Pattern Information Processing^{1,53} Neural Networks

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Linear/Non-Linear Models

Linear model: $\hat{f}(x)$ is linear with respect to α (Note: not necessarily linear with respect to x)

$$\hat{f}(\boldsymbol{x}) = \sum_{i=1}^{b} \alpha_i \varphi_i(\boldsymbol{x})$$

Non-linear model: Otherwise

Today's Plan

- Neural networks
- Least-squares in neural networks:
 Error back-propagation algorithm

Non-Linear Models

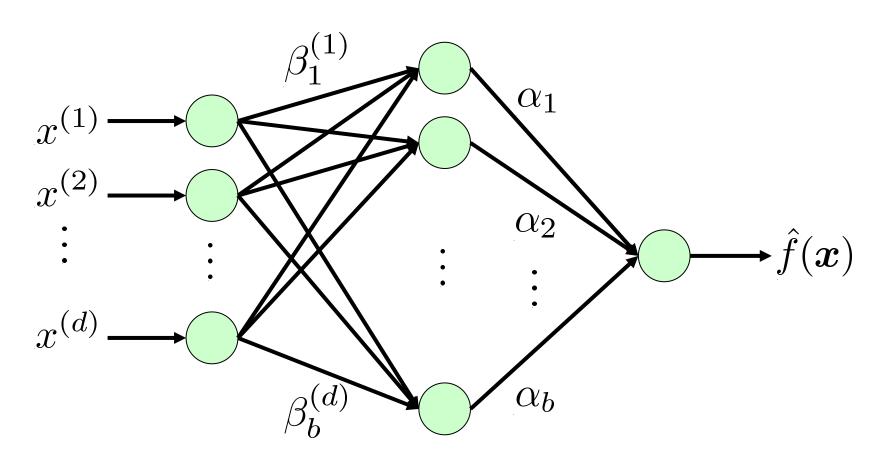
A popular choice: Hierarchical models

$$\hat{f}(\boldsymbol{x}) = \sum_{i=1}^{b} \alpha_i \varphi(\boldsymbol{x}; \boldsymbol{\beta}_i)$$

Basis function is parameterized by β_i

Three-Layer Networks

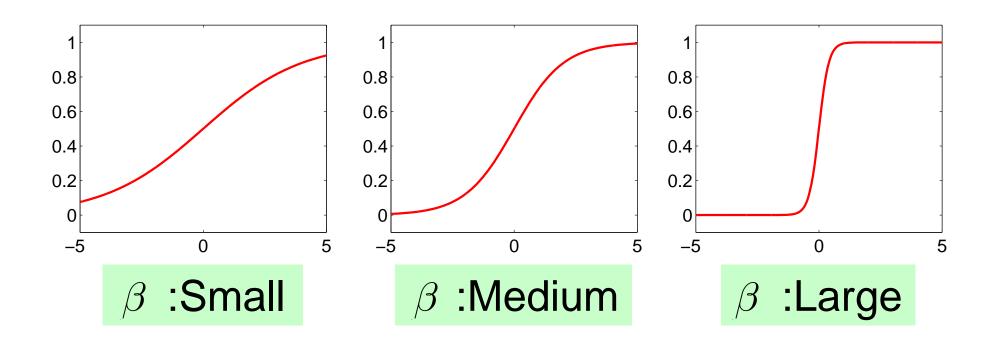
Such a hierarchical model can be represented as a 3-layer network.



Sigmoidal Function

A typical basis function: Sigmoidal function

$$\varphi(\boldsymbol{x};\boldsymbol{\beta},h) = \frac{1}{1 + \exp(-\langle \boldsymbol{x},\boldsymbol{\beta}\rangle - h)}$$



