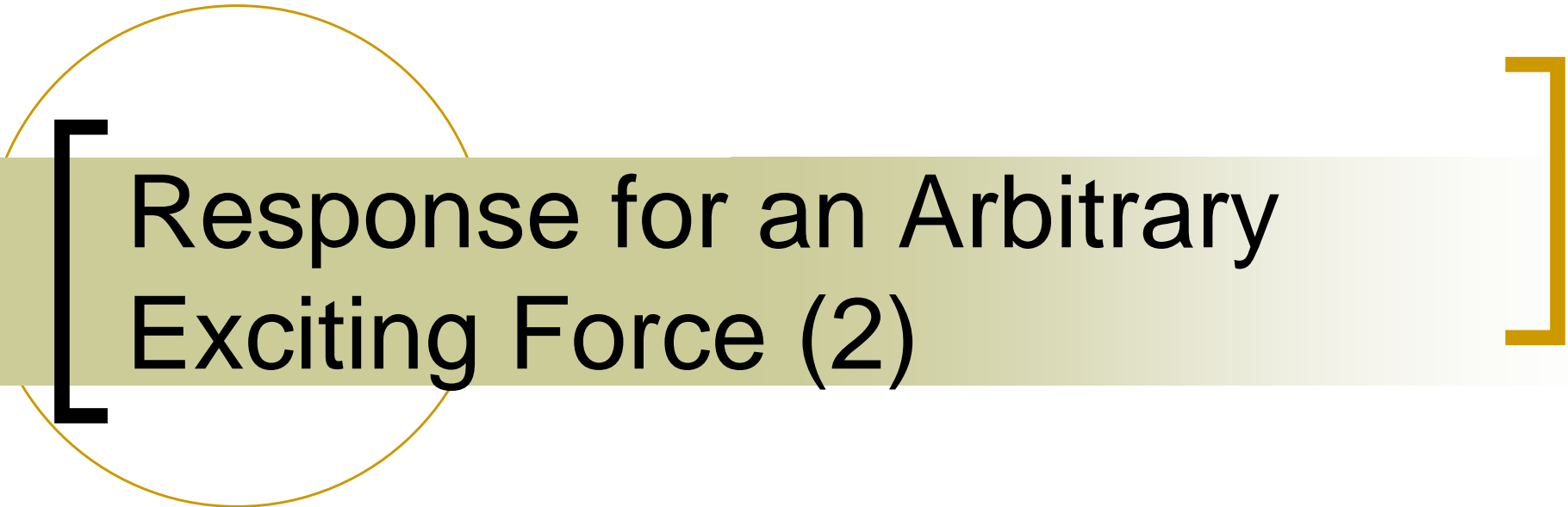




# Mechanical Vibration (12)

Department of Mechanical and  
Control Engineering

Hiroshi Yamaura



# Response for an Arbitrary Exciting Force (2)

# [ Transient response (1-1) ]

Define the frequency response function  $H(i\omega)$

$$H(i\omega) = \frac{X(i\omega)}{F}$$

Assume a complex exciting force

$$f(t) = F \exp(i\omega t)$$

Response against the complex exciting force

$$x(t) = FH(i\omega) \exp(i\omega t)$$

# [ Transient response (1-2) ]

Inverse Fourier transformation of the exciting force

$$f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(i\omega) \exp(i\omega t) d\omega$$

Response against the exciting force

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(i\omega) H(i\omega) \exp(i\omega t) d\omega$$

Fourier transformation of the response

$$X(i\omega) = F(i\omega) H(i\omega)$$

# [ Transient response (1-3) ]

Necessary condition of the Laplace transformation is not strict compared to that of the Fourier transformation.

$$x(t) = \frac{1}{2\pi} \int_{\sigma-i\infty}^{\sigma+i\infty} F(s)H(s)\exp(st)ds$$

where

$$F(s) = \int_0^{\infty} f(t)\exp(-st)dt$$

$$H(s) = \int_0^{\infty} h(t)\exp(-st)dt = H(i\omega) \big|_{i\omega=s}$$

# [ Transient response (1-4) ]

Table 2 Laplace transformation

Time function	Laplace transformation
$\delta(t)$	1
$u(t)$ (Unit function)	$\frac{1}{s}$
$e^{at}$	$\frac{1}{s-a}$
$\sin \omega t$	$\frac{\omega}{s^2 + \omega^2}$
$\cos \omega t$	$\frac{s}{s^2 + \omega^2}$
$f(t - T)$	$F(s)e^{-sT}$
$\frac{d}{dt}f(t)$	$sF(s) - f(0)$
$\frac{d^2}{dt^2}f(t)$	$s^2F(s) - sf(0) - \frac{d}{dt}f(0)$

