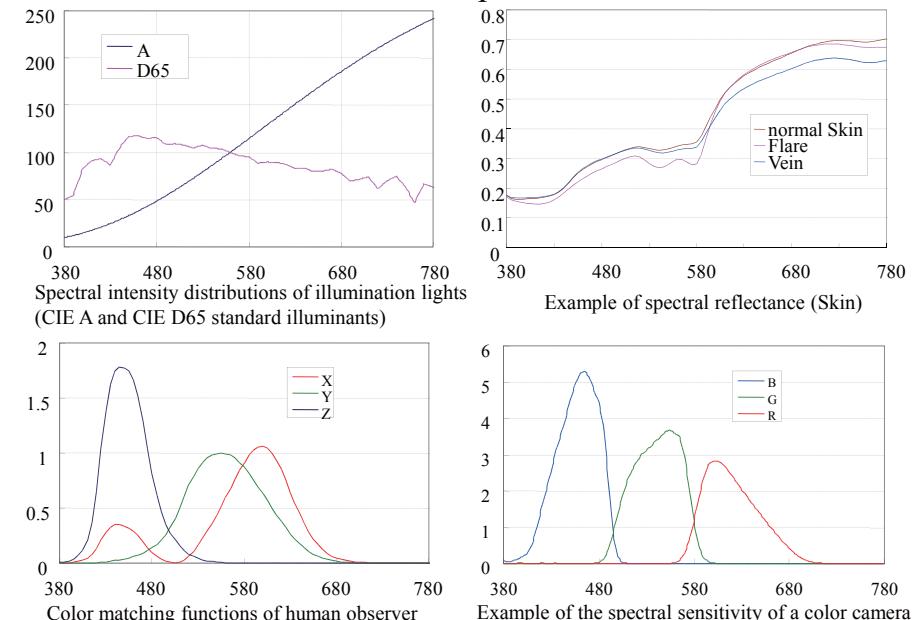


Spectral Sensitivity  
分光感度  
Output from the sensor  
センサーの出力＝三刺激値

## Color imaging system



## Examples



## Vector-matrix representation

Sampling of wavelengths

A graph shows a spectrum of light with various peaks and troughs. Below it, the text "Spectral reflectance =>  $\mathbf{f}$  ( $N$ -dimensional vector)" is followed by the equation  $y_j = \int f(\lambda) E(\lambda) S_j(\lambda) d\lambda$ .

$$\mathbf{f} = \begin{pmatrix} f(\lambda_1) \\ f(\lambda_2) \\ \vdots \\ f(\lambda_N) \end{pmatrix}$$

$$\begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} = \begin{pmatrix} S_1(\lambda_1) & S_1(\lambda_2) & \cdots & S_1(\lambda_N) \\ S_2(\lambda_1) & S_2(\lambda_2) & \cdots & S_2(\lambda_N) \\ S_3(\lambda_1) & S_3(\lambda_2) & \cdots & S_3(\lambda_N) \end{pmatrix}$$

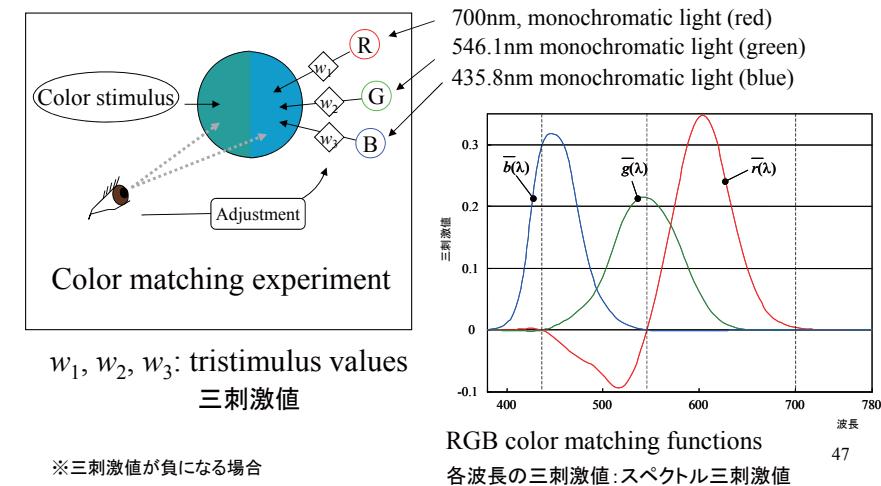
$$\begin{pmatrix} E(\lambda_1) & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & E(\lambda_N) \end{pmatrix} \begin{pmatrix} f(\lambda_1) \\ f(\lambda_2) \\ \vdots \\ f(\lambda_N) \end{pmatrix} \quad (5.3)$$

