

低雑音増幅回路

通信機器システムの要

雑音の評価

雑音の定式化

瞬時値での評価 困難(不可)



統計的な評価

$$2\text{乗平均値} : \overline{v_n^2} = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} v_n^2(t) dt$$

複数の雑音源の取り扱い

$$\begin{aligned}& \lim_{T \rightarrow \infty} \left[\frac{1}{T} \int_{-T/2}^{T/2} \{v_{n1}(t) + v_{n2}(t)\}^2 dt \right] \\&= \lim_{T \rightarrow \infty} \left[\frac{1}{T} \left\{ \int_{-T/2}^{T/2} v_{n1}^2(t) + 2v_{n1}(t)v_{n2}(t) + v_{n2}^2(t) dt \right\} \right] \\&= \overline{v_{n1}}^2 + \lim_{T \rightarrow \infty} \underline{\frac{2}{T} \int_{-T/2}^{T/2} v_{n1}(t)v_{n2}(t) dt} + \overline{v_{n2}}^2\end{aligned}$$

$v_{n1}(t)$ と $v_{n2}(t)$ が全く独立：無相関

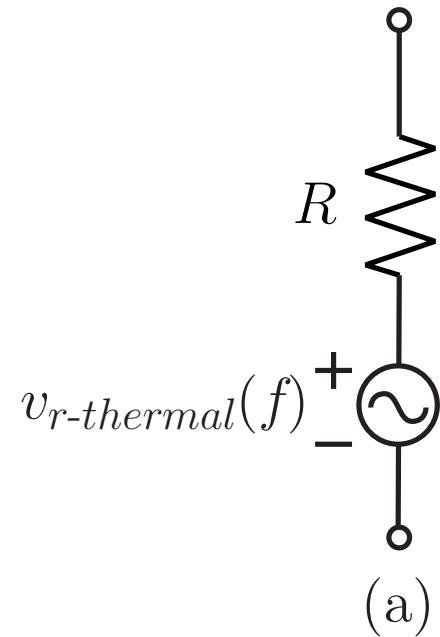
$$\int_0^\tau v_{n1}(t)v_{n2}(t) dt = 0$$

雑音源を考慮した回路素子モデル

熱雑音 , $1/f$ 雜音 , ショット雑音

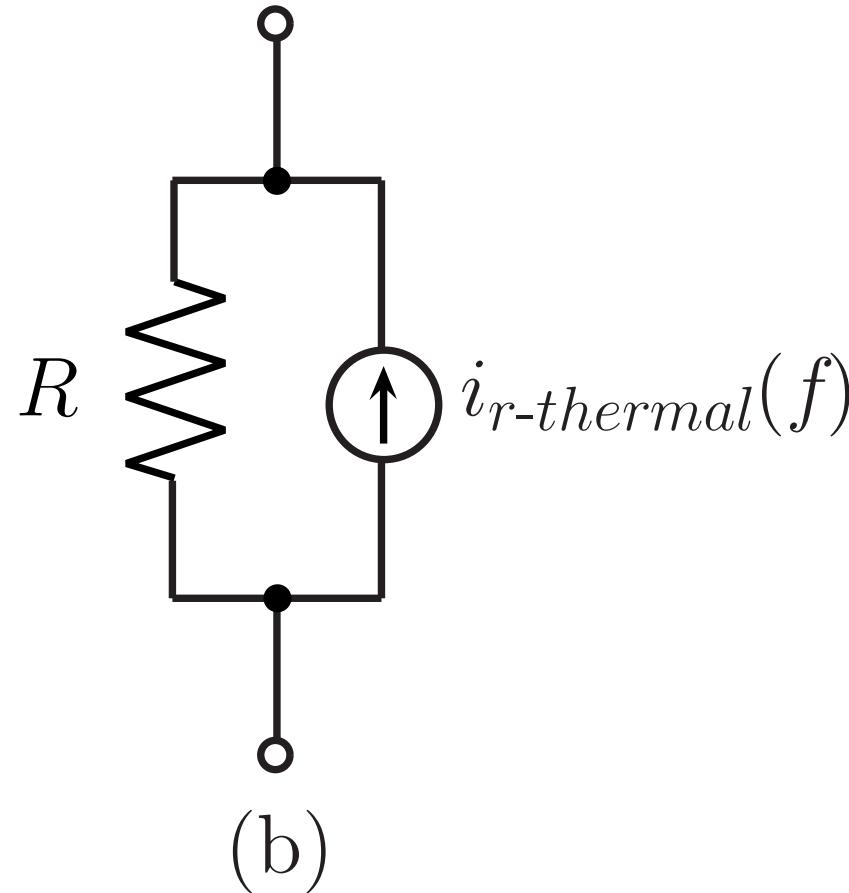
熱雑音 : キャリアが移動する際のランダムな動きによって
生じる雑音

抵抗の熱雑音



$$\overline{v_{r-thermal}^2(f)} = 4kTR[V^2/Hz]$$

電源の等価性($v_{r\text{-thermal}}=Ri_{r\text{-thermal}}$)から



$$\overline{i_{r\text{-thermal}}^2(f)} = 4kT \frac{1}{R} [\text{A}^2/\text{Hz}]$$

MOSトランジスタの熱雑音

キャリアがチャネルを通過する際に発生

$$\overline{v_{\text{mos-thermal}}}^2 = 4kT \gamma_n \frac{1}{g_m}$$

$$\overline{i_{\text{mos-thermal}}}^2 = 4kT \gamma_n g_m$$

$$\gamma_n \approx \frac{2}{3} \quad (\text{最小線幅が短くなると増加})$$

バイポーラトランジスタの熱雑音

ベース広がり抵抗 : $\overline{v_{b-thermal}(f)^2} = 4kT r_b$

エミッタ抵抗 , コレクタ・エミッタ間抵抗 : 仮想の抵抗



熱雑音の発生無し

スペクトラム強度が一定 : 白色雑音

1/f雑音：シリコンの汚れや結晶欠陥によりキャリアが
捕らわれたり、捕らわれたキャリアが離されたりを
繰り返すというランダムな過程によって生じる雑音

直流電流がないと発生しない

$$\overline{V_{mos-1/f}^2(f)} = \frac{\alpha_{1/f}}{C_{OX}WLf}$$

$$\overline{i_b-1/f^2(f)} = \frac{K_{1/f} I_B^a}{f}$$

ショット雑音：

電流 = キャリアによる電流パルスの和の平均値
電流の平均値からの揺らぎ

$$\overline{i_{b\text{-shot}}^2(f)} = 2qI_B$$

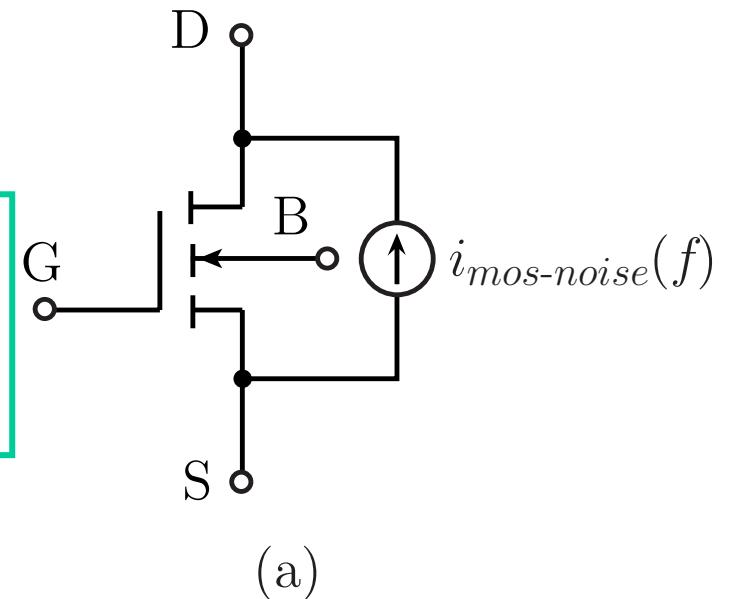
$$\overline{i_{c\text{-shot}}^2(f)} = 2qI_C$$

$$1\text{nA}@1\text{GHz} \rightarrow 1.6 \times 10^{-19} \text{C} \times 6.25\text{個}$$

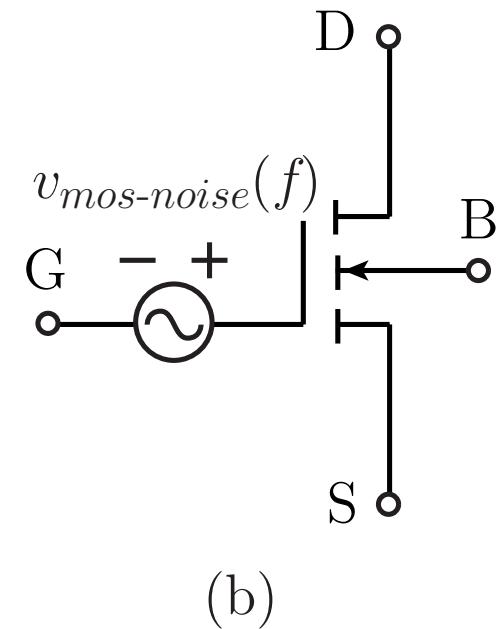
雑音源を含むトランジスタモデル

MOSトランジスタモデル

$$\overline{i_{mos-noise}^2(f)} = 4kT\gamma_n g_m + \frac{\alpha_1/f g_m^2}{C_{OX}WLf}$$



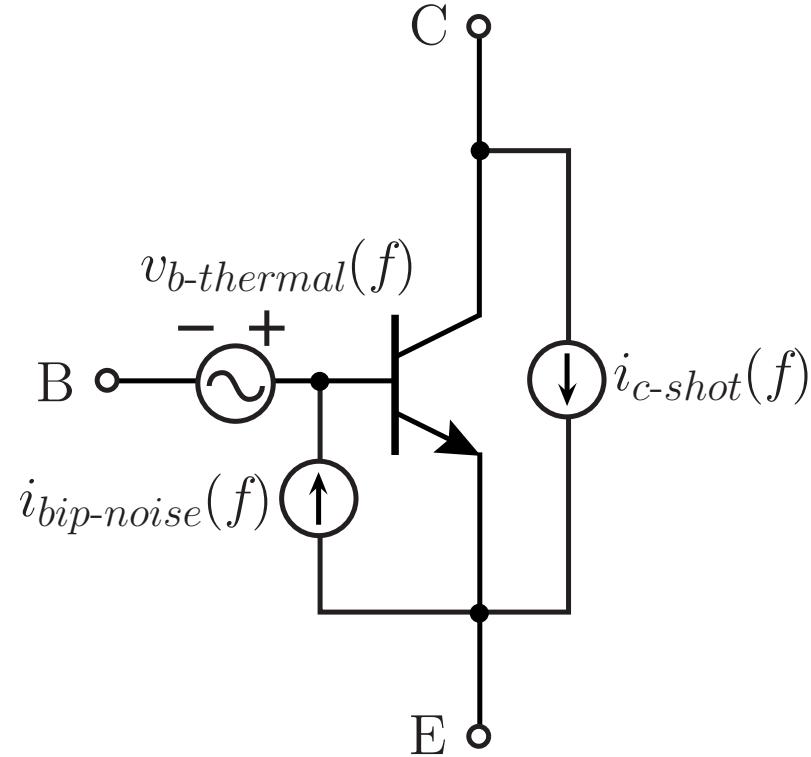
(a)



(b)

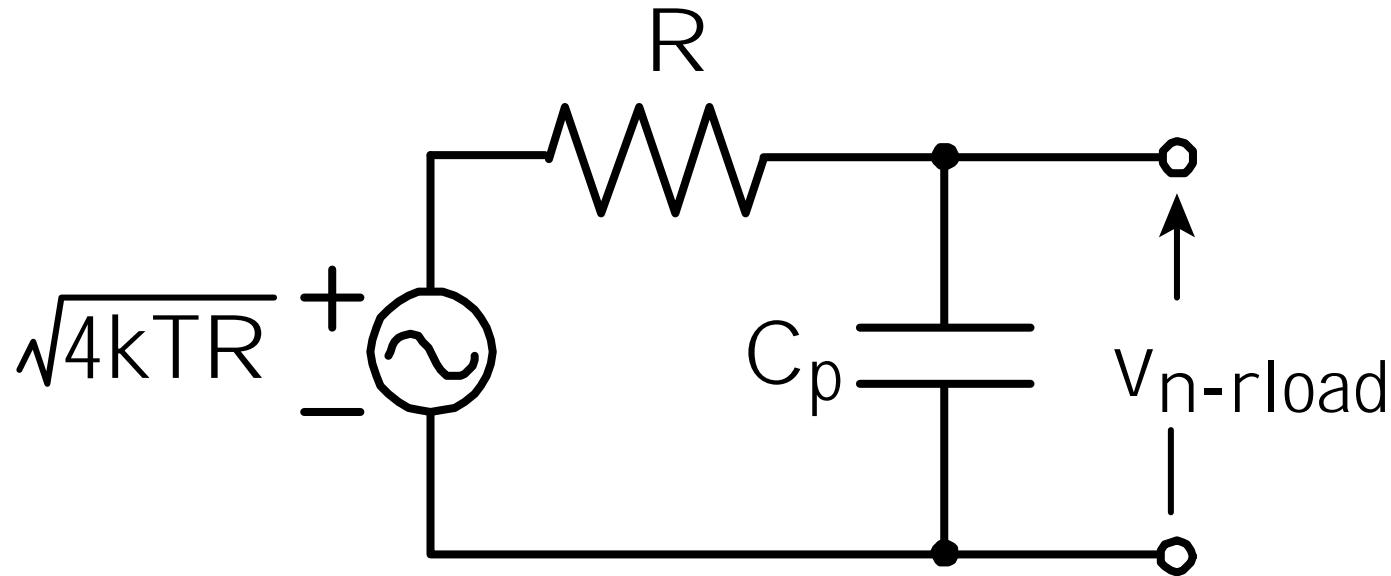
$$\overline{v_{mos-noise}^2(f)} = 4kT\gamma_n \frac{1}{g_m} + \frac{\alpha_1/f}{C_{OX}WLf}$$

バイポーラトランジスタモデル



$$\frac{1}{i_{bip-noise}^2(f)} = \frac{K_{1/f} I_B^a}{f} + 2qI_B$$

雑音解析の例(抵抗が発生する雑音)



$$T_{rload}(s) = \frac{1}{1+sC_pR} \Rightarrow |T_{rload}(j\omega)|^2 = \frac{1}{1+\omega^2 C_p^2 R^2}$$

$$T_{rload}(s) = \frac{1}{1+sC_pR} \Rightarrow |T_{rload}(j\omega)|^2 = \frac{1}{1+\omega^2C_p^2R^2}$$

$$\overline{v_{n-rload}}^2 = \int_0^\infty |T_{rload}(j\omega)|^2 \frac{4kTR}{2\pi} d\omega$$