Perceptrons

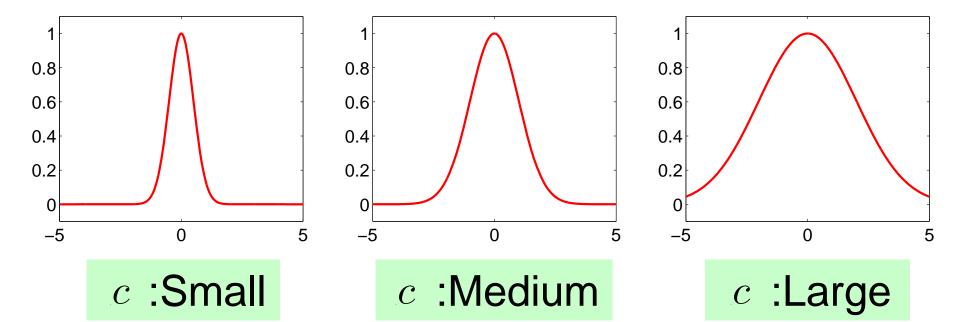
- The behavior of the sigmoidal functions is similar to the neurons in the brain.
- For this reason, hierarchical models with sigmoidal functions are called artificial neural networks or perceptrons.
- Mathematically, 3-layer neural networks can approximate any continuous functions with arbitrary small error ("universal approximator").

Gaussian Radial Basis Function 160

Another popular basis function:

Gaussian radial basis function

$$\varphi(\boldsymbol{x}; \boldsymbol{\beta}, c) = \exp\left(-\frac{\|\boldsymbol{x} - \boldsymbol{\beta}\|^2}{2c^2}\right)$$



Least-Squares Learning

$$\hat{f}(\boldsymbol{x}) = \sum_{i=1}^{b} \alpha_i \varphi(\boldsymbol{x}; \boldsymbol{\beta}_i)$$

$$oldsymbol{w} = (oldsymbol{lpha}^ op, oldsymbol{eta}_1^ op, oldsymbol{eta}_2^ op, \dots, oldsymbol{eta}_b^ op)^ op.$$

Least-squares learning is often used for training hierarchical models.

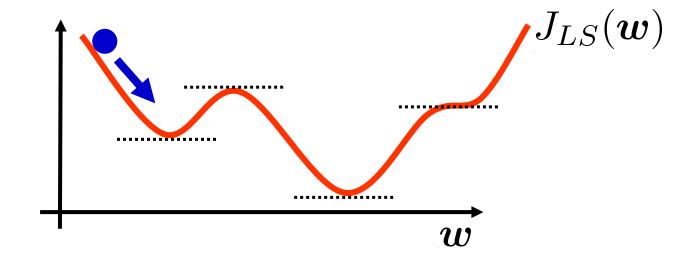
$$\min_{m{w}} J_{LS}(m{w})$$

$$J_{LS}(\boldsymbol{w}) = \sum_{i=1}^{n} \left(\hat{f}(\boldsymbol{x}_i) - y_i \right)^2$$

How to Obtain Solutions

- No analytic solution is known.
- Simple gradient search is usually used.

$$\widehat{\boldsymbol{w}}^{new} \longleftarrow \widehat{\boldsymbol{w}}^{old} - \varepsilon \nabla J_{LS}(\widehat{\boldsymbol{w}}^{old})$$



It converges to one of the local minima.

Error Back-Propagation

Efficient calculation of gradient for Sigmoidal basis functions

$$\frac{\partial J_{LS}}{\partial \alpha_j} = 2 \sum_{i=1}^n o_{i,j} \left(\hat{f}(\boldsymbol{x}_i) - y_i \right)$$

$$\frac{\partial J_{LS}}{\partial \beta_j^{(k)}} = 2\alpha_j \sum_{i=1}^n o_{i,j} \left(1 - o_{i,j}\right) x_i^{(k)} \left(\hat{f}(\boldsymbol{x}_i) - y_i\right)$$

$$\frac{\partial J_{LS}}{\partial h_j} = 2\alpha_j \sum_{i=1}^n o_{i,j} (1 - o_{i,j}) \left(\hat{f}(\boldsymbol{x}_i) - y_i \right)$$

$$o_{i,j} = \varphi(\boldsymbol{x}_i; \boldsymbol{\beta}_j, h_j)$$

Error Back-Propagation (cont.)¹⁶⁴

- When the output values of the network are calculated, the input points are propagated following the forward path.
- On the other hand, when the gradients are calculated, the output error $(\hat{f}(\boldsymbol{x}_i) y_i)$ is propagated backward.
- For this reason, this algorithm is called the error back-propagation.
- However, it is gradient descent so global convergence is not guaranteed.