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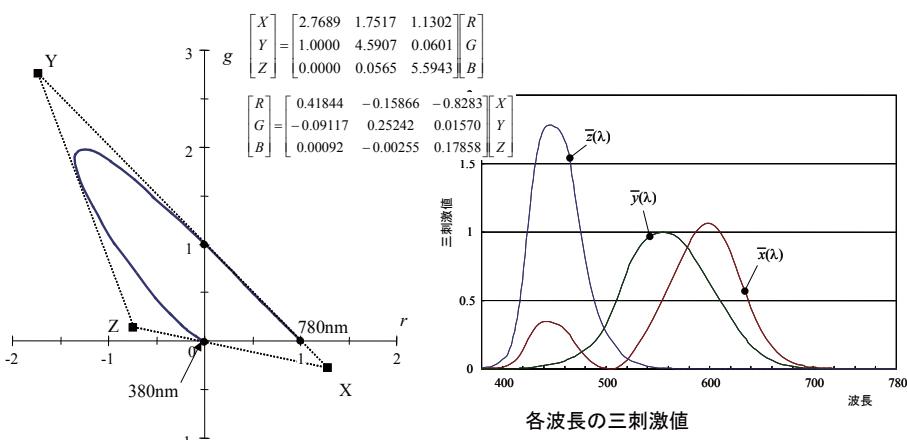
色空間はどのようにして定められたのか？

How were color spaces defined?

- Additive mixture of three-primary colors 3原色の加法混色

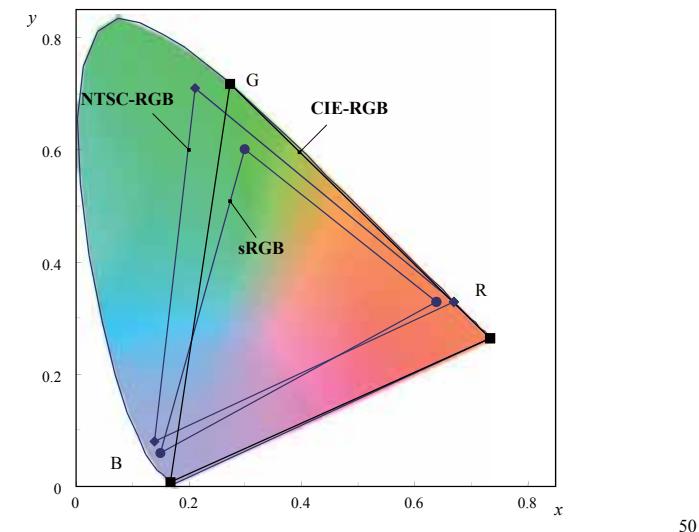


XYZ Color Matching Functions (CMF)  
Color is represented by three positive variables  
XYZ等色関数:3つの正の数で色を表す