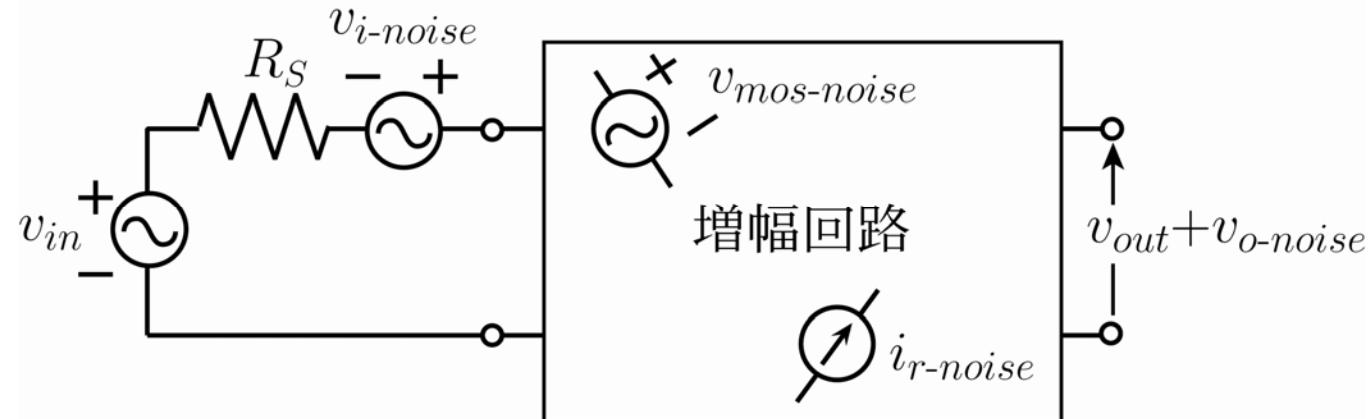
$$= \int_0^\infty \frac{1}{1+\omega^2C_p^2R^2} \frac{4kTR}{2\pi} d\omega$$

$$= \frac{2kT}{C_p^2R\pi} \int_0^\infty \frac{1}{\omega^2 + \frac{1}{C_p^2R^2}} d\omega = \frac{2kT}{C_p^2R\pi} \left[C_pR \tan^{-1}(C_pR\omega) \right]_0^\infty$$

$$= \frac{2kT}{C_p^2R\pi} \cdot C_pR \left(\frac{\pi}{2} - 0 \right) = \underline{\frac{kT}{C_p}}$$

増幅回路と雑音

雑音係数と雑音指数



$$SNR_{in} = \frac{\overline{v_{in}}^2}{\overline{v_{i-noise}}^2}$$

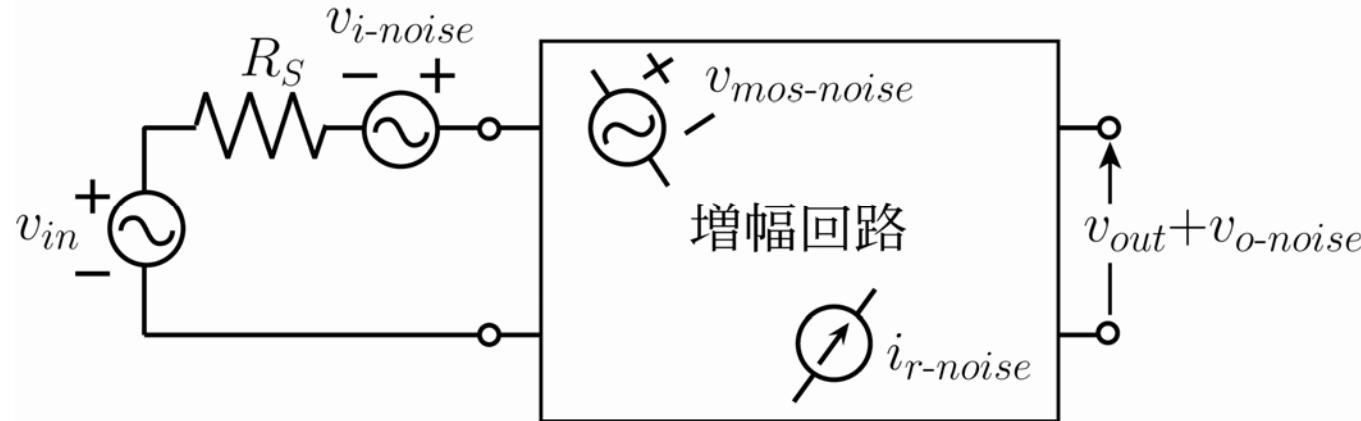
$$SNR_{out} = \frac{A^2 \overline{v_{in}}^2}{\overline{v_{o-noise}}^2}$$

$$F = \frac{SNR_{in}}{SNR_{out}}$$

: 雑音係数

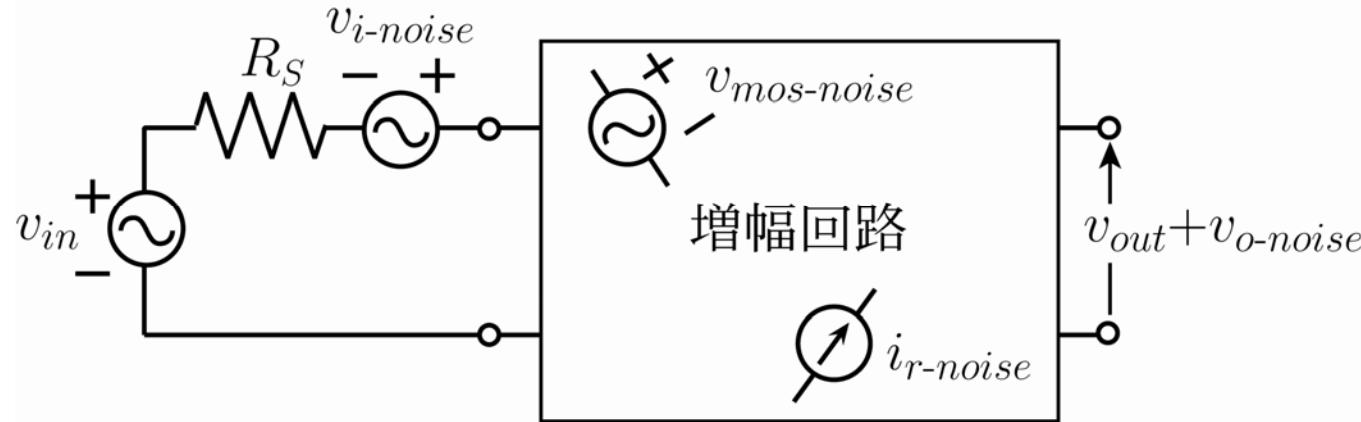
$$NF = 10 \log F$$

: 雑音指数



$$\overline{v_{o\text{-noise}}^2} = A^2 \overline{v_{i\text{-noise}}^2} + \overline{v_{\text{inner-noise}}^2}$$

$v_{\text{mos-noise}}$ や $i_{r\text{-noise}}$ などの增幅回路内部の
雑音に起因する成分



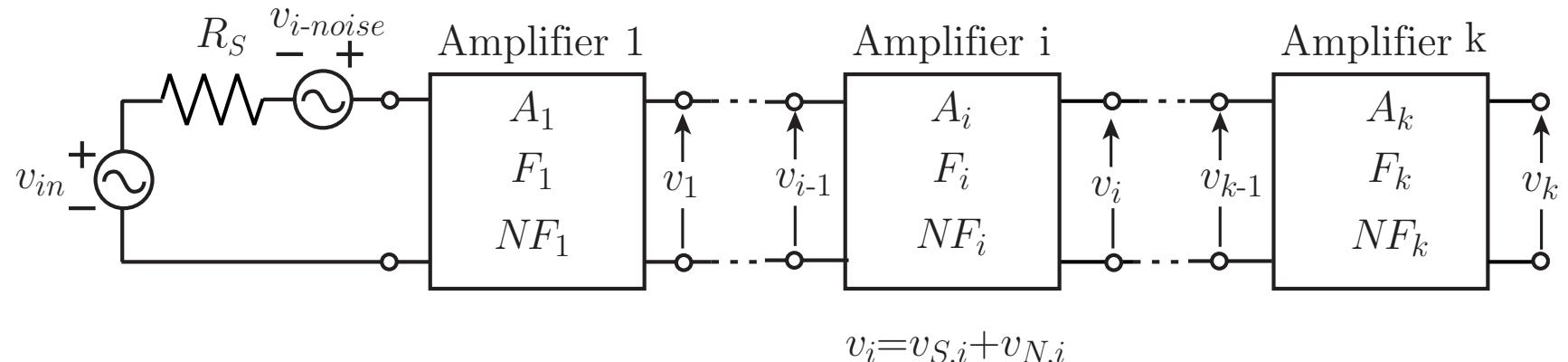
$$\overline{v_{o\text{-noise}}}^2 = A^2 \overline{v_{i\text{-noise}}}^2 + \overline{v_{\text{inner-noise}}}^2$$

$$\text{SNR}_{\text{out}} = \frac{\overline{A^2 v_{in}}^2}{\overline{v_{o\text{-noise}}}^2} = \frac{\overline{v_{in}}^2}{\overline{v_{i\text{-noise}}}^2 + \overline{v_{\text{inner-noise}}}^2 / A^2}$$

$$\text{SNR}_{\text{in}} = \frac{\overline{v_{in}}^2}{\overline{v_{i\text{-noise}}}^2} \geq \text{SNR}_{\text{out}}$$

$$F = 1 + \frac{\overline{v_{\text{inner-noise}}}^2}{A^2 \overline{v_{i\text{-noise}}}^2}$$

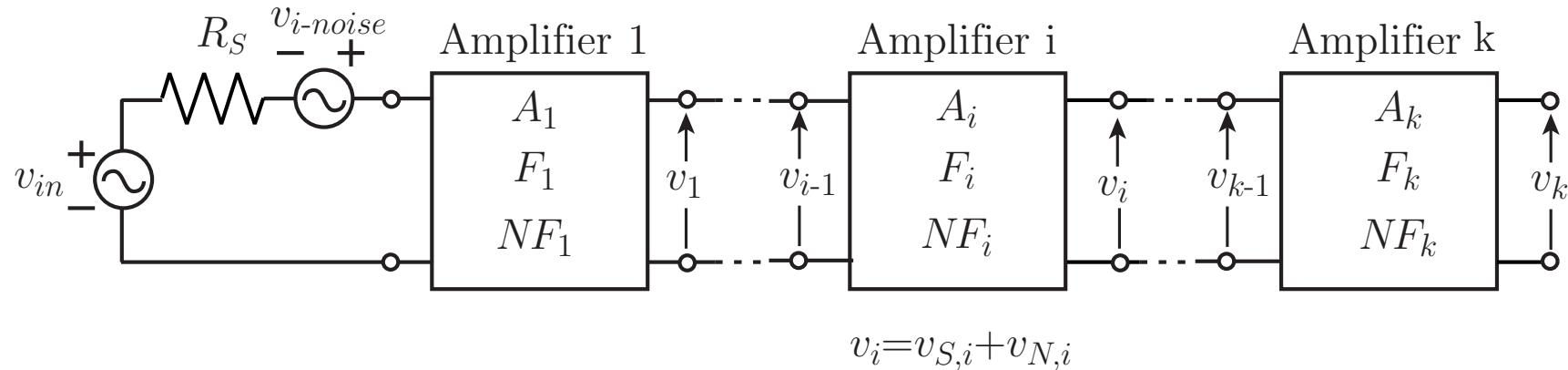
縦続接続型システムの評価



$$\overline{v_{0\text{-noise}}}^2 = A^2 \overline{v_{i\text{-noise}}}^2 + \overline{v_{\text{inner-noise}}}^2$$

$$F = 1 + \frac{\overline{v_{\text{inner-noise}}}^2}{A^2 \overline{v_{i\text{-noise}}}^2}$$

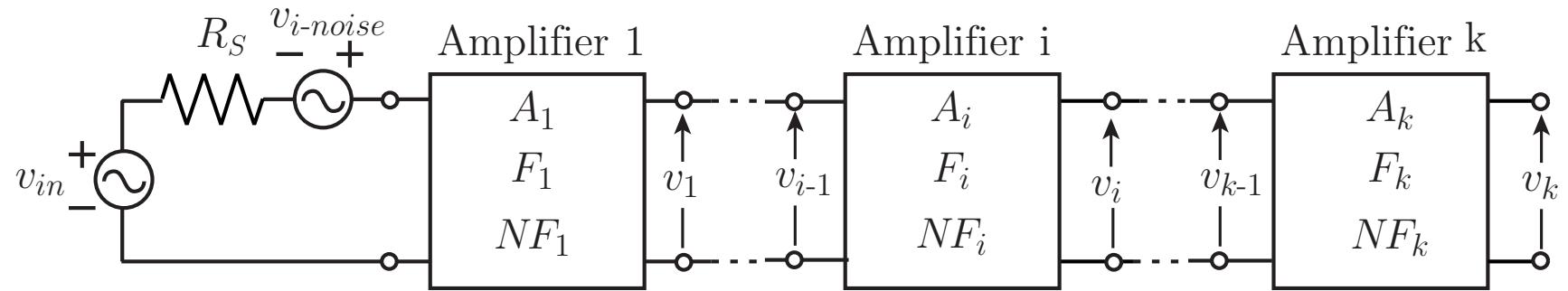
$$\boxed{\overline{v_{N,i}}^2 = A_i^2 F_i \overline{v_{N,i-1}}^2}$$



$$\overline{v_{N,i}}^2 = A_i^2 F_i \overline{v_{N,i-1}}^2$$

$$\overline{v_{S,i}}^2 = A_i^2 \overline{v_{S,i-1}}^2$$

$$F_{\text{total}} = \frac{\frac{\overline{v_{in}}^2}{\overline{v_{S,k}}^2}}{\frac{\overline{v_{N,k}}^2}{\overline{v_{i-\text{noise}}}^2}} = \frac{\overline{v_{i-\text{noise}}}^2}{A_1^2 A_2^2 \dots A_k^2 \overline{v_{in}}^2} = \underline{\underline{F_1 F_2 \dots F_k}}$$



$$v_i = v_{S,i} + v_{N,i}$$

$$\overline{v_{N,i}^2} = A_i^2 \overline{v_{N,i-1}^2} + v_{\text{inner-noise},i}^2$$

$$\overline{v_{N,k}^2} = A_k^2 A_{k-1}^2 \cdots A_1^2 \overline{v_{i-\text{noise}}^2}$$

$$+ A_k^2 A_{k-1}^2 \cdots A_2^2 \overline{v_{\text{inner-noise},1}^2}$$

$$+ A_k^2 A_{k-1}^2 \cdots A_3^2 \overline{v_{\text{inner-noise},2}^2} + \cdots$$

$$+ A_k^2 \overline{v_{\text{inner-noise},k-1}^2} + \overline{v_{\text{inner-noise},k}^2}$$

$$\begin{aligned}
& \overline{v_{N,k}^2} = A_k^2 A_{k-1}^2 \cdots A_1^2 \overline{v_{i-\text{noise}}^2} \\
& + A_k^2 A_{k-1}^2 \cdots A_2^2 \overline{v_{\text{inner-noise},1}^2} \\
& + A_k^2 A_{k-1}^2 \cdots A_3^2 \overline{v_{\text{inner-noise},2}^2} + \cdots \\
& + A_k^2 \overline{v_{\text{inner-noise},k-1}^2} + \overline{v_{\text{inner-noise},k}^2}
\end{aligned}$$