Stochastic Gradient Descent 165

- In the usual gradient method, all training examples are used at the same time.
- In practice, the following stochastic method would be computationally advantageous.
 - Randomly choose one of the training examples (say, (\boldsymbol{x}_i, y_i))
 - Update the parameter vector by

$$\widehat{\boldsymbol{w}}^{new} \longleftarrow \widehat{\boldsymbol{w}}^{old} - \varepsilon \nabla J_i(\widehat{\boldsymbol{w}}^{old})$$
$$J_i(\boldsymbol{w}) = (\widehat{f}(\boldsymbol{x}_i) - y_i)^2$$

Repeat this procedure until convergence.

Avoiding Overfitting

$$\hat{f}(\boldsymbol{x}) = \sum_{i=1}^{b} \alpha_i \varphi(\boldsymbol{x}; \boldsymbol{\beta}_i)$$

$$oldsymbol{w} = (oldsymbol{lpha}^ op, oldsymbol{eta}_1^ op, oldsymbol{eta}_2^ op, \dots, oldsymbol{eta}_b^ op)^ op.$$

- LS overfits to noisy samples.
 - Regularization:

$$\min_{\boldsymbol{w}}[J_{LS}(\boldsymbol{w}) + \lambda \|\boldsymbol{w}\|^2]$$

$$J_{LS}(\boldsymbol{w}) = \sum_{i=1}^{n} \left(\hat{f}(\boldsymbol{x}_i) - y_i \right)^2 \qquad \lambda > 0$$

 Early stopping: Stop gradient descent before it converges

Special Structure of Neural Networks

Parameters and functions are not one-to-one mapping.

$$\hat{f}(\boldsymbol{x}) = \sum_{i=1}^{b} \alpha_i \varphi(\boldsymbol{x}; \boldsymbol{\beta}_i)$$

- If $\alpha_i = 0$, any β_i gives the same function.
- Any permutation gives the same function.
- This non-identifiability causes great difficulty in the mathematical analysis of neural networks.

Homework

 Prove that the gradients for Sigmoidal basis functions are given as

$$\frac{\partial J_{LS}}{\partial \alpha_j} = 2 \sum_{i=1}^n o_{i,j} \left(\hat{f}(\boldsymbol{x}_i) - y_i \right) \qquad o_{i,j} = \varphi(\boldsymbol{x}_i; \boldsymbol{\beta}_j, h_j)$$

$$\frac{\partial J_{LS}}{\partial \beta_j^{(k)}} = 2\alpha_j \sum_{i=1}^n o_{i,j} \left(1 - o_{i,j}\right) x_i^{(k)} \left(\hat{f}(\boldsymbol{x}_i) - y_i\right)$$

$$\frac{\partial J_{LS}}{\partial h_j} = 2\alpha_j \sum_{i=1}^n o_{i,j} \left(1 - o_{i,j}\right) \left(\hat{f}(\boldsymbol{x}_i) - y_i\right)$$

Homework (cont.)

- For your own toy 1-dimensional data, perform simulations using
 - 3-layer neural networks with sigmoid functions
 - Error back-propagation
 - and analyze the results, e.g., by changing
 - Target functions
 - Number of training samples
 - Noise level
 - Number of neurons in the second layer (b)

Notification of Final Assignment

- Apply supervised learning techniques to your data set and analyze it.
- 2. Write your opinion about this course

- Final report deadline: Aug 6th (Fri.)
- E-mail submission is also accepted! sugi@cs.titech.ac.jp

Mini-Workshop on Data Mining⁷¹

- On July 20th and 27th, we have a miniworkshop on data mining, instead of regular lectures.
- We have 16 speakers in total.
- Presentation: 10 minutes per person (including Q&A).
 - Specification of your dataset
 - Employed methods
 - Outcome

Schedule

July 13th

: Preparation for workshop

(no lecture)

July 20th

: Mini-workshop Day 1

■July 27th

: Mini-workshop Day 2

Mini-Workshop: Program

July 20th ,2010: 10:40-12:10

- Wittawat Jitkrittum
- Nakamasa Inoue
- Yukihiro Fukunaga
- Tatsuya Shigemura
- Ahmet Cetinkaya
- Michael Hamarneh
- Yonatan Andy Fajar Nugraha
- Youhei Namiki

July 27th ,2010: 10:40-12:10

- Johan Rohdin
- Hilman F. Pardede
- Sangeeta Biswas
- Rubaiya Rahtin Khan
- Mori Syogo
- M. Rasyid Aqmar
- Nozomi Kurihara
- Yuan Liang

Talk: 9 mins. Q&A: 2 mins.