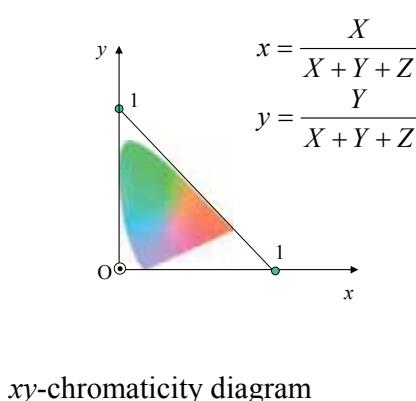
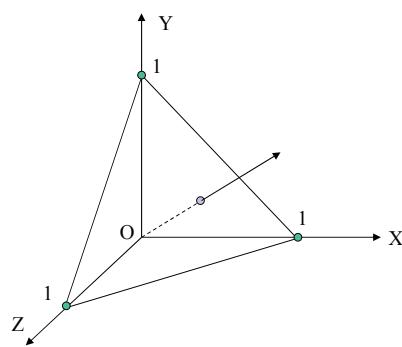
CIE 1931XYZ CMF (2 degrees)  
CIE 1964XYZ CMF (10degrees) 48

RGB three primary colors  
RGB 3原色



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XYZ color space, xy-chromaticity diagram  
XYZ色空間、xy-色度図



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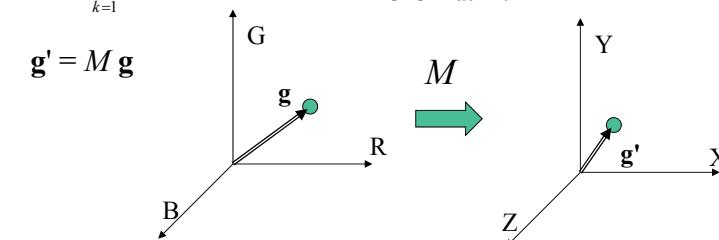
- Linear combination of a set of color matching functions yields another set of color matching functions

$$C'_j(\lambda) = \sum_{k=1}^3 a_{jk} C_k(\lambda)$$

ある等色関数のセットの線形結合により、別の3つの等色関数のセットを導出できる

$$\begin{aligned} g'_{\cdot j} &= \int f(\lambda) E(\lambda) C'_j(\lambda) d\lambda \\ &= \int f(\lambda) E(\lambda) \sum_{k=1}^3 a_{jk} C_k(\lambda) d\lambda \\ &= \sum_{k=1}^3 a_{jk} \int f(\lambda) E(\lambda) C_k(\lambda) d\lambda \\ &= \sum_{k=1}^3 a_{jk} g_k \end{aligned}$$

Color space can be converted using a 3x3 matrix.



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## CIE 1976 L\*a\*b\* Uniform Chromaticity Space (UCS) 均等色空間

$$L^* = \begin{cases} 116\left(\frac{Y}{Y_n}\right)^{1/3} - 16, & \frac{Y}{Y_n} > 0.008856 \\ 903.29\frac{Y}{Y_n}, & \frac{Y}{Y_n} \leq 0.008856 \end{cases} = \text{Lightness}$$

$$a^* = 500\{\phi\left(\frac{X}{X_n}\right) - \phi\left(\frac{Y}{Y_n}\right)\}$$

$$b^* = 200\{\phi\left(\frac{Y}{Y_n}\right) - \phi\left(\frac{Z}{Z_n}\right)\}$$

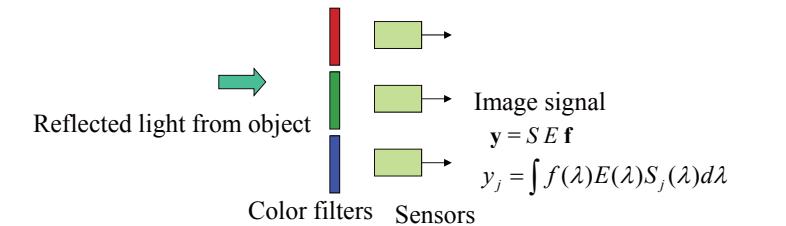
$$\text{where } \phi(a) = \begin{cases} a^{1/3} & \frac{Y}{Y_n} > 0.008856 \\ 7.78a + 16/116, & \frac{Y}{Y_n} \leq 0.008856 \end{cases}$$