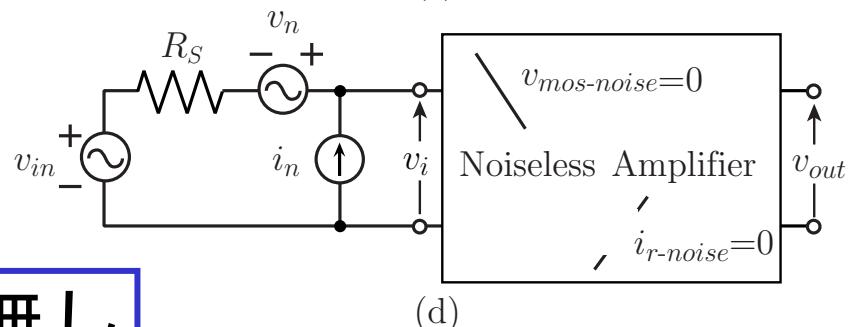
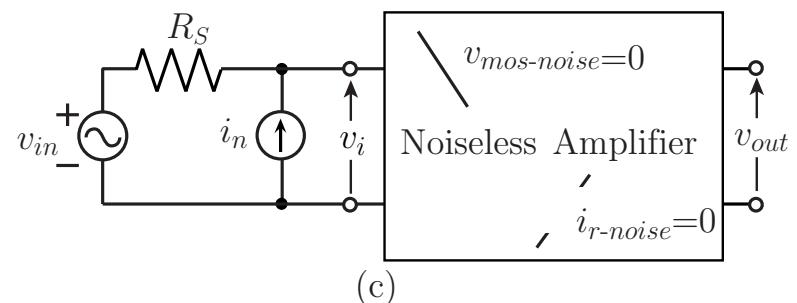
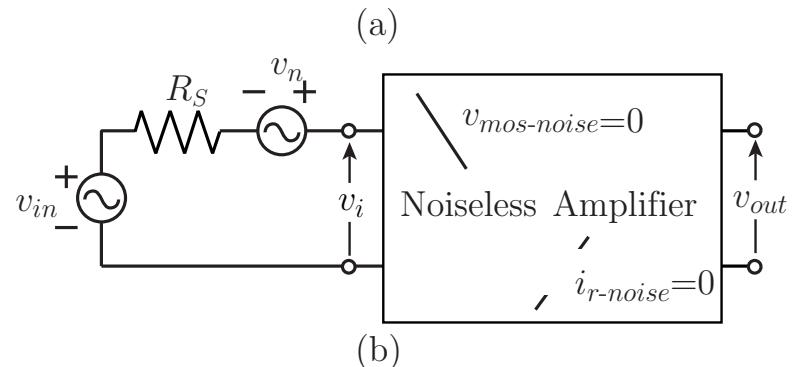
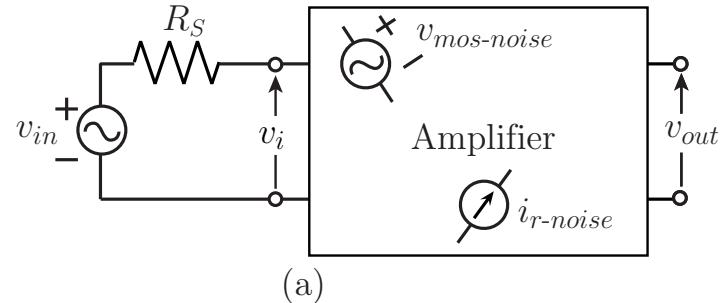
$$F_{\text{total}} = \frac{\overline{v_{in}^2}}{\overline{v_{i-\text{noise}}^2}} \cdot \frac{\overline{v_{N,k}^2}}{\overline{v_{S,k}^2}} = 1 + \frac{\overline{v_{\text{inner-noise},1}^2}}{A_1^2 \overline{v_{i-\text{noise}}^2}} + \frac{\overline{v_{\text{inner-noise},2}^2}}{A_1^2 A_2^2 \overline{v_{i-\text{noise}}^2}} \\
+ \cdots + \frac{\overline{v_{\text{inner-noise},k-1}^2}}{A_1^2 A_2^2 \cdots A_{k-1}^2 \overline{v_{i-\text{noise}}^2}} + \frac{\overline{v_{\text{inner-noise},k}^2}}{A_1^2 A_2^2 \cdots A_k^2 \overline{v_{i-\text{noise}}^2}}$$

低雑音増幅回路の設計

増幅回路内部で発生する
雑音の等価表現

- (b): R_S が無限大のとき矛盾
(c): R_S が零のとき矛盾

- (d): 任意の R_S について矛盾無し

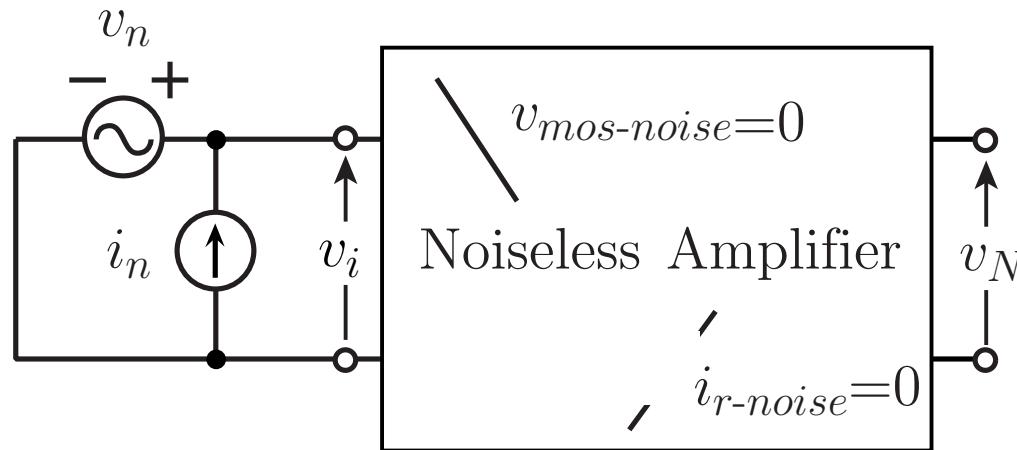


増幅回路の出力雑音のみ考慮

v_n の求め方

$$v_n = \frac{v_N}{A}$$

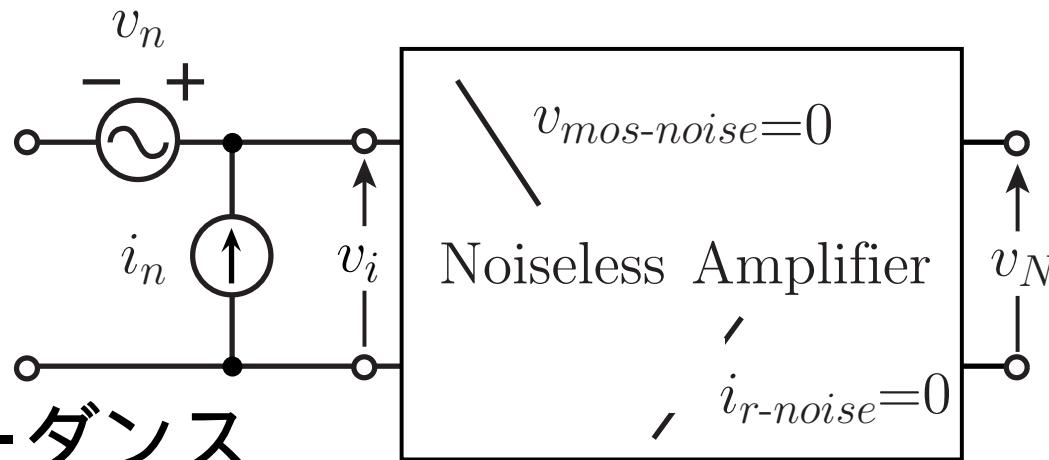
A : 電圧利得



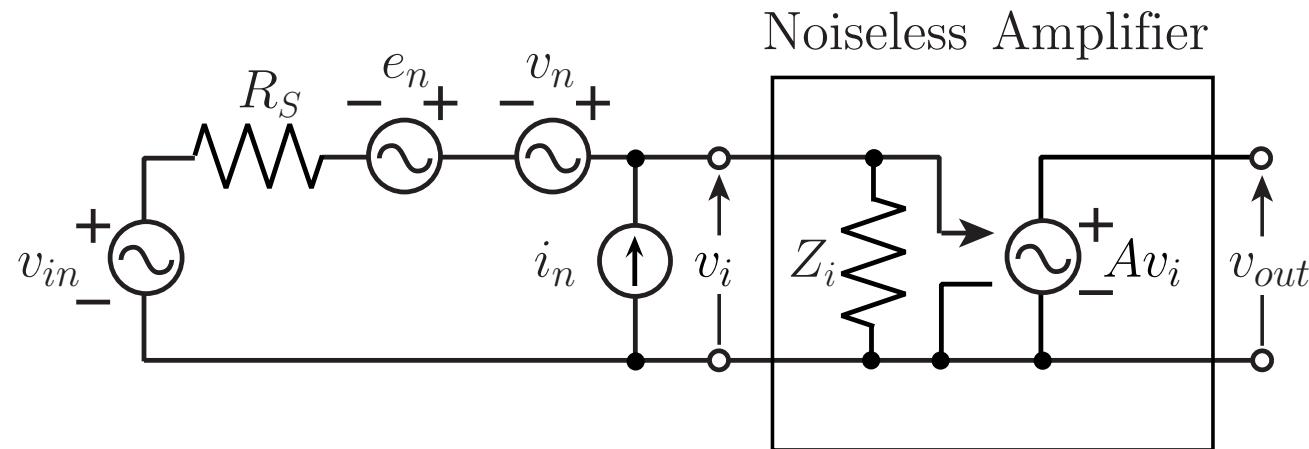
i_n の求め方

$$i_n = \frac{v_N}{Z_T}$$

Z_T : 伝達インピーダンス

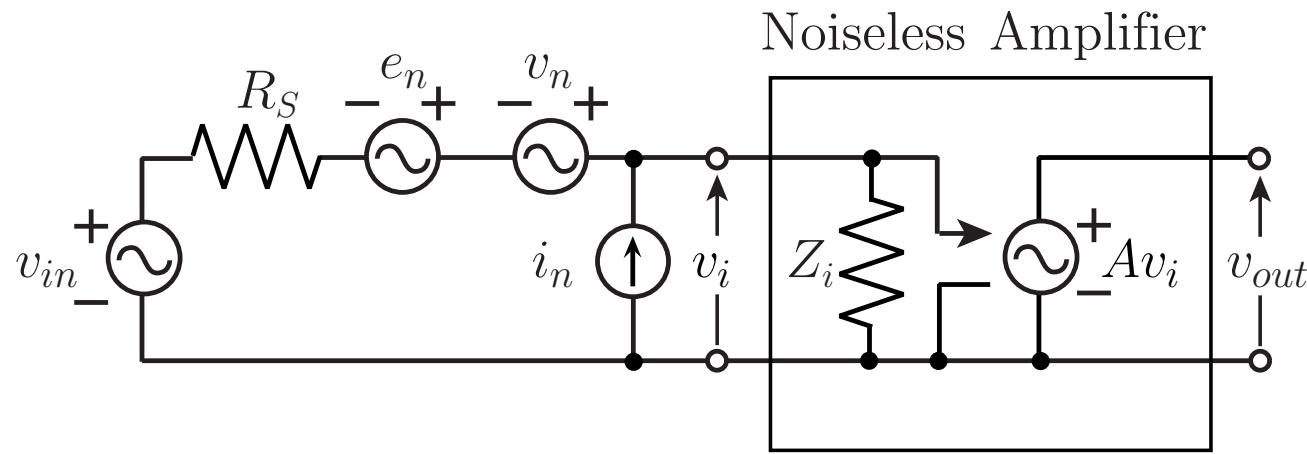


雜音整合



$$\overline{e_n^2} = 4kT R_S$$

$$v_S = \frac{A Z_i}{R_S + Z_i} v_{in}$$



e_n と v_n , e_n と i_n は無相関

v_n と i_n も無相関と仮定

$$\overline{v_N^2} = \frac{A^2 Z_i^2}{|R_S + Z_i|^2} (\overline{e_n^2} + \overline{v_n^2} + \overline{R_S^2 i_n^2})$$

$$\overline{e_n^2} = 4kT R_S$$

$$v_S = \frac{A Z_{in}}{R_S + Z_{in}} v_{in}$$

$$\overline{v_N^2} = \frac{A^2 Z_{in}^2}{|R_S + Z_{in}|^2} (\overline{e_n^2} + \overline{v_n^2} + R_S^2 \overline{i_n^2})$$

$$SNR_{in} = \frac{\overline{v_{in}^2}}{\overline{e_n^2}}$$

$$SNR_{out} = \frac{\overline{v_S^2}}{\overline{v_N^2}} = \frac{\overline{v_{in}^2}}{\overline{e_n^2} + \overline{v_n^2} + R_S^2 \overline{i_n^2}}$$

$$F = \frac{SNR_{in}}{SNR_{out}} = \frac{\overline{e_n^2} + \overline{v_n^2} + R_S^2 \overline{i_n^2}}{\overline{e_n^2}} = 1 + \frac{\overline{v_n^2} + R_S^2 \overline{i_n^2}}{4kT R_S}$$