# [ Transient response (1-5) ]

Example 1 Unit impulse response function

$$m\ddot{x} + c\dot{x} + kx = f \quad \text{and} \quad f(t) = \delta(t)$$

$$\rightarrow ms^2 X(s) + csX(s) + kX(s) = 1$$

$$\rightarrow X(s) = \frac{1}{ms^2 + cs + k} \quad \text{Transfer function}$$

$$= \frac{1}{m} \frac{i}{2\omega_d} \left( \frac{-1}{s - \lambda_1} + \frac{1}{s - \lambda_2} \right)$$

$$\text{where } \lambda_{1,2} = -\zeta\omega_n \pm i\omega_d$$

# [ Transient response (1-6) ]

Example 1 Unit impulse response function

$$\begin{aligned} \rightarrow x(t) &= \frac{1}{m} \frac{i}{2\omega_d} \left( -e^{\lambda_1 t} + e^{\lambda_2 t} \right) \\ &= e^{-\zeta\omega_n t} \frac{1}{m\omega_d} \sin \omega_d t \equiv h(t) \end{aligned}$$



# [ Transient response (1-7) ]

## Example 2

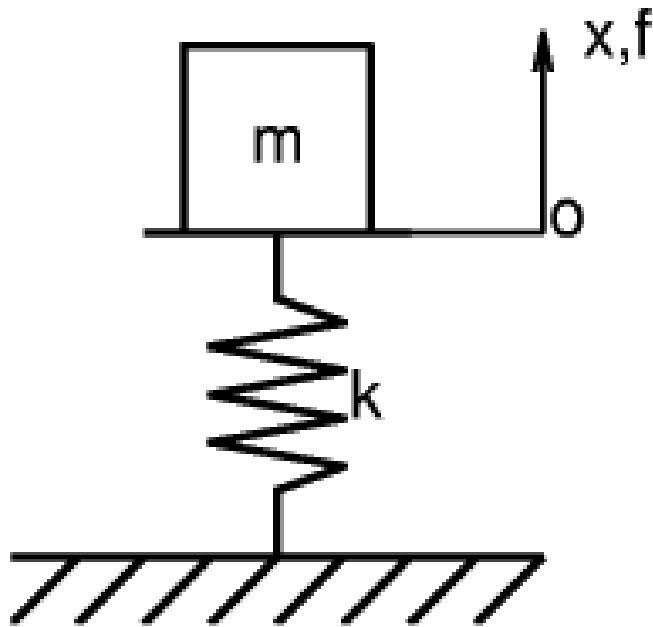


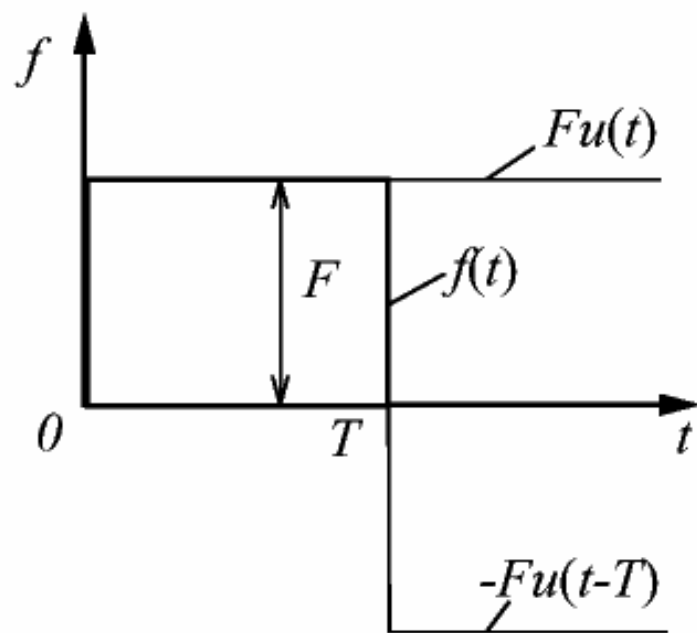
Fig.4 Undamped one degree-of-freedom  
vibration system

Transfer function

$$H(s) = \frac{1}{m} \frac{1}{s^2 + \omega_n^2}$$

# [ Transient response (1-8) ]

## Example 2



Exciting force

$$f(t) = \begin{cases} 0 & (t < 0) \\ Fu(t) & (0 \leq t \leq T) \\ Fu(t) - Fu(t-T) & (t > T) \end{cases}$$

Fig.6 Decomposition of the exciting force into unit step functions

# [ Transient response (1-9) ]

## Example 2

$$x(t) = \begin{cases} 0 & 0 \\ L^{-1}\left[H(s)\frac{F}{s}\right] & (0 \leq t \leq T) \\ L^{-1}\left[H(s)\frac{F}{s}(1 - e^{-sT})\right] & (t > T) \end{cases}$$

$L^{-1}[\ ]$  : Inverse Laplace transformation