CIELAB color difference  $\Delta E_{ab}^* = \sqrt{(\Delta L^*)^2 + (\Delta a^*)^2 + (\Delta b^*)^2}$

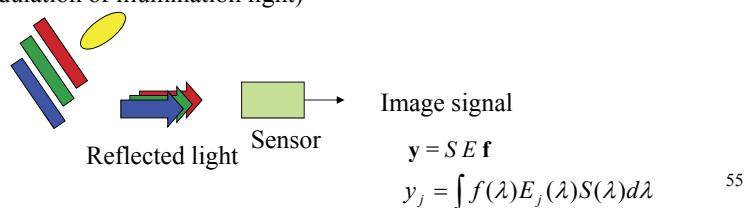
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## 5.2.1 Input of color images カラー画像の入力 Color image input devices

- Color camera, scanner, ..., endoscopy

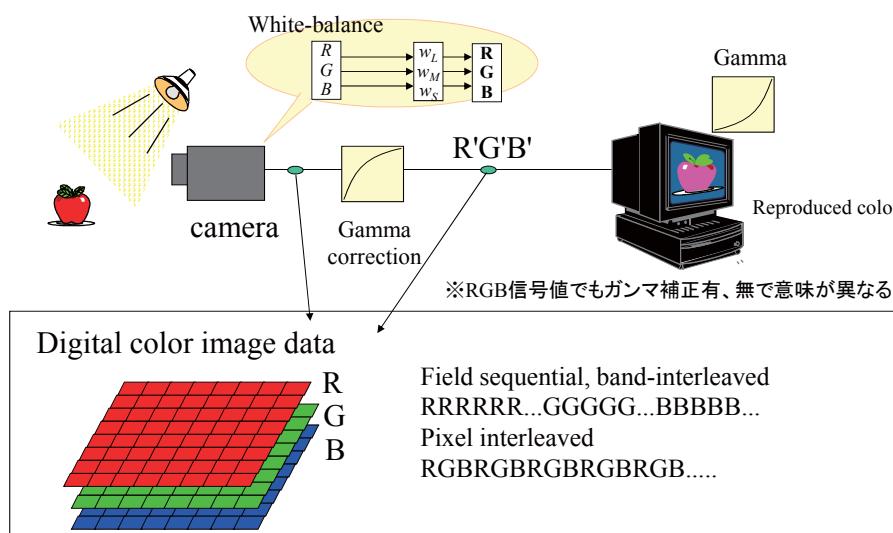


(Modulation of illumination light)



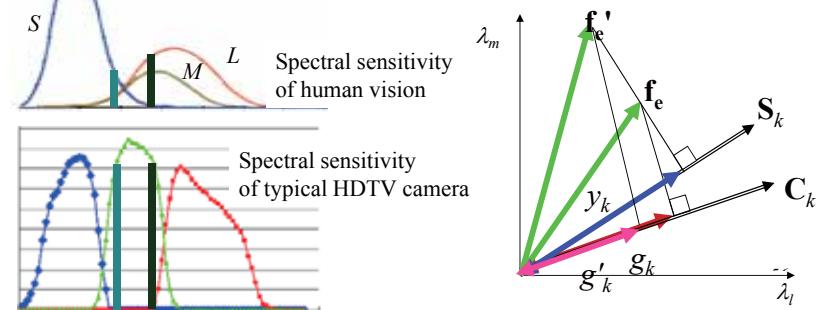
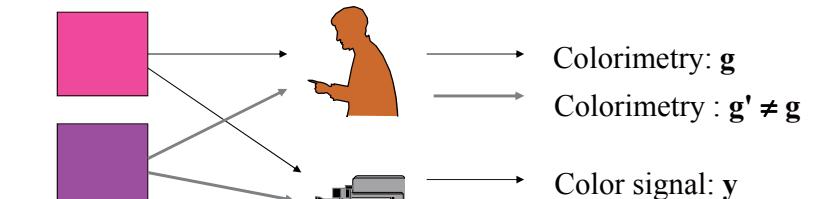
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## 5.2 Color imaging and display systems 5.2 カラーイメージングとディスプレイシステム



- Two color objects

Impossible to discriminate !