$$F = 1 + \frac{\sqrt{v_n^2 + R_S^2 i_n^2}}{4kT R_S}$$

相加・相乗平均の定理

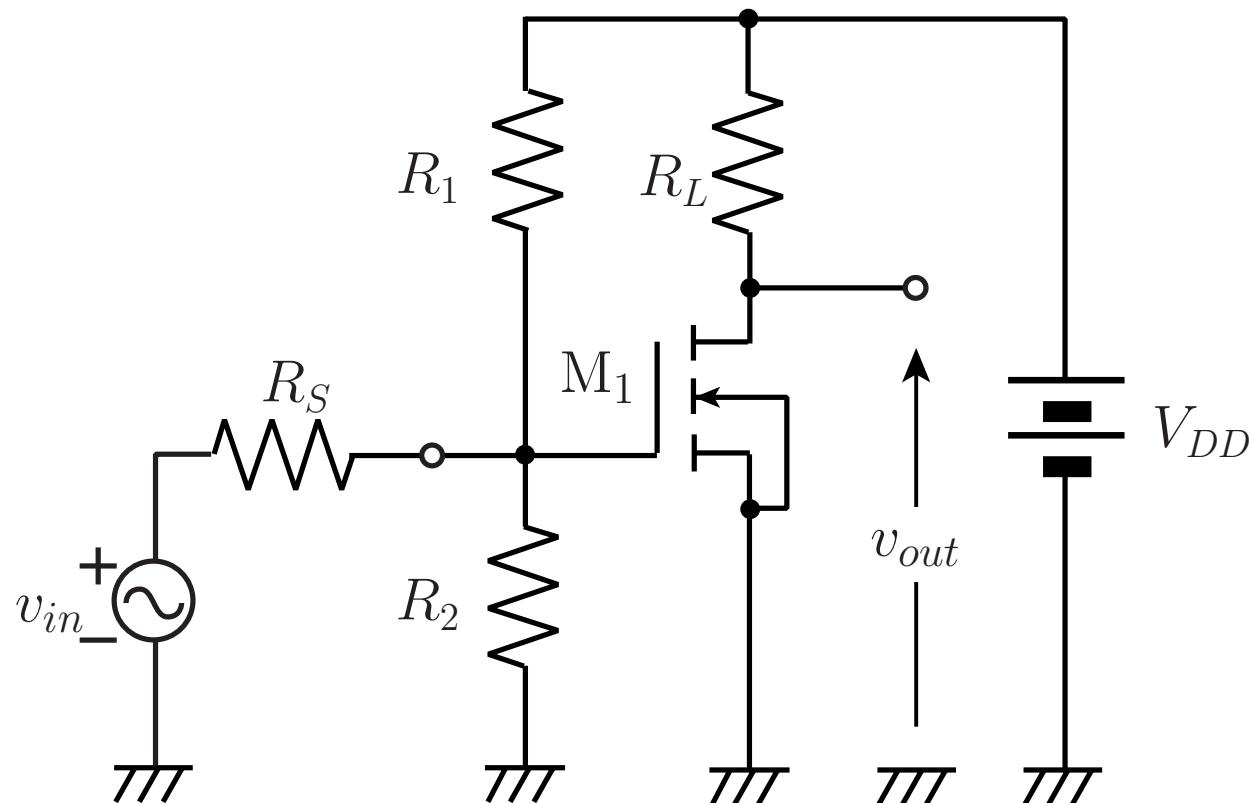
$$a + b \geq 2\sqrt{ab}$$

$\frac{\sqrt{v_n^2}}{R_S} = R_S \sqrt{i_n^2}$ のとき F が最小

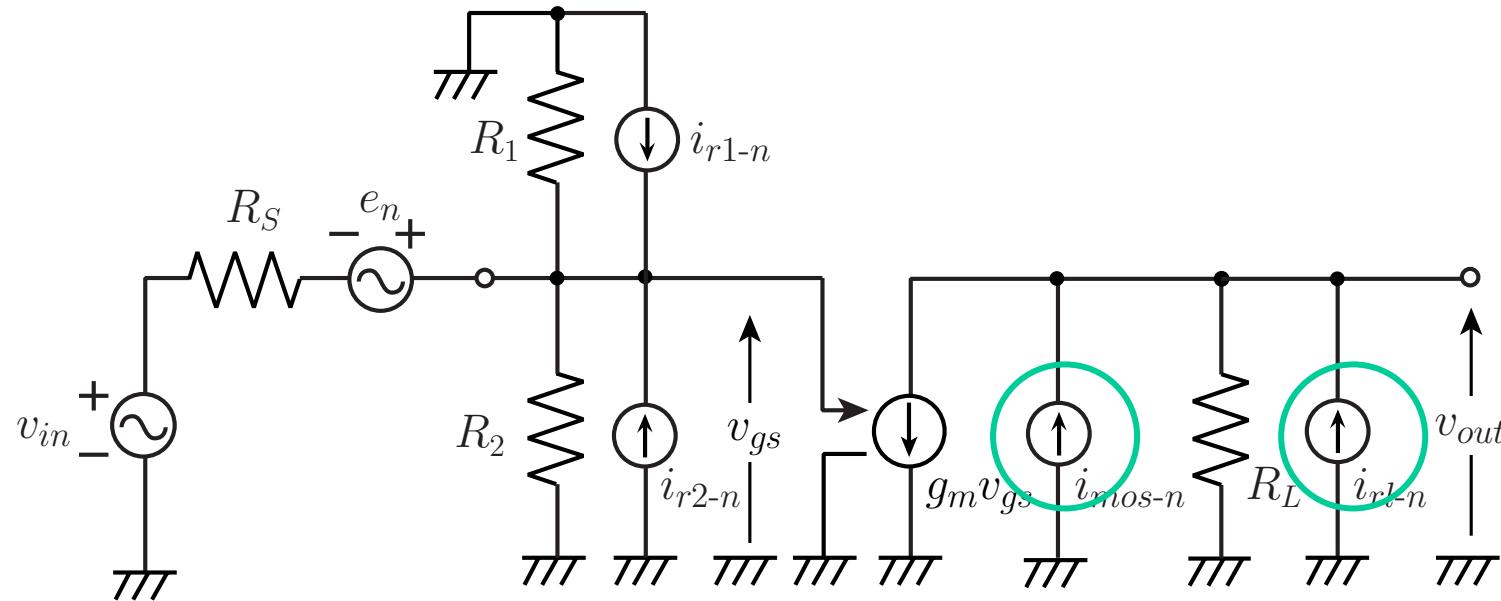
$$R_S = \sqrt{\frac{v_n^2}{i_n^2}}$$

実際の増幅回路の雑音解析例

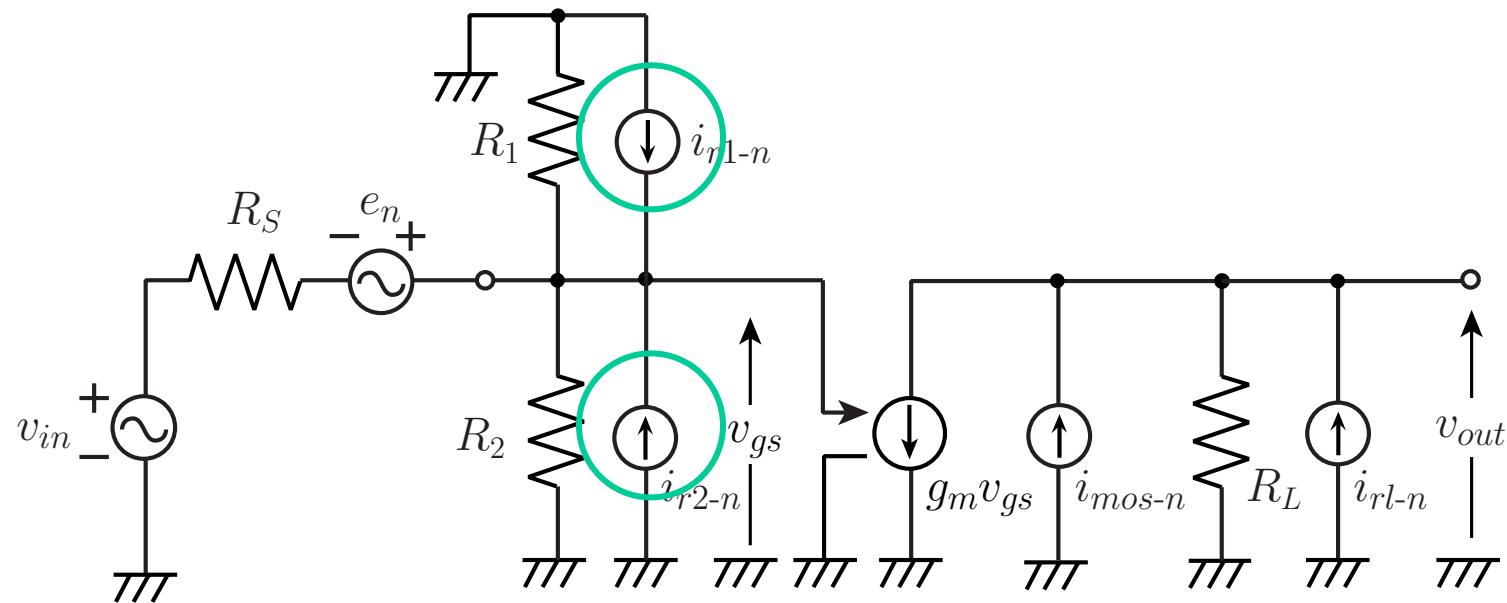
ソース接地増幅回路



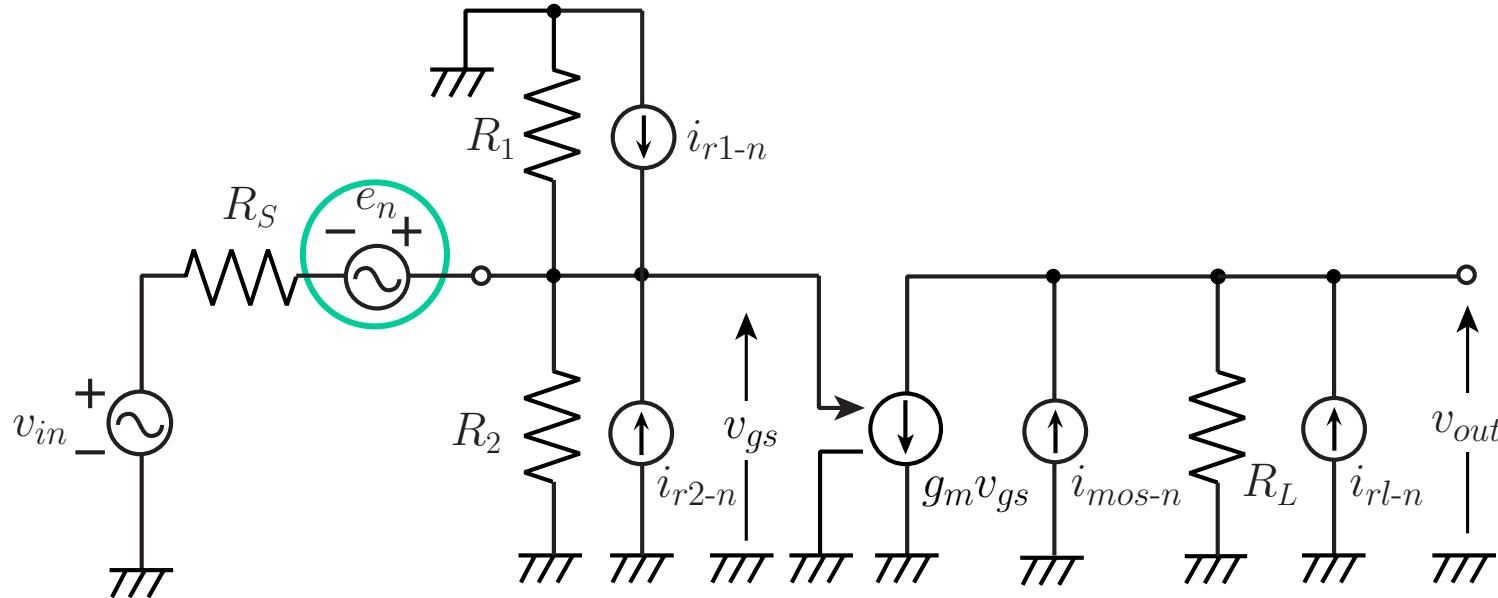
ソース接地増幅回路の小信号モデル



$$\overline{v_{o-n1}^2} = R_L^2 (\overline{i_{rl-n}^2} + \overline{i_{mos-n}^2})$$



$$\overline{v_{0-n}}^2 = \left| g_m R_L \frac{R_1 R_2 R_S}{R_1 R_2 + R_2 R_S + R_S R_1} \right|^2 \left(\overline{i_{r1-n}}^2 + \overline{i_{r2-n}}^2 \right)$$



$$\overline{v_{o-n3}^2} = \left| g_m R_L \frac{R_1 R_2}{R_1 R_2 + R_2 R_S + R_S R_1} \right|^2 \overline{e_n^2}$$

$$\begin{aligned}
\overline{v_N^2} &= \overline{v_{0-n1}^2} + \overline{v_{0-n2}^2} + \overline{v_{0-n3}^2} \\
&= R_L^2 (\overline{i_{r1-n}^2} + \overline{i_{mos-n}^2}) \\
&+ \left| g_m R_L \frac{R_1 R_2 R_S}{R_1 R_2 + R_2 R_S + R_S R_1} \right|^2 (\overline{i_{r1-n}^2} + \overline{i_{r2-n}^2}) \\
&+ \left| g_m R_L \frac{R_1 R_2}{R_1 R_2 + R_2 R_S + R_S R_1} \right|^2 \overline{e_n^2} \\
\overline{v_s^2} &= \left| g_m R_L \frac{R_1 R_2}{R_1 R_2 + R_2 R_S + R_S R_1} \right|^2 \overline{v_{in}^2} \\
\text{SNR}_{in} &= \frac{\overline{v_{in}^2}}{\overline{e_n^2}}
\end{aligned}$$

$$\overline{v_N}^2 = \overline{v_{0-n1}}^2 + \overline{v_{0-n2}}^2 + \overline{v_{0-n3}}^2$$

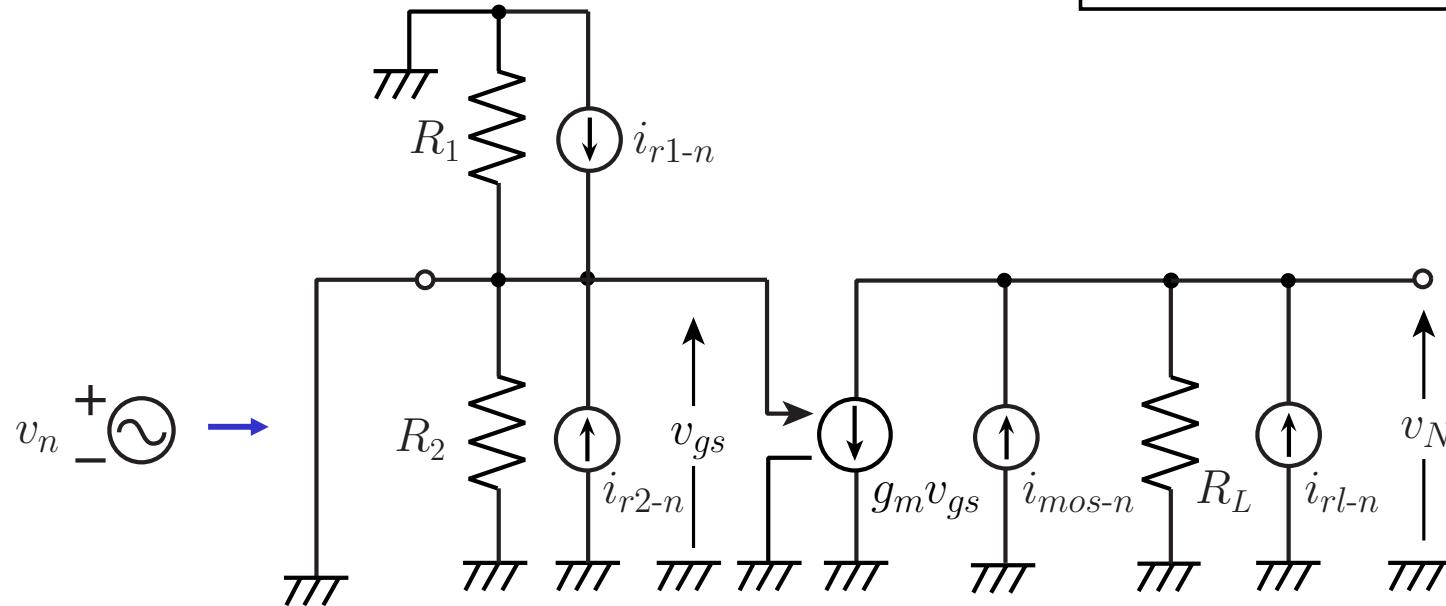
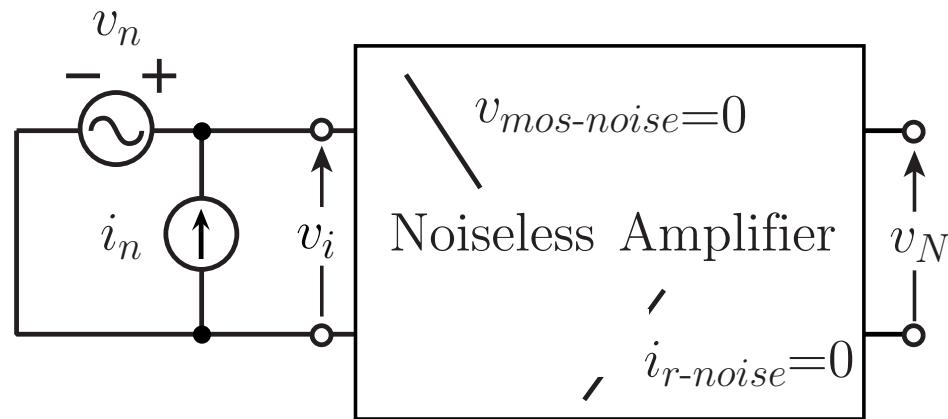
$$\overline{v_S}^2 = \left| g_m R_L \frac{R_1 R_2}{R_1 R_2 + R_2 R_S + R_S R_1} \right|^2 \overline{v_{in}}^2$$