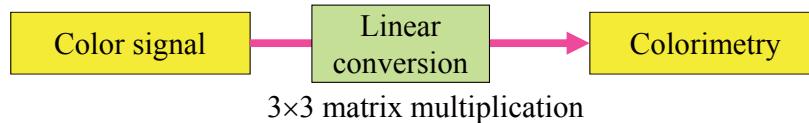


## Luther condition

- If the space spanned by  $S_k$  covers the space spanned by  $C_k$



$\mathbf{g}$  is derivable from  $\mathbf{y}$  for arbitrary  $\mathbf{f}_e$   
 $\mathbf{g} = M \mathbf{y}$



- Conversion matrix

$$\mathbf{y} = S E \mathbf{f}$$

$$\mathbf{g} = C E \mathbf{f}$$

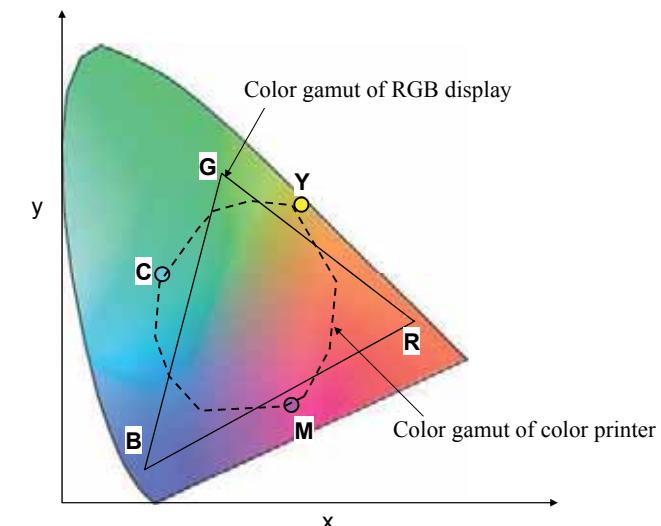
$$M = C S^t (S S^t)^{-1}$$

$$\begin{aligned} \mathbf{g}_e &= M \mathbf{y} \\ &= C S^t (S^t S)^{-1} S E \mathbf{f} = C E \mathbf{f} = \mathbf{g} \end{aligned}$$

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## Color gamut

色域



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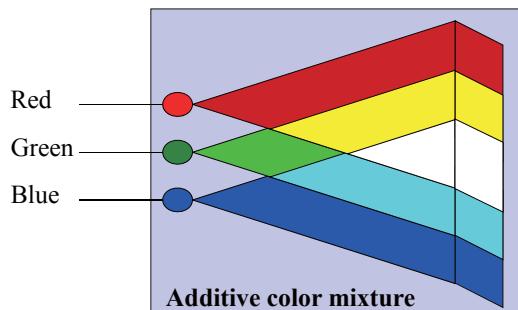
## 5.2.2 Color display

### カラーディスプレイ

- Spectral radiance of  $j$ -th primary color :  $P_j(\lambda)$
- Color signal for  $j$ -th primary color:  $\{ \mathbf{r} \}_j = r_j$
- Spectral radiance of reproduced color :  $Q(\lambda) = \sum_{j=R,G,B} r_j P_j(\lambda)$
- Reproduced color  $\mathbf{q}$

$$q_k = \int Q(\lambda) C_k(\lambda) d\lambda = \int_{j=R,G,B} r_j P_j(\lambda) C_k(\lambda) d\lambda = \sum_{j=R,G,B} \alpha_{jk} r_j \quad (5.13)$$

- $\mathbf{q} = \mathbf{A} \mathbf{r}$

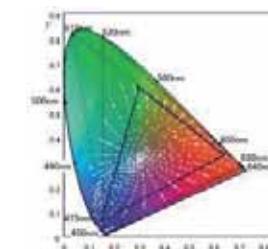


加法混色の原理

※ 3原色の加法混色で  
全ての色を表示できる  
訳ではない！

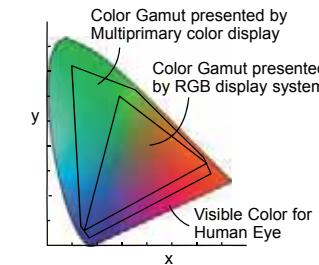
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- Wide gamut televisions



Ex.Laser display

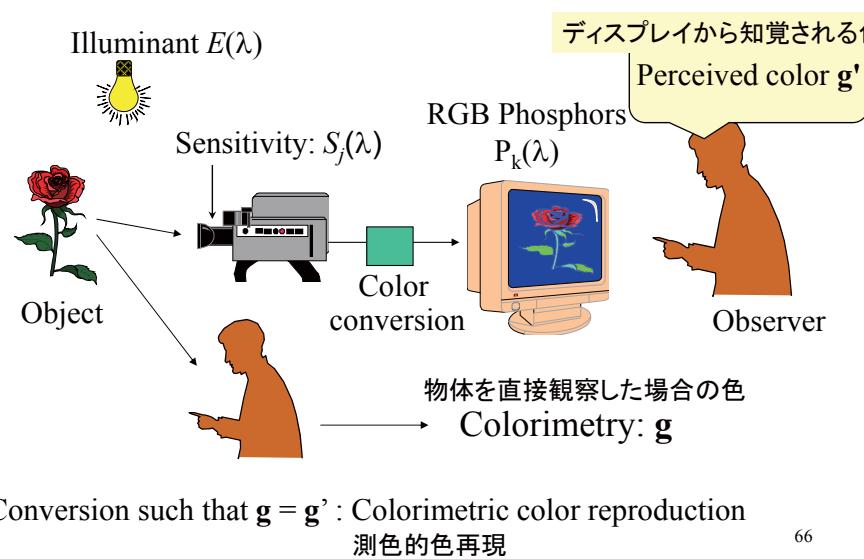
- Expanding Color Gamut: Multiprimary color display



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### 5.3 Color reproduction

#### 5.3 色再現



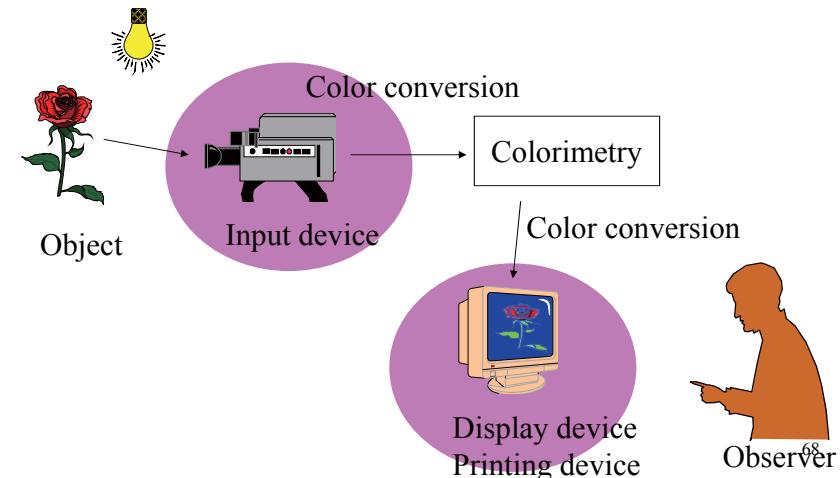
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### 5.3.2 Color management