$$SNR_{in} = \frac{\overline{v_{in}}^2}{\overline{e_n}^2} \quad e_n^2 = 4kT R_S$$

$$F = \frac{SNR_{in}}{SNR_{out}}$$

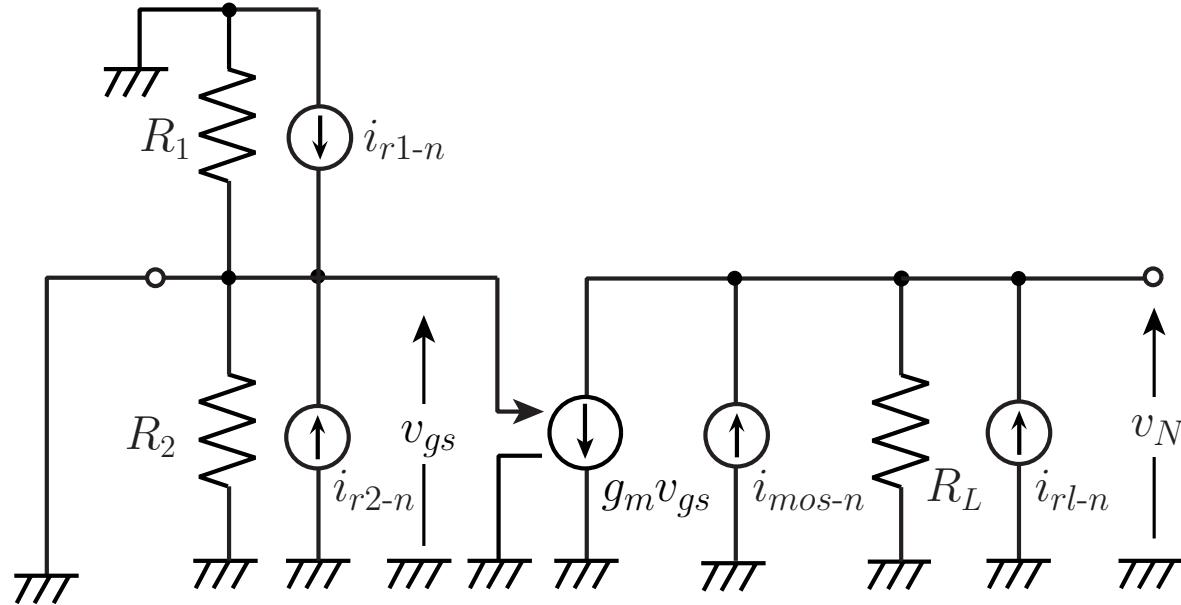
$$= 1 + \frac{1}{4kT R_S} \left\{ \left| \frac{R_1 R_2 + R_2 R_S + R_S R_1}{g_m R_1 R_2} \right|^2 (\overline{i_{rl-n}}^2 + \overline{i_{mos-n}}^2) + R_S^2 (\overline{i_{r1-n}}^2 + \overline{i_{r2-n}}^2) \right\}$$

v_n の求め方



$$A = \frac{V_{out}}{V_n} = -g_m R_L$$

$$\overline{V_n^2} = \frac{\overline{V_N^2}}{A^2}$$

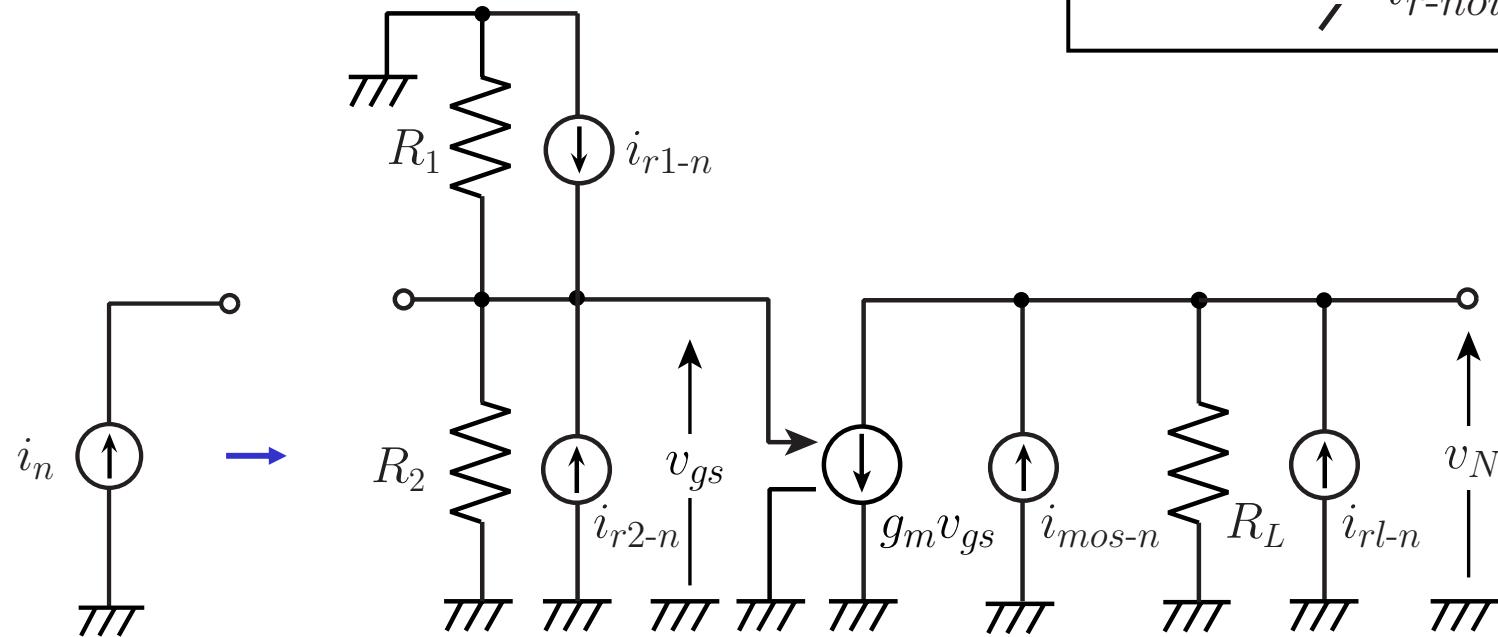
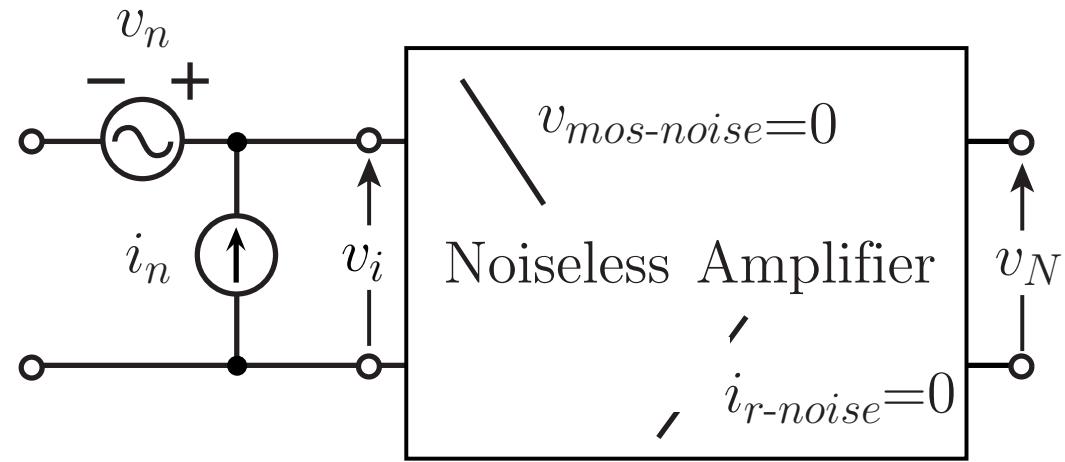


$$\overline{v_N^2} = R_L^2 (\overline{i_{rl-n}^2} + \overline{i_{mos-n}^2})$$

$$A = \frac{v_{out}}{v_n} = -g_m R_L$$

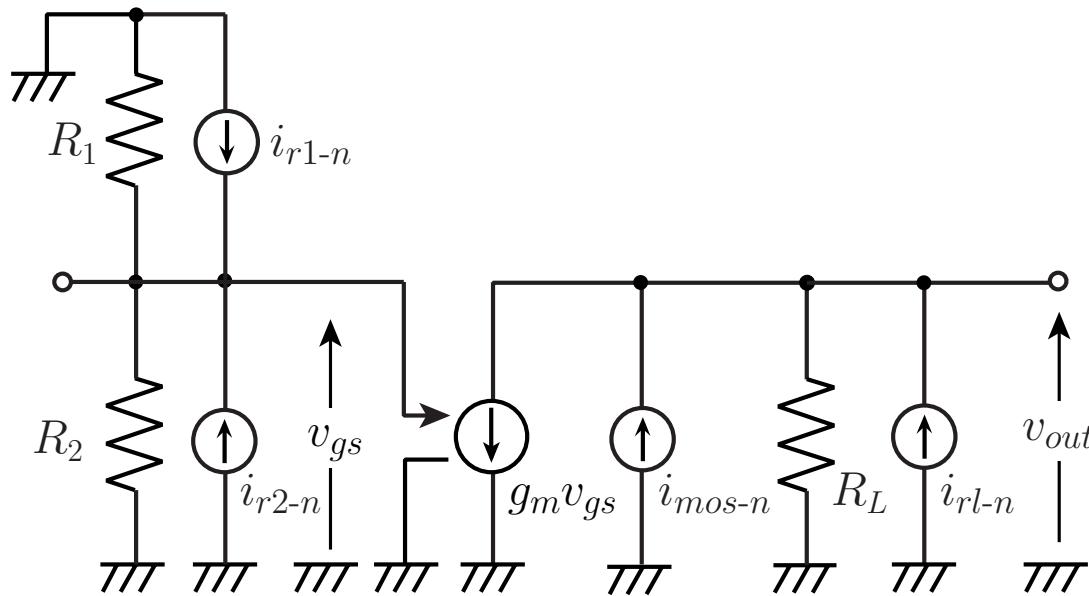
$$\boxed{\overline{v_n^2} = \frac{1}{2} (\overline{i_{rl-n}^2} + \overline{i_{mos-n}^2})}$$

i_nの求め方



$$Z_T = -g_m R_L \frac{R_1 R_2}{R_2 + R_1}$$

$$\overline{i_n^2} = \frac{\overline{v_N^2}}{Z_T^2}$$

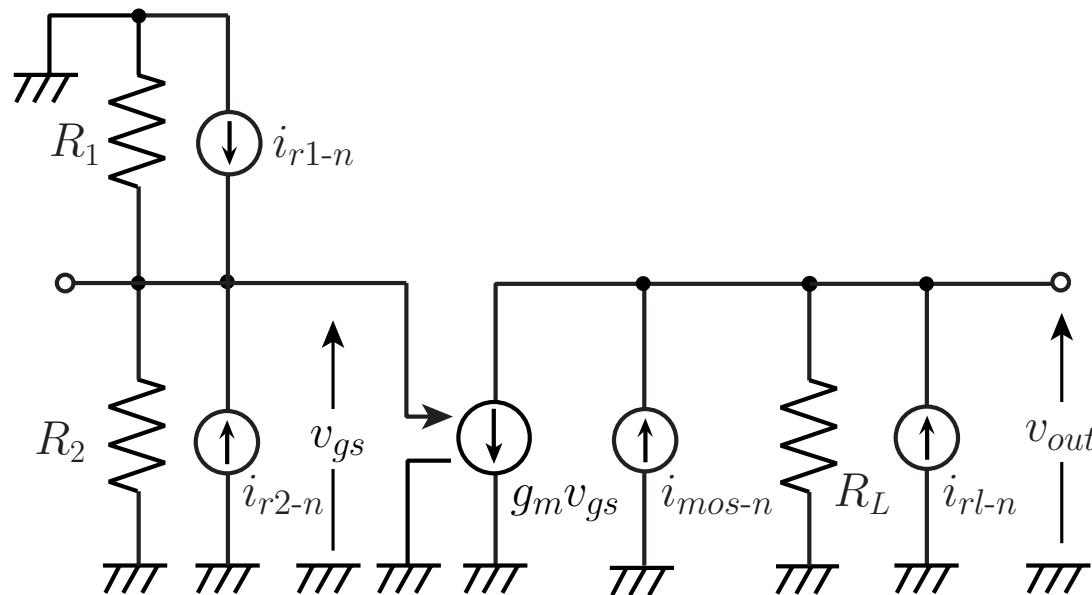


$$\overline{v_{o-n1}}^2 = R_L^2 (\overline{i_{rl-n}}^2 + \overline{i_{mos-n}}^2)$$

$$\overline{v_{o-n2}}^2 = \left| g_m R_L \frac{R_1 R_2}{R_2 + R_1} \right|^2 (\overline{i_{r1-n}}^2 + \overline{i_{r2-n}}^2)$$

$$\overline{v_{out}}^2 = \overline{v_{o-n1}}^2 + \overline{v_{o-n2}}^2$$

$$\overline{v_N^2} = R_L^2 \left(\overline{i_{rl-n}^2} + \overline{i_{mos-n}^2} \right) + \left| g_m R_L \frac{R_1 R_2}{R_2 + R_1} \right|^2 \left(\overline{i_{r1-n}^2} + \overline{i_{r2-n}^2} \right)$$