#### カラー・マネージメント、色管理

- Device independent color reproduction

##### Device characterization



### 5.3.1 Objectives in color reproduction

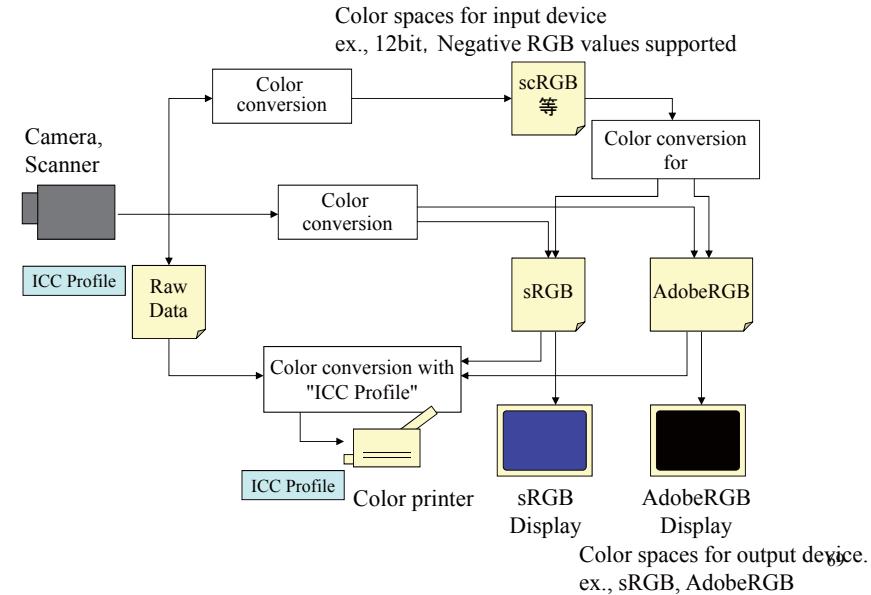
#### 色再現の分類 (R. W. G. Hunt)

- Spectral color reproduction 分光的色再現
- Exact color reproduction 正確な色再現
  - Tristimulus values are reproduced
- Colorimetric color reproduction 測色的色再現
  - Do not care luminance
- Equivalent color reproduction 等価な色再現
  - Tristimulus values do not agree with original, but matching the color appearance
  - Luminance should be similar to the original
- Corresponding color reproduction 対応する色再現
  - Tristimulus values do not agree with original, but matching the color appearance
- Preferred color reproduction 好ましい色再現

※消費者向け機器の開発では「好みの色再現」が重要とされてきた！

### Color spaces for input and output devices

#### 入力用の色空間、出力用の色空間



## Color spaces used in color images カラー画像に使われている各種の色空間

- NTSC RGB (1953)
- SMPTE 170M RGB (Current NTSC)              ※現在のNTSCはBT.709に近い
- ITU-R BT.709 RGB (HDTV)
- IEC 61966-2-1 (sRGB)
- IEC 61966-2-2 (scRGB)
- Adobe RGB
- sYCC (sRGB to YCC)
- ITU-R BT.709 Y Cb Cr
- xvYCC
- Others

Physical Standards: CIERGB, CIEXYZ, CIELAB

Perceptual: Munsell Color Space, Natural Color System

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## 5.4 Color image processing

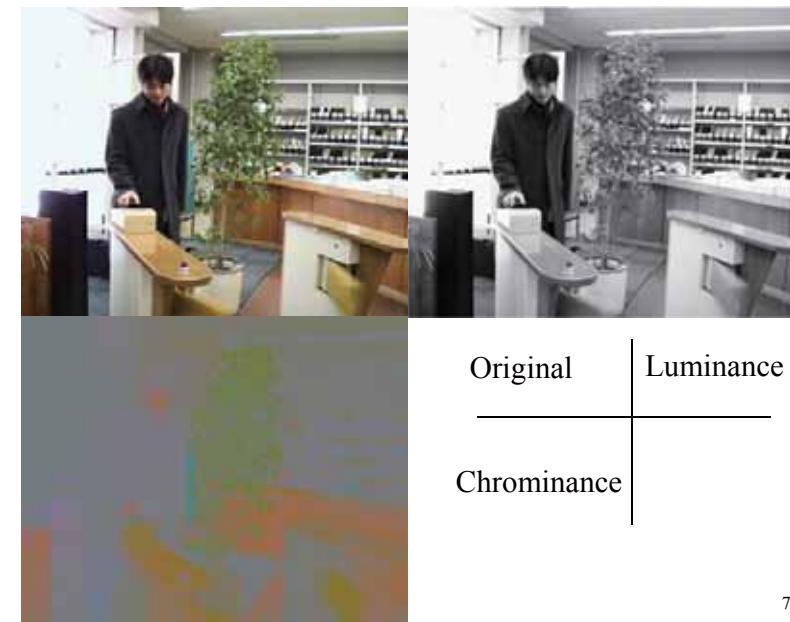
### 5.4 カラー画像処理

#### 5.4.1 Properties of color images      カラー画像の性質

- Monochromatic image, B/W image = 1-dimensional  
⇒ Color image = 3-dimensional
- larger bandwidth in the luminance signal, and smaller bandwidth in the chrominance signal
  - TV signal, Color image compression
- Resemblance in RGB primary component
  - The spectral reflectance of most objects are smooth
- The characteristics of human visual system (HVS)
  - HVS is not sensitive to the blur in the chrominance component
  - but is sensitive to the spatial color variation
  - It is difficult to memorize the color accurately

(The memorized color shifts)

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#### 5.4.2 Wiener filtering in color images (Color estimation) カラー画像におけるウイナーフィルタ(色推定)

Image signal  $\mathbf{y} = \mathbf{S E f} + \mathbf{n} = \mathbf{S f}_e + \mathbf{n}$

Color (tristimulus values)  $\mathbf{g} = \mathbf{C E f} = \mathbf{C f}_e$

Estimated Color  $\hat{\mathbf{g}} = \mathbf{M y}$

$$e = E\{\|\mathbf{g} - \hat{\mathbf{g}}\|^2\} = E\{\|\mathbf{g} - \mathbf{M y}\|^2\} \longrightarrow \min$$

$$e = E\{tr[(\mathbf{g} - \mathbf{M y})(\mathbf{g} - \mathbf{M y})^t]\}$$

$$\frac{\partial e}{\partial \mathbf{M}} = 0$$

$$\frac{\partial}{\partial \mathbf{M}}(\mathbf{g} - \mathbf{M y}) = \frac{\partial}{\partial \mathbf{M}}[\mathbf{C E f} - \mathbf{M}(\mathbf{S E f} + \mathbf{n})] = -(\mathbf{S E f} + \mathbf{n})$$

#### 5.4.3 Color image restoration カラー画像の復元

- Restoration of R, G, B channels independently
- Restoration of luminance component only
  - Human vision is less sensitive to the high-frequency component of chrominance.
- Image restoration considering inter-channel correlation
  - Chromatic aberration => Different blur in each channel =>  
It is effective to make use of the difference of the transfer functions in the R, G, B components.
- Color image captured by color filter array (demosaicing)
  - Color artifact sometimes appears at the edge of monochromatic object
  - Restoration using the inter-channel correlation

#### 5.4.4 Color image analysis カラー画像解析(例)

- Color image segmentation
- The distribution of pixels values in the color space (color signal space)
- Selection of color space
  - Considering the characteristics of human vision: UCS, HSV
  - Discounting the illumination nonuniformity: 2-D subspace perpendicular to the illumination color (white)
- Vector quantization