$$i_n = \frac{v_N}{Z_T}$$

$$Z_T = -g_m R_L \frac{R_1 R_2}{R_2 + R_1}$$

$$\overline{i_n^2} = \left| \frac{R_1 + R_2}{g_m R_2 R_1} \right|^2 \left(\overline{i_{rl-n}^2} + \overline{i_{mos-n}^2} \right) + \left(\overline{i_{r1-n}^2} + \overline{i_{r2-n}^2} \right)$$

$$\overline{v_n^2} = \frac{1}{g_m^2} (\overline{i_{rl-n}^2} + \overline{i_{mos-n}^2})$$

$$\overline{i_n^2} = \left| \frac{R_1 + R_2}{g_m R_2 R_1} \right|^2 (\overline{i_{rl-n}^2} + \overline{i_{mos-n}^2}) + (\overline{i_{r1-n}^2} + \overline{i_{r2-n}^2})$$

$$F = 1 + \frac{\overline{v_n^2} + R_S^2 \overline{i_n^2}}{4kT R_S} \text{ より}$$

$$F = 1 + \frac{1}{4kT R_S} \left[\left\{ \frac{1}{g_m^2} + \left| \frac{(R_1 + R_2) R_S}{g_m R_1 R_2} \right|^2 \right\} (\overline{i_{rl-n}^2} + \overline{i_{mos-n}^2}) + R_S^2 (\overline{i_{r1-n}^2} + \overline{i_{r2-n}^2}) \right]$$

v_n と i_n の間の相関も考慮

$$F = 1 + \frac{1}{4kTR_S} \left\{ \left| \frac{R_1 R_2 + R_2 R_S + R_S R_1}{g_m R_1 R_2} \right|^2 \left(\frac{i_{rl-n}^2 + i_{mos-n}^2}{i_{rl-n}^2 + i_{r2-n}^2} \right) + R_S^2 \left(\frac{i_{r1-n}^2 + i_{r2-n}^2}{i_{rl-n}^2 + i_{r2-n}^2} \right) \right\}$$

v_n と i_n は無相関と仮定

$$F = 1 + \frac{1}{4kTR_S} \left\{ \frac{1}{g_m^2} + \left| \frac{(R_1 + R_2)R_S}{g_m R_1 R_2} \right|^2 \right\} \left(\frac{i_{rl-n}^2 + i_{mos-n}^2}{i_{r1-n}^2 + i_{r2-n}^2} \right) + R_S^2 \left(\frac{i_{r1-n}^2 + i_{r2-n}^2}{i_{rl-n}^2 + i_{r2-n}^2} \right)$$

低雑音増幅回路の設計(1)

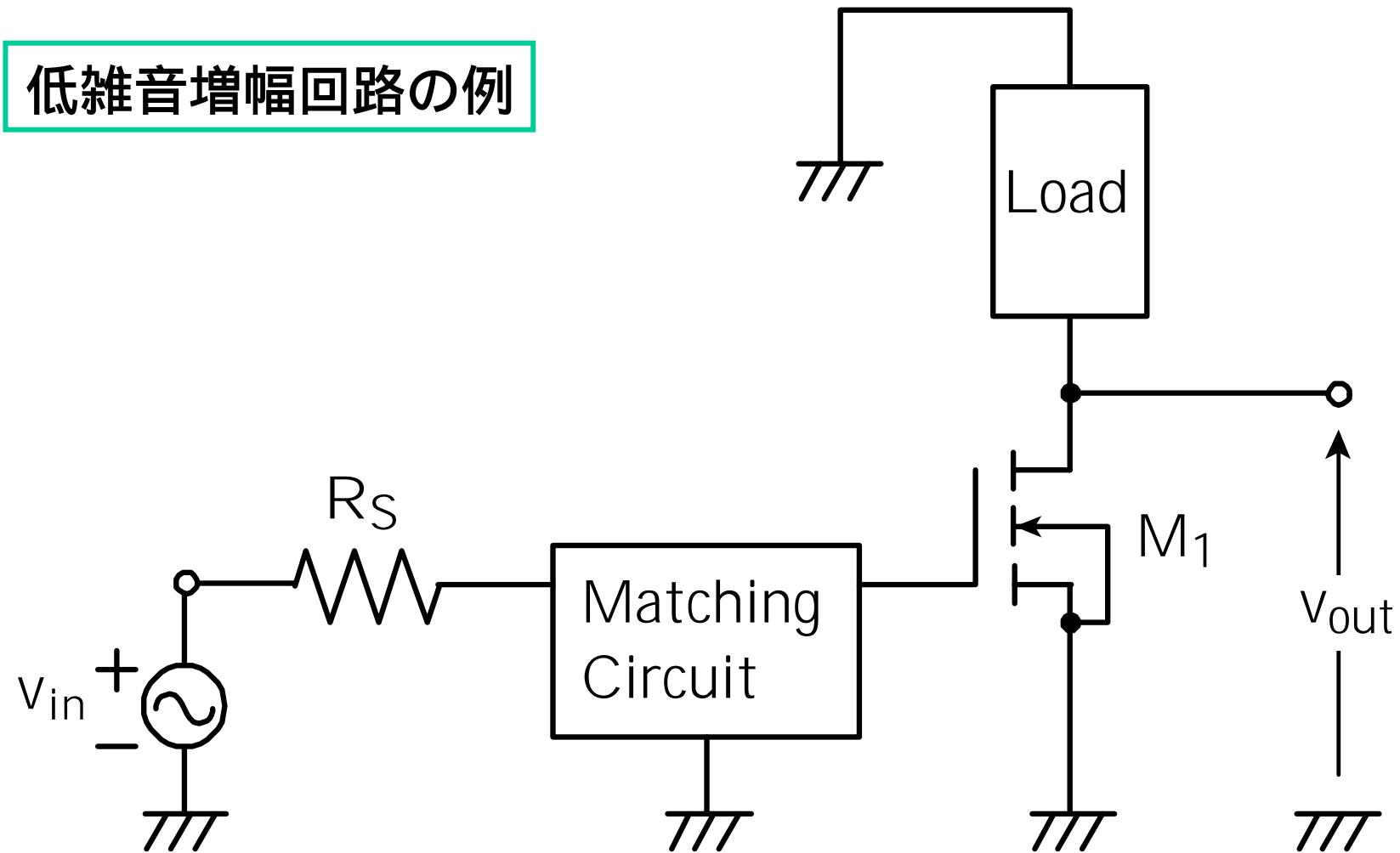
通信機器用低雑音増幅回路

高周波(数GHz)

狭帯域

LC共振特性の応用

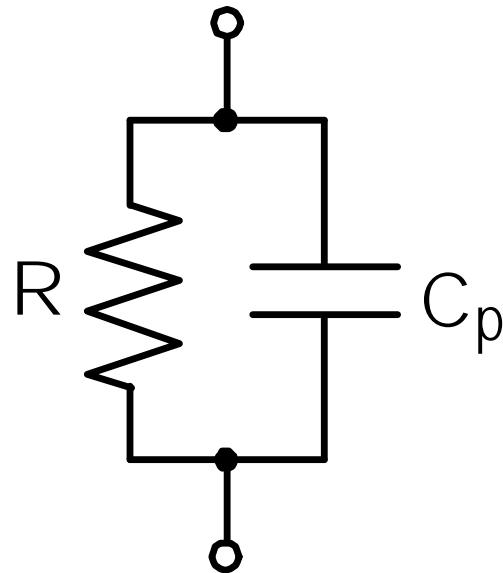
低雑音増幅回路の例



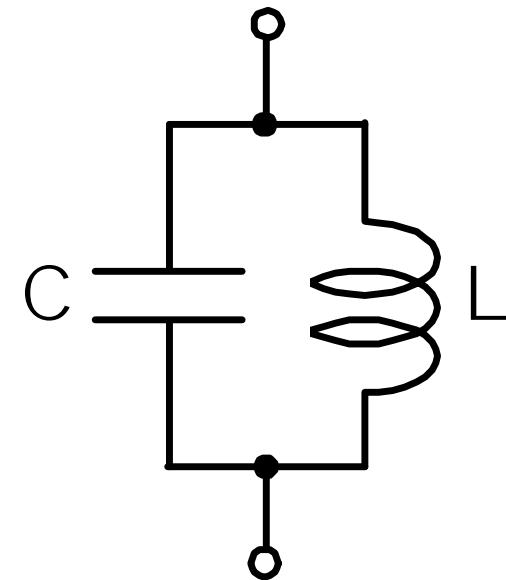
バイアス回路は省略

低雑音増幅回路における負荷の例

抵抗(寄生容量付き)

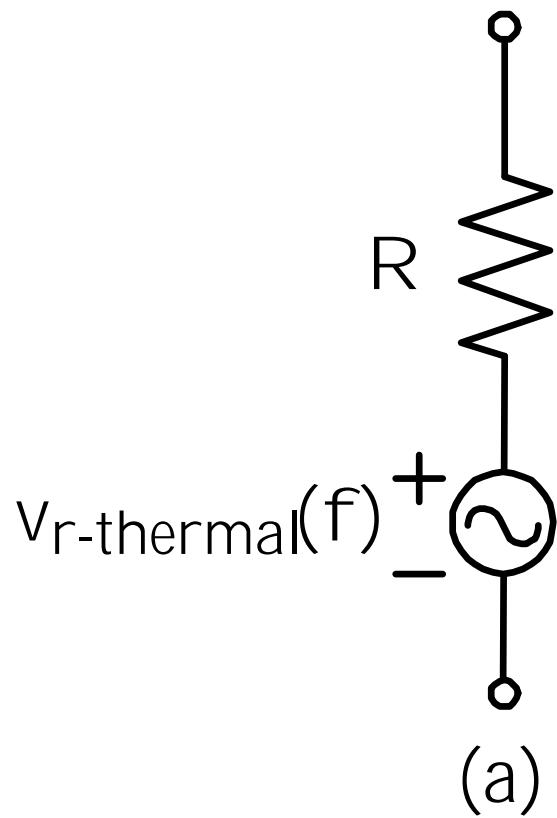


LC共振回路

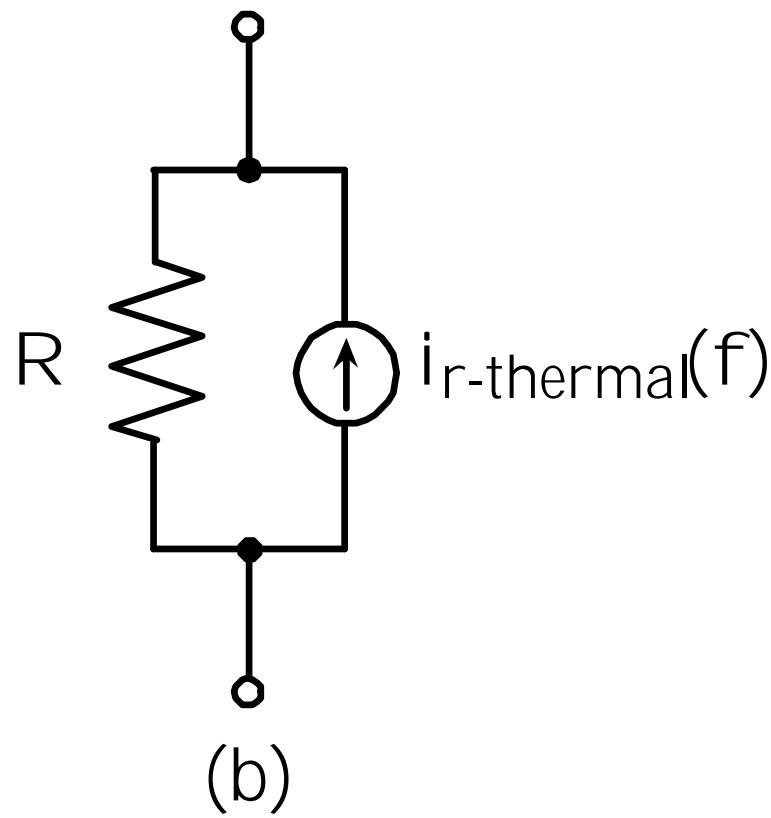


LC共振回路は無雑音?

抵抗の熱雑音



(a)

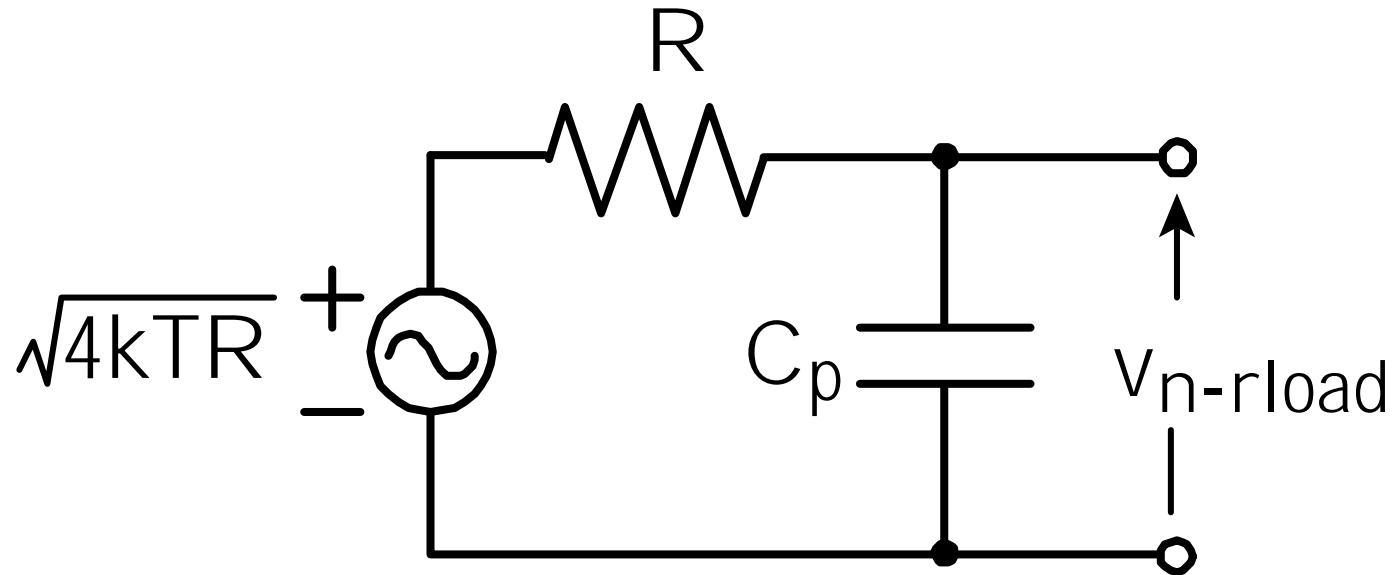


(b)

$$\overline{v_{r\text{-thermal}}^2(f)} = 4kT R$$

$$\overline{i_{r\text{-thermal}}^2(f)} = 4kT \frac{1}{R}$$

負荷抵抗が発生する雑音

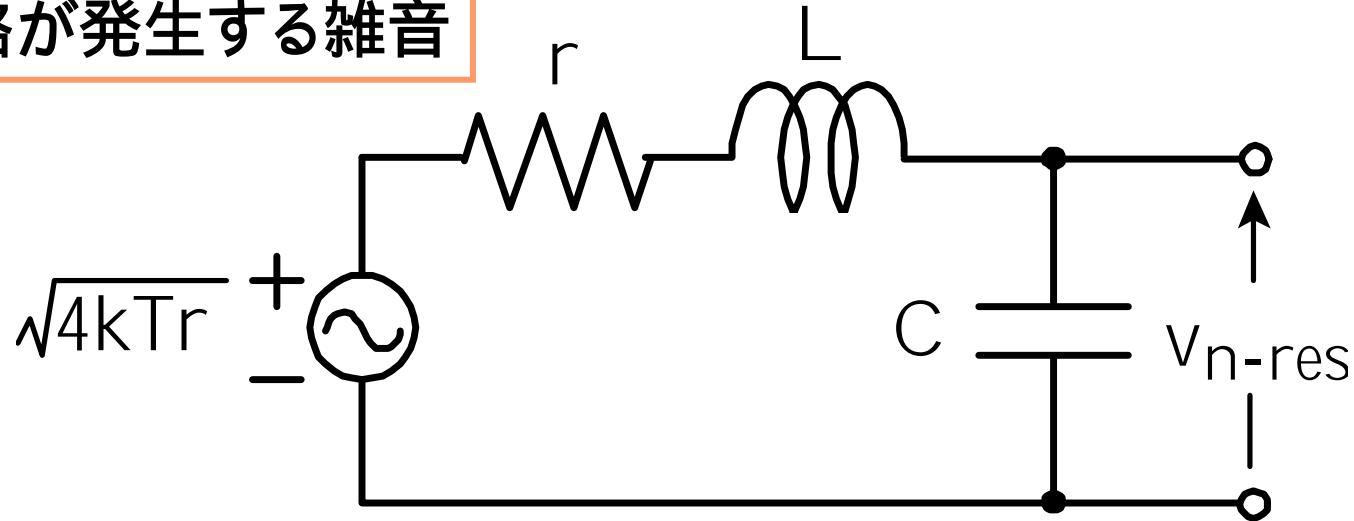


$$T_{rload}(s) = \frac{1}{1+sC_pR} \Rightarrow |T_{rload}(j\omega)|^2 = \frac{1}{1+\omega^2 C_p^2 R^2}$$

$$T_{rload}(s) = \frac{1}{1+sC_pR} \Rightarrow |T_{rload}(j\omega)|^2 = \frac{1}{1+\omega^2C_p^2R^2}$$

$$\begin{aligned}\overline{v_{n-rload}}^2 &= \int_0^\infty |T_{rload}(j\omega)|^2 \frac{4kTR}{2\pi} d\omega \\ &= \int_0^\infty \frac{1}{1+\omega^2C_p^2R^2} \frac{4kTR}{2\pi} d\omega \\ &= \frac{2kT}{C_p^2R\pi} \int_0^\infty \frac{1}{\omega^2 + \frac{1}{C_p^2R^2}} d\omega = \frac{2kT}{C_p^2R\pi} \left[C_pR \tan^{-1}(C_pR\omega) \right]_0^\infty \\ &= \frac{2kT}{C_p^2R\pi} C_pR \left(\frac{\pi}{2} - 0 \right) = \frac{kT}{C_p}\end{aligned}$$

LC共振回路が発生する雑音



$$T_{res}(s) = \frac{\frac{1}{LC}}{s^2 + s\frac{r}{L} + \frac{1}{LC}}$$

$$\Rightarrow |T_{res}(j\omega)|^2 = \frac{\frac{1}{L^2 C^2}}{\left(\omega^2 - \frac{1}{LC}\right)^2 + \left(\frac{r}{L}\right)^2 \omega^2}$$

$$T_{res}(s) = \frac{1}{s^2 + s \frac{r}{L} + \frac{1}{LC}}$$

$$\Rightarrow |T_{res}(j\omega)|^2 = \frac{1}{\left(\omega^2 - \frac{1}{LC}\right)^2 + \left(\frac{r}{L}\right)^2 \omega^2}$$

$$\overline{v_{n-res}}^2 = \int_0^\infty |T_{res}(j\omega)|^2 \frac{4kTr}{2\pi} d\omega$$

$$\overline{v_{n-\text{res}}}^2$$

$$= \int_0^\infty \frac{1}{\left(\omega^2 - \frac{1}{LC}\right)^2 + \left(\frac{r}{L}\right)^2} \cdot \frac{4kTr}{2\pi} d\omega$$

$$\int_0^\infty \frac{x^2}{(x^2 - a^2)^2 + b^2 x^2} dx = \frac{\pi}{2b}$$

ただし $\rho < \frac{b}{2} < a$ でなければならぬ。

$$\omega = \frac{1}{x} \text{ と置 } \Leftrightarrow d\omega = -\frac{1}{x^2} dx$$

$$\overline{v_{n-\text{res}}}^2 = \frac{2kTr}{\pi L^2 C^2} \int_0^\infty \frac{1}{\left(\omega^2 - \frac{1}{LC}\right)^2 + \left(\frac{r}{L}\right)^2 \omega^2} d\omega$$

$$= \frac{2kTr}{\pi L^2 C^2} \int_0^\infty \frac{1}{\left(\frac{1}{x^2} - \frac{1}{LC}\right)^2 + \left(\frac{r}{L}\right)^2 \frac{1}{x^2}} \cdot \frac{-1}{x^2} dx$$

$$= \frac{2kTr}{\pi L^2 C^2} \int_0^\infty \frac{1}{\left(\frac{1}{x^2} - \frac{1}{LC}\right)^2 x^2 + \left(\frac{r}{L}\right)^2} dx$$

$$= \frac{2kTr}{\pi L^2 C^2} \int_0^\infty \frac{x^2}{\left(1 - \frac{1}{LC}x^2\right)^2 + \left(\frac{r}{L}\right)^2 x^2} dx$$

$$\overline{V_{n-res}}^2 = \frac{2kTr}{\pi L^2 C^2} \int_0^\infty \frac{x^2}{\left(1 - \frac{1}{LC}x^2\right)^2 + \left(\frac{r}{L}\right)^2 x^2} dx$$

$$= \frac{2kTr}{\pi} \int_0^\infty \frac{x^2}{(x^2 - LC)^2 + (Cr)^2 x^2} dx$$

$$\int_0^\infty \frac{x^2}{(x^2 - a^2)^2 + b^2 x^2} dx = \frac{\pi}{2b}$$

ただし $\frac{b}{2} < a$ でなければならぬ。

$$\overline{v_{n-res}}^2 = \frac{2kTr}{\pi} \int_0^\infty \frac{x^2}{(x^2 - LC)^2 + (Cr)^2 x^2} dx$$

$$a = \sqrt{LC} \quad b = Cr \text{ より}$$

$\sqrt{\frac{L}{C}} > \frac{r}{2}$ が成り立てばよい

$$\overline{v_{n-res}}^2 = \frac{2kTr}{\pi} \cdot \frac{\pi}{2Cr} = \frac{kT}{C}$$

LC共振回路と抵抗負荷が発生する雑音の比較

- 雜音電力はいずれの場合も容量値のみに依存
- $C=C_p$ であれば雑音電力は等しい

信号増幅周波数の上限に関する考察

条件(1): $C = C_p$

(負荷の雑音電力が等しい)

条件(2): LC共振回路の共振時の抵抗 $R_{res} = R$

(增幅利得が等しい)

$$Z_{res}(s) = \frac{sL + r}{s^2LC + sCr + 1} = R_{res}$$

$$\Rightarrow j\omega_{res}L + r = j\omega_{res}CR_{res}r + R_{res}(1 - \omega_{res}^2LC)$$

$$j\omega_{res}L + r = j\omega_{res}CR_{res}r + R_{res}(1 - \omega_{res}^2 LC)$$

$$\Rightarrow L = CR_{res}r, \quad r = R_{res}(1 - \omega_{res}^2 LC)$$

$$\omega_{res} = \sqrt{\frac{1}{LC} \left(1 - \frac{r}{R_{res}} \right)} = \sqrt{\frac{1}{C^2 R_{res} r} \left(1 - \frac{r}{R_{res}} \right)} = \frac{1}{CR_{res}} \sqrt{\frac{R_{res}}{r} - 1}$$

$$Q_L = \frac{\omega_{res} L}{r} = \left(\frac{1}{CR_{res}} \sqrt{\frac{R_{res}}{r} - 1} \right) CR_{res} = \sqrt{\frac{R_{res}}{r} - 1}$$

$$\omega_{res} = \frac{1}{CR_{res}} Q_L$$

$$\omega_{\text{res}} = \frac{1}{C R_{\text{res}}} Q_L$$

抵抗負荷の場合の遮断角周波数 : $\omega_C = \frac{1}{C_p R}$

C=C_pかつR_{res}=RならばLC共振回路負荷の場合の
信号增幅周波数の上限はQ_L倍

増幅利得に関する考察

LC共振回路負荷の場合 : $R_{res} = \frac{1}{C\omega_{res}} Q_L$

抵抗負荷の場合 : $R = \frac{1}{C_p \omega_C}$

$C = C_p$ かつ $\omega_{res} = \omega_C$ ならば

LC共振回路負荷の場合の増幅利得は
抵抗負荷の場合の Q_L 倍

雑音に関する考察

LC共振回路負荷の場合 : $C = \frac{1}{R_{\text{res}} \omega_{\text{res}}} Q_L$

抵抗負荷の場合 : $C_p = \frac{1}{R \omega_C}$

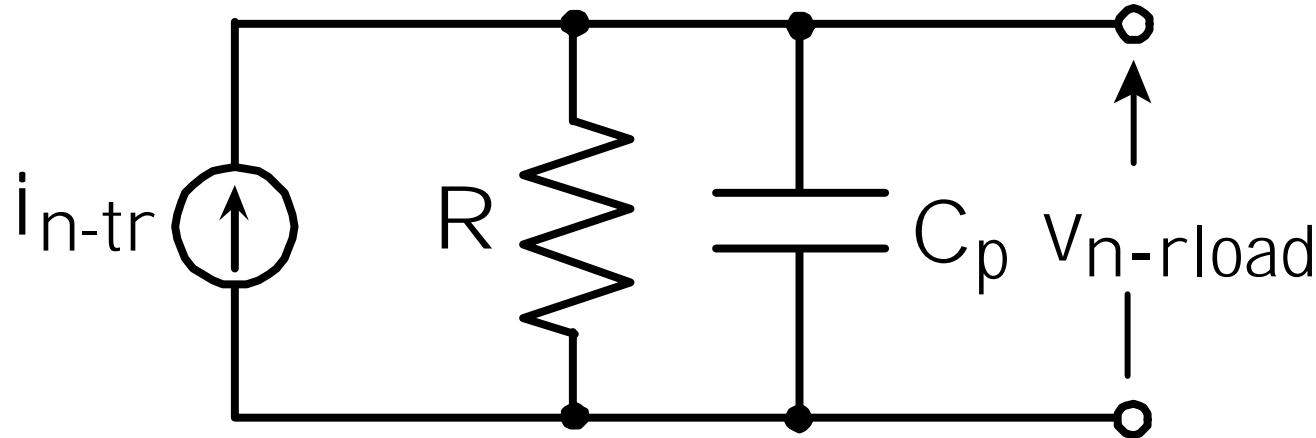
$\omega_{\text{res}} = \omega_C$ かつ $R_{\text{res}} = R$ ならば

LC共振回路負荷の場合の雑音は

抵抗負荷の場合の $\frac{1}{Q_L}$ 倍

トランジスタからの雑音の影響

抵抗負荷の場合



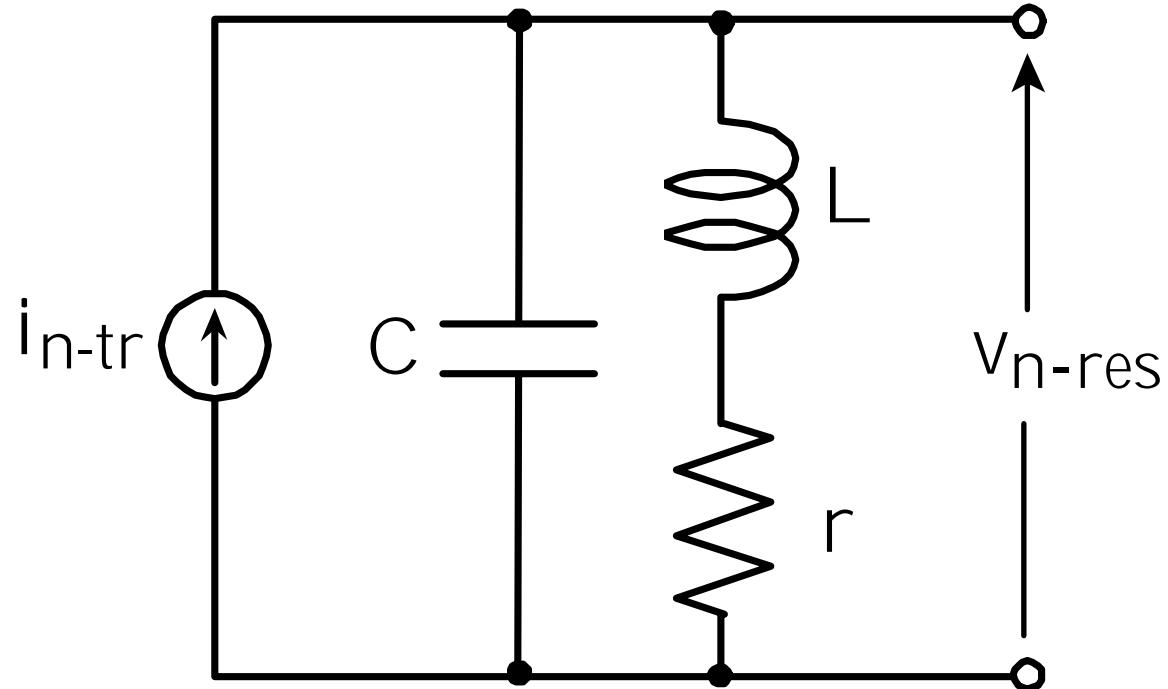
$$\overline{v_{n-rload}^2} = \int_0^\infty \frac{R^2}{1+\omega^2 C_p^2 R^2} \overline{i_{n-tr}^2} d\omega$$

$$\overline{v_{n-rload}^2} = \int_0^\infty \frac{R^2}{1+\omega^2 C_p^2 R^2} \overline{i_{n-tr}^2} d\omega$$

$$= \frac{\overline{i_{n-tr}^2}}{C_p^2} \int_0^\infty \frac{1}{\omega^2 + \frac{1}{C_p^2 R^2}} d\omega = \frac{\overline{i_{n-tr}^2}}{C_p^2} \left[C_p R \tan^{-1}(C_p R \omega) \right]_0^\infty$$

$$= \frac{\overline{i_{n-tr}^2}}{C_p^2} \cdot C_p R \frac{\pi}{2} = \underline{\underline{\frac{R\pi}{2C_p} \overline{i_{n-tr}^2}}}$$

LC共振回路負荷の場合



$$Z_{\text{res}}(s) = \frac{sL+r}{s^2LC+sCr+1}$$

$$\overline{V_{n\text{-res}}}^2 = \int_0^\infty \frac{\omega^2 L^2 + r^2}{(1 - \omega^2 LC)^2 + \omega^2 C^2 r^2} \overline{i_{n\text{-tr}}}^2 d\omega$$

$$\begin{aligned}
& \overline{v_{n-\text{res}}^2} = \int_0^\infty \frac{\omega^2 L^2 + r^2}{(1 - \omega^2 LC)^2 + \omega^2 C^2 r^2} \overline{i_{n-\text{tr}}^2} d\omega \\
&= \int_0^\infty \frac{\omega^2 L^2 \overline{i_{n-\text{tr}}^2}}{(1 - \omega^2 LC)^2 + \omega^2 C^2 r^2} d\omega + \int_0^\infty \frac{r^2 \overline{i_{n-\text{tr}}^2}}{(1 - \omega^2 LC)^2 + \omega^2 C^2 r^2} d\omega \\
&= \frac{1}{C^2} \int_0^\infty \frac{\omega^2 \overline{i_{n-\text{tr}}^2}}{\left(\omega^2 - \frac{1}{LC}\right)^2 + \frac{r^2}{L^2} \omega^2} d\omega + \int_0^\infty \frac{r^2 \overline{i_{n-\text{tr}}^2} x^2}{(x^2 - LC)^2 + C^2 r^2 x^2} dx \\
&= \left(\frac{1}{C^2} \frac{L\pi}{2r} + r^2 \frac{\pi}{2Cr} \right) \overline{i_{n-\text{tr}}^2} = \left(\frac{L}{Cr} + r \right) \frac{\pi}{2C} \overline{i_{n-\text{tr}}^2}
\end{aligned}$$

$$\overline{v_{n-res}}^2 = \left(\frac{L}{Cr} + r \right) \frac{\pi}{2C} \overline{i_{n-tr}}^2$$

$$\overline{v_{n-rload}}^2 = R \frac{\pi}{2C_p} \overline{i_{n-tr}}^2$$

$$j\omega_{res}L + r = j\omega_{res}CR_{res}r + R_{res}(1-\omega_{res}^2LC)$$

$$\Rightarrow L = CR_{res}r , \quad r = R_{res}(1-\omega_{res}^2LC)$$

$$\overline{v_{n-res}}^2 = (R_{res} + r) \frac{\pi}{2C} \overline{i_{n-tr}}^2$$

負荷の雑音レベルと增幅利得が等しい場合

$$Q_L = \sqrt{\frac{R_{res}}{r} - 1} \text{ より } r = \frac{R_{res}}{1 + Q_L^2}$$

$Q_L = 3$ のとき , $R_{res} + r$ は R の 1.1 倍 = 0.41dB

$Q_L = 5$ のとき , $R_{res} + r$ は R の 1.04 倍 = 0.16dB

$Q_L = 10$ のとき , $R_{res} + r$ は R の 1.01 倍 = 0.043dB

最大利得周波数 : LC 共振回路負荷 = 抵抗負荷 $\times Q_L$

増幅利得と最大利得周波数が等しい場合

$$C = \frac{1}{R_{\text{res}} \omega_{\text{res}}} Q_L$$

$$C_p = \frac{1}{R \omega_C}$$

$$\overline{v_{n-\text{res}}}^2 = (R_{\text{res}} + r) \frac{\pi}{2C} \overline{i_{n-\text{tr}}}^2 = \frac{R_{\text{res}}(R_{\text{res}} + r) \omega_{\text{res}}}{2Q_L} \pi \overline{i_{n-\text{tr}}}^2$$

$$\overline{v_{n-r\text{load}}}^2 = R \frac{\pi}{2C_p} \overline{i_{n-\text{tr}}}^2 = \frac{R_{\text{res}}^2 \omega_{\text{res}}}{2} \pi \overline{i_{n-\text{tr}}}^2$$

最大利得周波数と負荷の雑音レベルが等しい場合

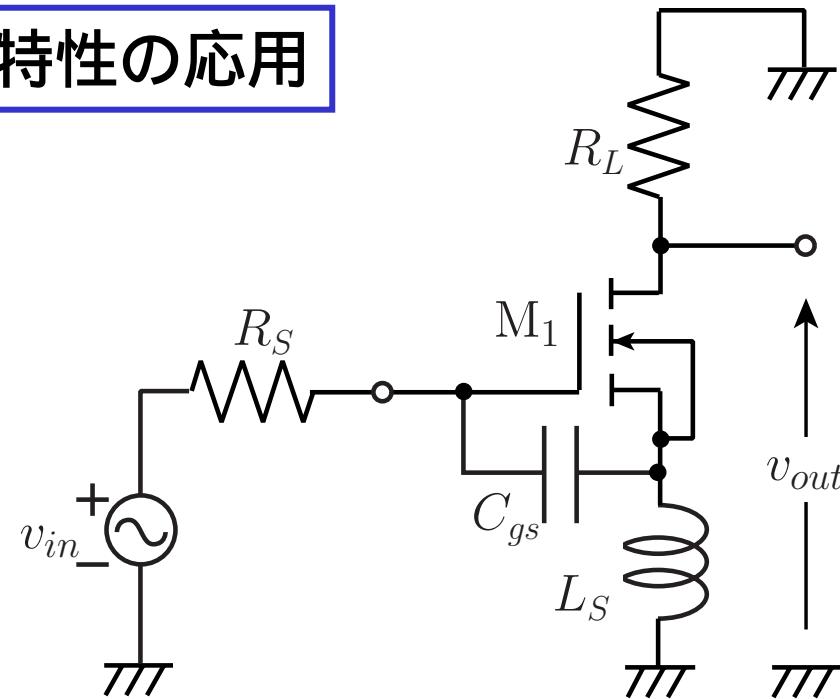
$$R_{res} = \frac{1}{\omega_{res} C} Q_L \quad R = \frac{1}{\omega_C C_p}$$

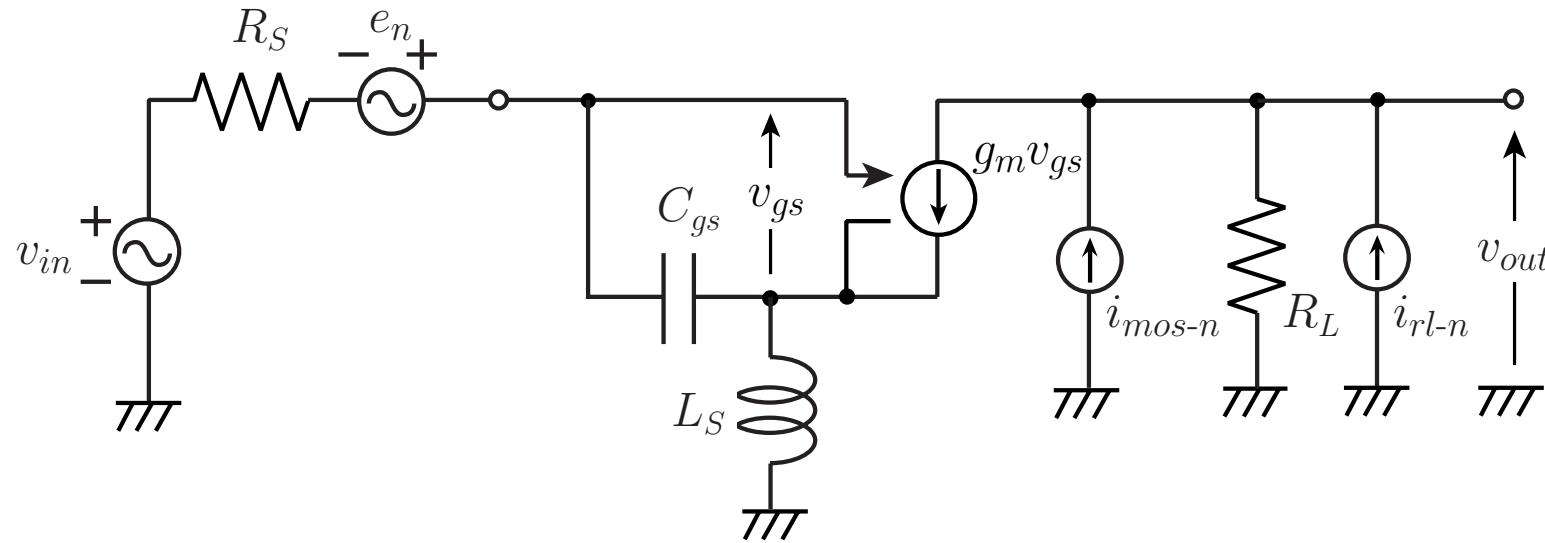
$$\overline{v_{n-res}^2} = (R_{res} + r) \frac{\pi}{2C} \overline{i_{n-tr}^2} = \left(\frac{Q_L}{\omega_{res} C} + r \right) \frac{\pi}{2C} \overline{i_{n-tr}^2}$$

$$\overline{v_{n-rload}^2} = R \frac{\pi}{2C_p} \overline{i_{n-tr}^2} = \frac{1}{\omega_{res} C} \frac{\pi}{2C} \overline{i_{n-tr}^2}$$

低雑音增幅回路の設計(2)

LC共振特性の応用





$$\overline{v_N^2} = R_L^2 (\overline{i_{rl-n}^2} + \overline{i_{mos-n}^2})$$

$$A = \frac{-g_m R_L}{1 + sL_S(g_m + sC_{gs})}$$

$$Z_T = \frac{g_m}{sC_{gs}} R_L$$

$$\overline{v_N}^2 = R_L^2 (\overline{i_{rl-n}}^2 + \overline{i_{mos-n}}^2)$$

$$A = \frac{-g_m R_L}{1 + sL_S(g_m + sC_{gs})}$$

$$Z_T = \frac{g_m}{sC_{gs}} R_L$$

$$\overline{v_n}^2 = \left| \frac{1 + sL_S(g_m + sC_{gs})}{g_m} \right|^2 (\overline{i_{rl-n}}^2 + \overline{i_{mos-n}}^2)$$

$$\overline{i_n}^2 = \left| \frac{sC_{gs}}{g_m} \right|^2 (\overline{i_{rl-n}}^2 + \overline{i_{mos-n}}^2)$$

$$\overline{v_n^2} = \left| \frac{1+sL_S(g_m+sC_{gs})}{g_m} \right|^2 \left(\overline{i_{rl-n}^2} + \overline{i_{mos-n}^2} \right)$$

$$\overline{i_n^2} = \left| \frac{sC_{gs}}{g_m} \right|^2 \left(\overline{i_{rl-n}^2} + \overline{i_{mos-n}^2} \right)$$

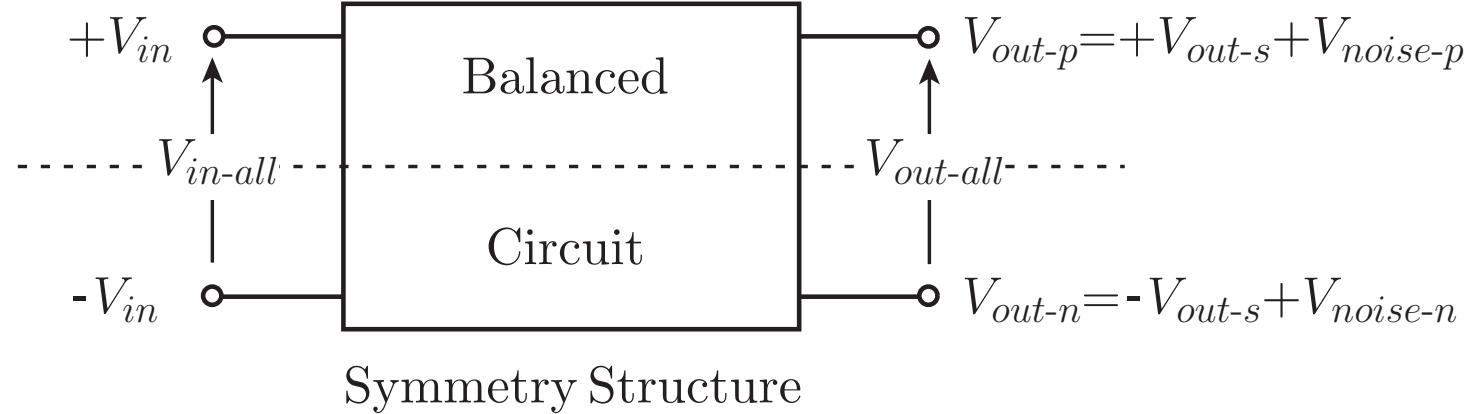
$$\sqrt{\frac{\overline{v_n^2}}{\overline{i_n^2}}} = \left| \frac{1+sL_S(g_m+sC_{gs})}{sC_{gs}} \right|$$

$$\left| \frac{1+sL_S(g_m+sC_{gs})}{sC_{gs}} \right| = R_S$$

↑

$$f = \frac{1}{2\pi} \sqrt{\frac{1}{L_S C_{gs}}} \text{ のとき } \frac{L_S g_m}{C_{gs}} \text{ の純抵抗}$$

平衡型構成の利用



$$V_{noise-d} = \frac{V_{noise-p} - V_{noise-n}}{2}$$

$$V_{noise-c} = \frac{V_{noise-p} + V_{noise-n}}{2}$$

$$V_{noise-p} = +V_{noise-d} + V_{noise-c}$$

$$V_{noise-n} = -V_{noise-d} + V_{noise-c}$$

$$V_{out-all} = V_{out-p} - V_{out-n} = 2V_{out-s} + 2V_{noise-d}$$

不平衡型回路のSNR

$$V_{\text{out}} = V_{\text{out-s}} + V_{\text{noise}}$$

$$\lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T V_{\text{out-s}}^2 dt = \overline{V_{\text{out-s}}}^2$$

$$\lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T V_{\text{noise}}^2 dt = \overline{V_{\text{noise}}}^2$$

$$\text{SNR}_{\text{imbal}} = \frac{\overline{V_{\text{out-s}}}^2}{\overline{V_{\text{noise}}}^2}$$

平衡型回路のSNR

$$V_{\text{out-all}} = V_{\text{out-p}} - V_{\text{out-n}} = 2(V_{\text{out-s}} + V_{\text{noise-d}})$$

$$\lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T V_{\text{out-s}}^2 dt = \overline{V_{\text{out-s}}}^2$$

$$\overline{V_{\text{noise-d}}}^2 = \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T V_{\text{noise-d}}^2 dt = \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T V_{\text{noise-c}}^2 dt = \frac{1}{2} \overline{V_{\text{noise}}}^2$$

$$\text{SNRの改善 : } \text{SNR}_{\text{bal}} = \frac{\overline{V_{\text{out-s}}}^2}{\overline{V_{\text{noise-d}}}^2} = 2 \frac{\overline{V_{\text{out-s}}}^2}{\overline{V_{\text{noise}}}^2}$$

ただし、回路規模は2倍